

Optimal transport paths and their applications

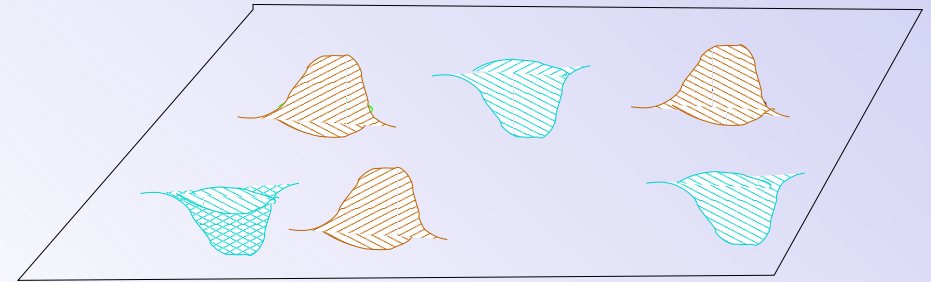
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May 27, 2008

Monge's Transport Problem

How do you best move a given pile of sand to fill a given hole of the same volume?



Pile of Sand: a positive Radon measure μ^+ on a compact convex subset $X \subset \mathbb{R}^m$.

Hole: another positive Radon measure μ^- on X .

Same Volume: $0 < \mu^+(X) = \mu^-(X) < +\infty$

move: a Borel, one-to-one map $\psi : X \rightarrow X$

fill: $\psi_{\#}\mu^+ = \mu^-$ (i.e. $\mu^-(A) = \psi_{\#}\mu^+(A) = \mu^+(\psi^{-1}(A))$).

best: minimum total “work”

Work or cost of ψ : $I(\psi) = \int_X |x - \psi(x)| d\mu^+(x)$.

Monge's problem (1781)

Find an “optimal transport map” in

$$\mathcal{A} = \{ \psi : X \rightarrow X \text{ Borel, one-to-one, } \psi_{\#}(\mu^+) = \mu^- \}$$

which minimizes the cost

$$I[\psi] := \int_X |x - \psi(x)| d\mu^+(x)$$

or in general case

$$I[\psi] := \int_X c(x, \psi(x)) d\mu^+(x)$$

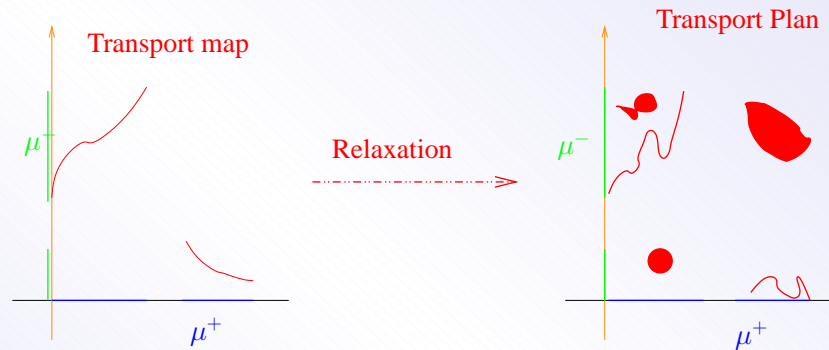
for some given cost density function $c : X \times X \rightarrow [0, +\infty)$.

Technical Difficulties:

- Highly **nonlinear** structure of I .
- No solution for $X = [-1, 1]$, $\mu^+ = \delta_0$, $\mu^- = \frac{1}{2}\delta_{-1} + \frac{1}{2}\delta_1$.

Kantorovich (1940's)

Transform it into a linear problem on a convex set.



Minimize

$$J(\gamma) := \int_{X \times X} c(x, y) d\gamma(x, y)$$

in the class of **transport plans**

$$\mathcal{M} = \{ \gamma \in P(X \times X) \mid \pi_{x\#}\gamma = \mu^+, \pi_{y\#}\gamma = \mu^- \}$$

Existence: from a simple compactness argument of probability measures.

Wasserstein distances on $P(X)$

Definition. Given $p \in (0, +\infty)$ (usually $[1, +\infty)$), for any $\mu^+, \mu^- \in P(X)$, define

$$W_p(\mu^+, \mu^-) := \left(\min_{\gamma \in \mathcal{M}} \int_{X \times X} |x - y|^p d\gamma(x, y) \right)^{\min(1, 1/p)}.$$

distance between measures = minimal cost

Proposition. W_p is a distance on $P(X)$ and metrizes the weak * topology of $P(X)$.

Many people has been working on this interesting problem.

Applications: This problem has many applications in Economic; Fluid Mechanics; PDE; Optimization; meteorology and oceanography; surface reconstruction; \dots .

Summary: For a given cost function $c : X \times X \rightarrow [0, +\infty)$, we have considered

- **Monge problem:** Minimize

$$I[\psi] := \int_X c(x, \psi(x)) d\mu^+(x)$$

among all transport maps.

- **Monge-Kantorovich problem:** Minimize

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But, should we always define transportation cost as an integral of a cost function $c(x, y)$?

Answer: Not always.

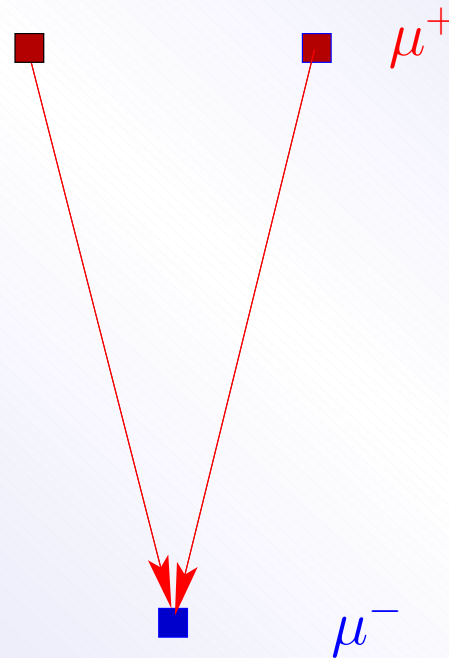
A simple example

What is the best way to ship two items from nearby cities to the same destination far away.



A simple example

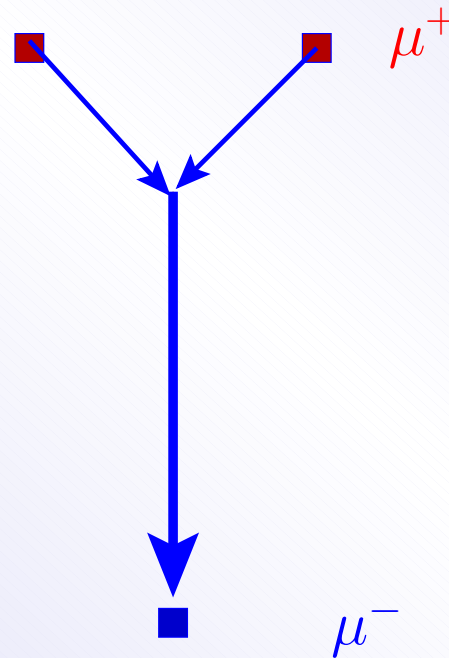
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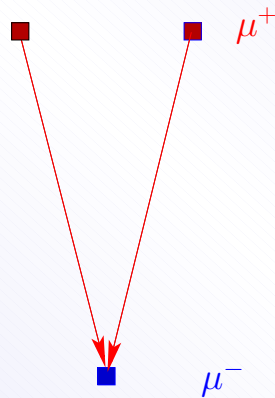
First Attempt: Move them directly to their destination.

A simple example

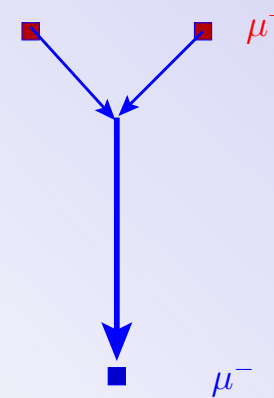
What is the best way to ship two items from nearby cities to the same destination far away.



Another way: put them on the same truck and transport together!



A V-shaped path



A Y-shaped path

Answer: Transporting two items together might be cheaper than the total cost of transporting them separately. As a result,

- A “Y shaped” path is preferable to a “V shaped” path.
- Here, the cost is naturally given by the actual transport “path”, while the transport maps for both types are trivially same. Knowing only maps is not enough here.

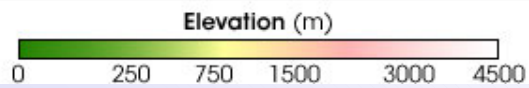
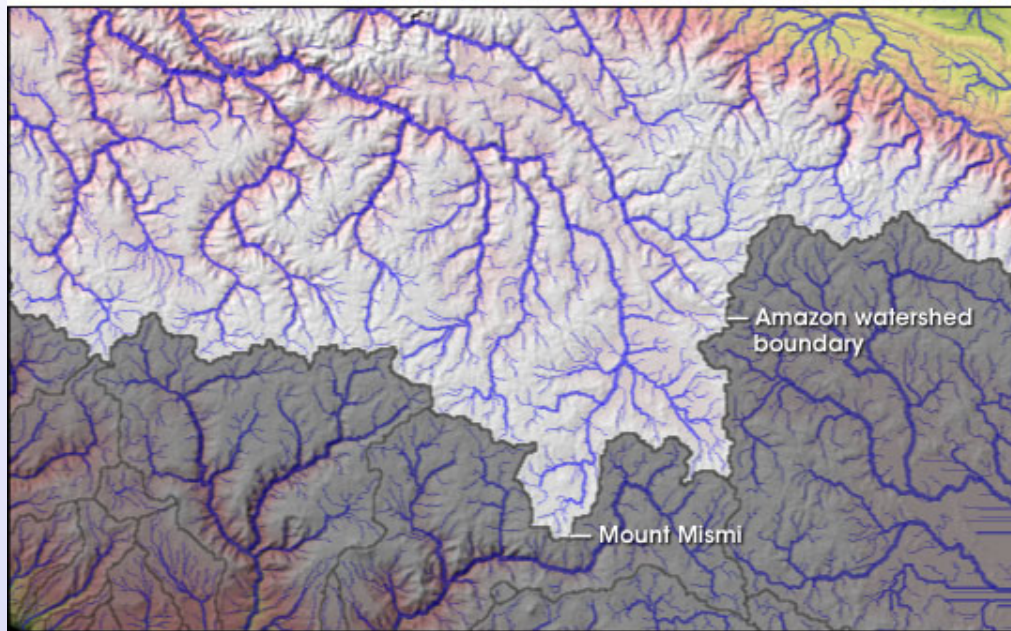
In general, a **ramified structure** might be more efficient than a “**linear**” **structure** consisting of straight lines.

Examples of Ramified Structures

- Trees
- Circulatory systems
- Cardiovascular systems
- Railways, Airlines
- Electric power supply
- River channel networks
- Post office mailing system
- Urban transport network
- Marketing
- Ordinary life
- Communications
- Superconductor



Conclusion: **Ramified structures** are very common in living and non-living systems. It deserves a more general theoretic treatment.





Problem: Given two arbitrary probability measures μ^+ and $\mu^- \in P(X)$ on a convex compact subset $X \subset \mathbb{R}^m$, find an optimal path transporting μ^+ to μ^- .

Need:

- A class of “transport paths”.
 - Broad enough to ensure the existence of optimal transport paths;
- A reasonable cost functional on the category.
 - Optimal transport paths should allow some parts overlap in a cost efficient fashion. Should be “Y-shaped” rather than “V shaped”.
 - Nice regularity of optimal transport paths.

Idea: figuring out **simple cases** first!

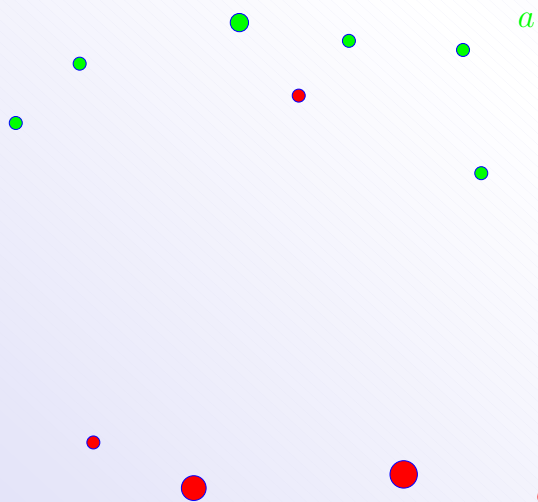
Atomic measures

An **atomic measure** is a (finite) sum of Dirac measures with positive multiplicities.

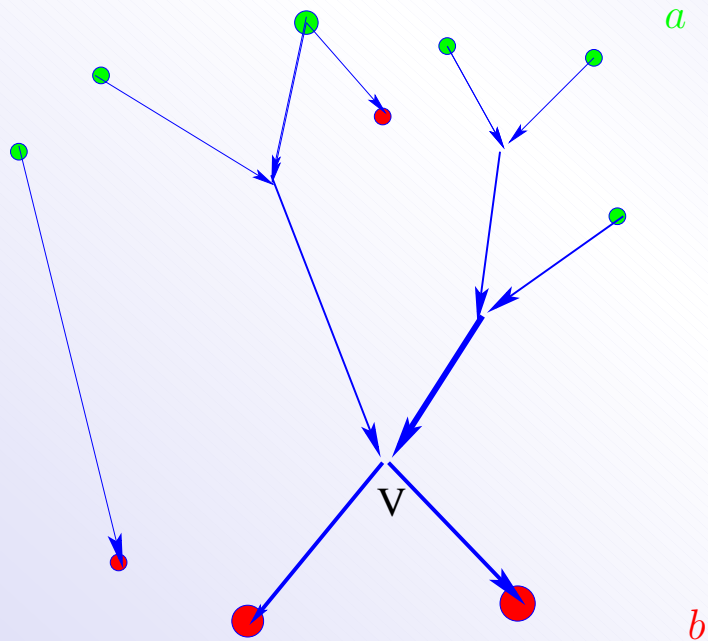
$$a = \sum_i a_i \delta_{x_i}$$

for some $x_i \in X$ and $a_i > 0$. Let $\mathcal{A}(X)$ be the space of all atomic measures on X .

Question: What is a **transport path** between two atomic probability measures a and b ?



Transport atomic measures



A transport path from a to b is a weighted directed graph

$$G = \{V(G), E(G), w : E(G) \rightarrow (0, +\infty)\}$$

satisfying **Kirchhoff's laws** (for electrical circuits):

$$\sum_{v=e^-} w(e) = \sum_{v=e^+} w(e)$$

for any interior vertex v .

Notation: For atomic measures $a, b \in P(X)$, let

$Path(a, b)$ be the family of all transport paths from a to b .

Cost Functionals

Note that in general the space $\text{Path}(a, b)$ might be very large.

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Answer: For each $G = \{V(G), E(G), w : E(G) \rightarrow (0, +\infty)\}$, define the M_α mass of G by

$$M_\alpha(G) := \sum_e w(e)^\alpha \text{length}(e)$$

for some $\alpha \in [0, 1)$.

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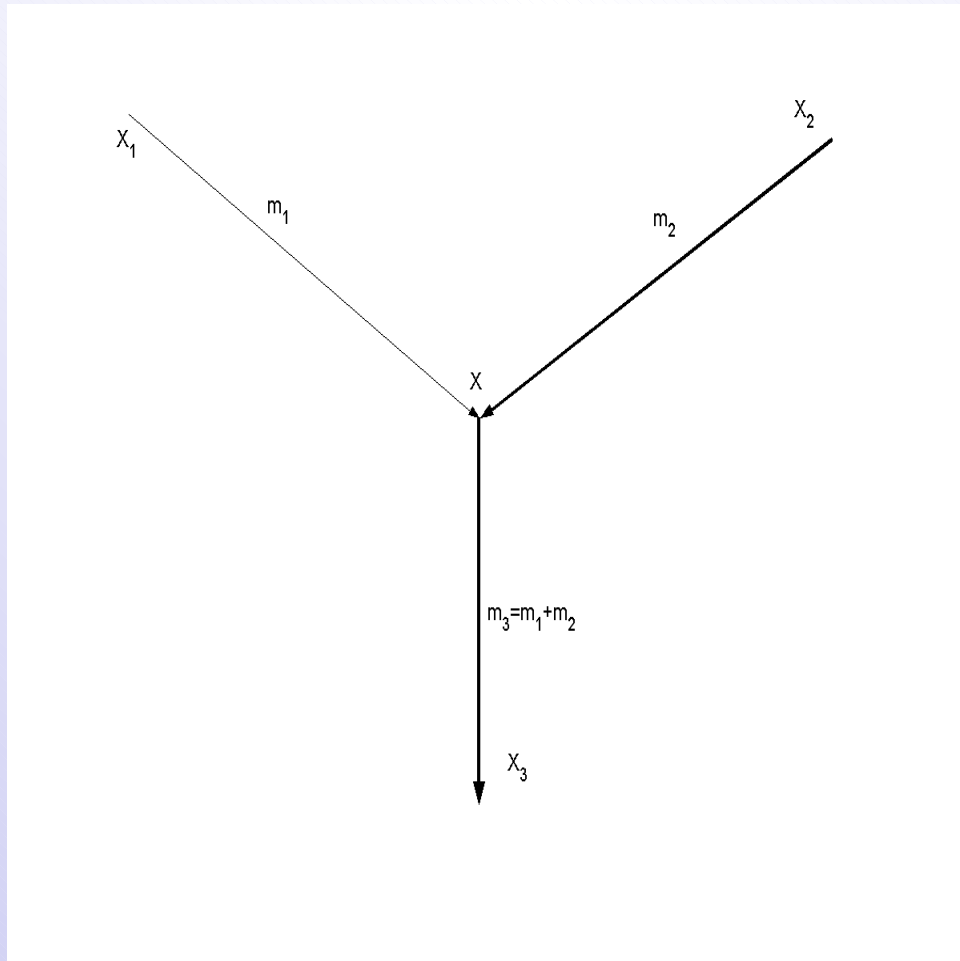
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for some $\alpha \in [0, 1)$.

Result: an M_α mass minimizer is indeed “Y-shaped” or “ramified”.

Example 1: Two points to one point



It satisfies a balance equation:

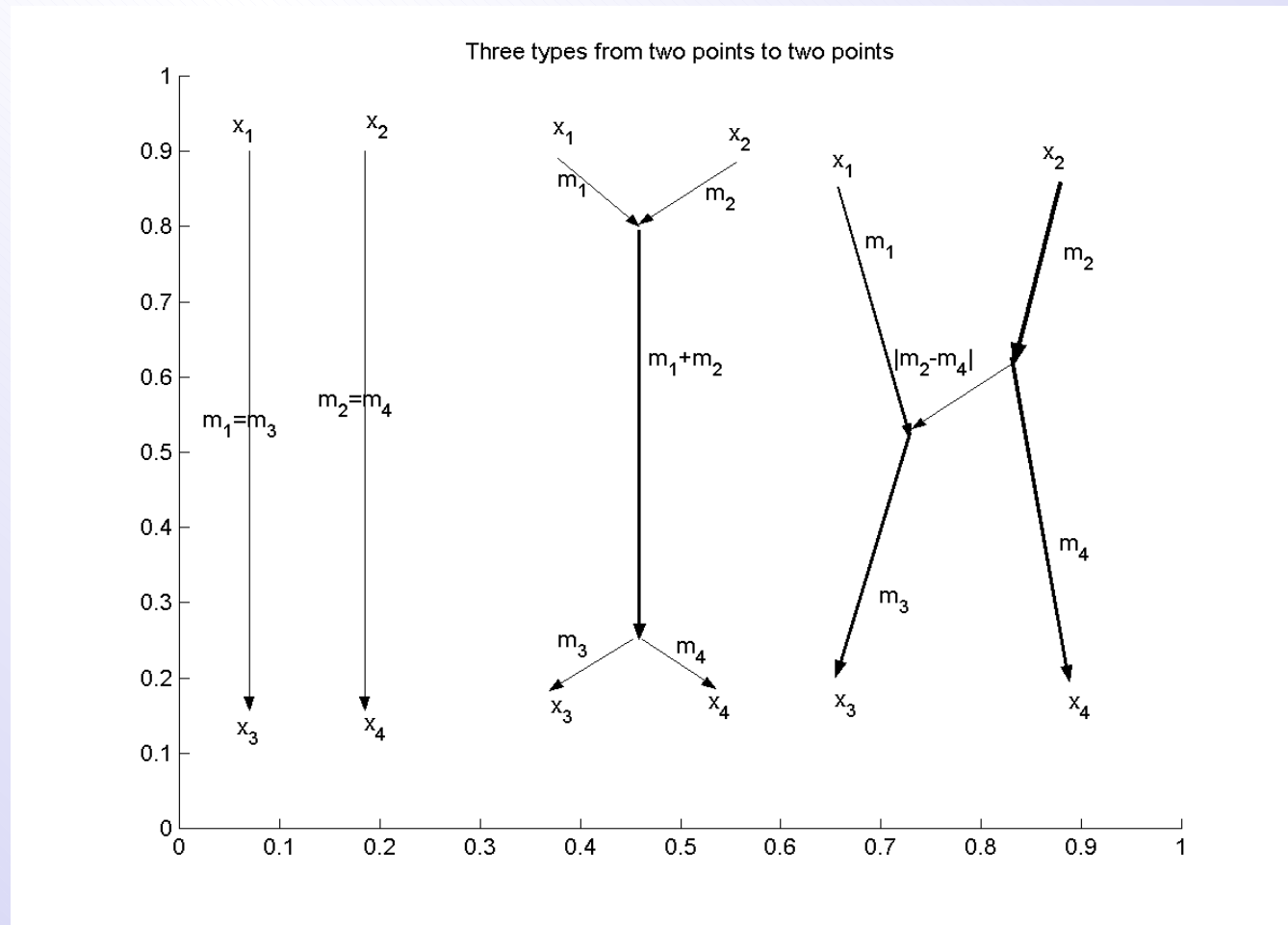
$$\sum_{i=1}^3 m_i^\alpha \vec{n}_i = \vec{0}.$$

Using this equation, we have a formula to calculate the angles.

In particular, if $\alpha = 0$, then the angles are 120° .

Also, if $\alpha = 1/2$, then the top angle must be 90° .

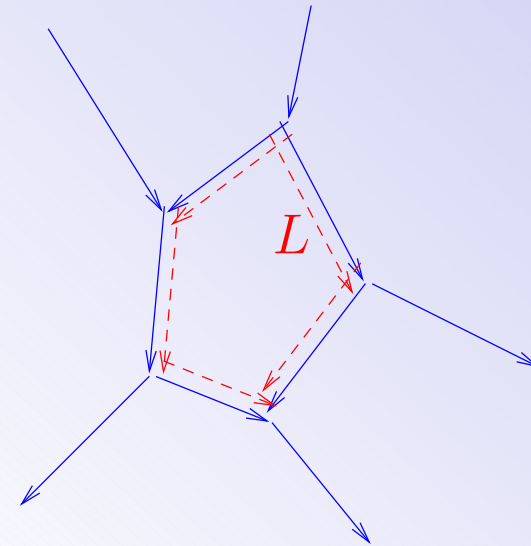
Two points to two points



Some lemmas (Xia, 2001)

Lemma. For any $G \in \text{Path}(a, b)$, there exists a $\tilde{G} \in \text{Path}(a, b)$ such that \tilde{G} contains no *cycles* and

$$M_\alpha(\tilde{G}) \leq M_\alpha(G).$$

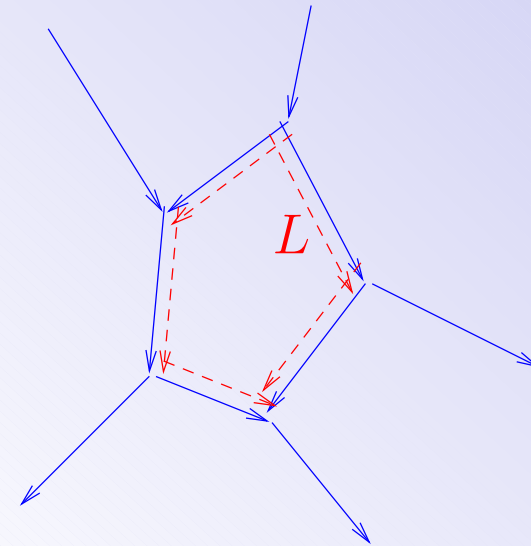


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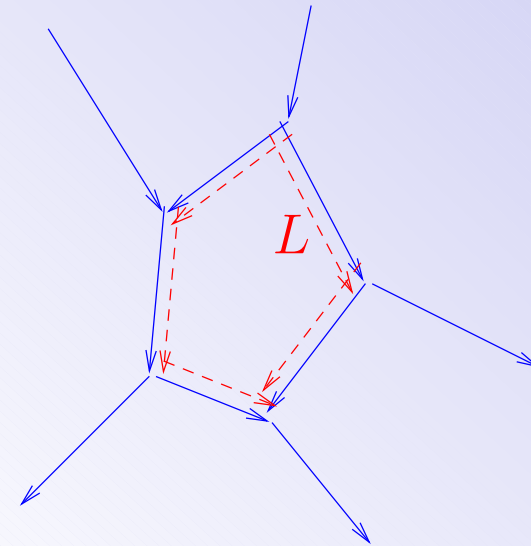
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Lemma. If G contains no cycles, then $0 < w(e) \leq 1$ for any $e \in E(G)$.
Thus

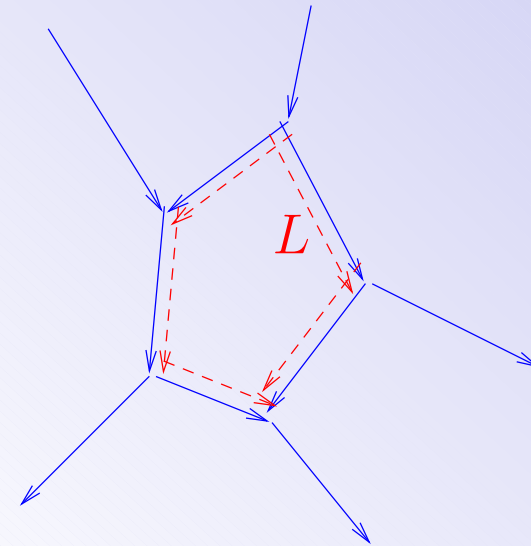
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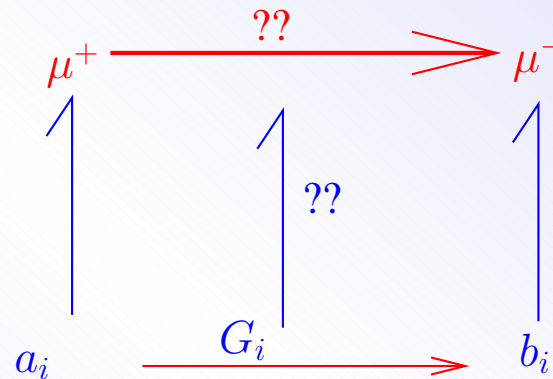
Lemma. If G contains no cycles, then $0 < w(e) \leq 1$ for any $e \in E(G)$.
Thus

$$M(G) \leq M_\alpha(G).$$

Now, given any two probability measures μ^+ and μ^- , what is a transport path from μ^+ to μ^- ?

$$\mu^+ \quad \text{---??---} \Rightarrow \mu^-$$

Transport general probability measures



Idea:

- Approximate μ^+ , μ^- by atomic measures a_i, b_i ;
- Transport a_i to b_i by a graph G_i ;
- The limit T of G_i (in a suitable sense) is a transportation of μ^+ to μ^- .

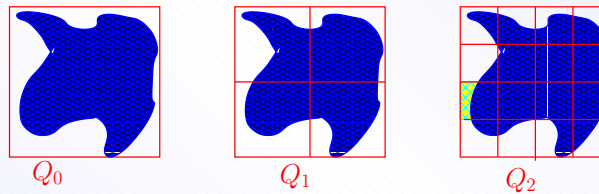
The sequence of triples $\{a_i, b_i, G_i\}$ is called an **approximating graph sequence** of T .

Dyadic approximation of Radon measures

Assume $X \subset Q$, a cube in \mathbf{R}^m of the edge length d , with center c . Let

$$Q_i = \{Q_i^h : h \in \mathbf{Z}^m \cap [0, 2^i)^m\}$$

be a partition of Q into smaller cubes of edge length $\frac{d}{2^i}$.



For any Radon measure μ on X , let

$$A_i(\mu) = \sum_h \mu(Q_i^h) \delta_{c_i^h}$$

where c_i^h is the center of Q_i^h . Then, $A_i(h)$ converges to μ weakly as measures. This is called “**Dyadic approximation of μ** ”.

How to take limits of G_i 's ? —Duality!!

Answer: View each G_i as a 1 dimensional **normal current** with $\partial G_i = b_i - a_i$.

Let $U \subset \mathbf{R}^m$ be any open set.

- $\mathcal{D}^n(U)$: C^∞ differential n -forms in U with compact support.
- An **n -current** is an element of the dual space $\mathcal{D}_n(U)$ of $\mathcal{D}^n(U)$. i.e. an n -current is a continuous linear functional on $\mathcal{D}^n(U)$. Thus, 0-currents are just distributions.
- For any $T \in \mathcal{D}_n(U)$, its **boundary** $\partial T \in \mathcal{D}_{n-1}(U)$ is given by

$$\partial T(\psi) = T(d\psi), \forall \psi \in \mathcal{D}^{n-1}(U).$$

- The **mass** of $T \in \mathcal{D}_n(U)$ is given by

$$\mathbf{M}(T) = \sup\{T(\omega) : |\omega| \leq 1, \omega \in \mathcal{D}^n(U)\}$$

- $T \in \mathcal{D}_n(U)$ is **normal** if $\mathbf{M}(T) + \mathbf{M}(\partial T) < +\infty$.

Examples of n-current

- Oriented n -dimensional submanifold M of U with $\mathcal{H}^n(M) < +\infty$.

$$[M](\omega) = \int_M \omega = \int_M \langle \omega(x), \xi(x) \rangle d\mathcal{H}^n(x)$$

for any $\omega \in \mathcal{D}^n(U)$. Note that $\partial[M] = [\partial M]$ and $\mathbf{M}([M]) = \mathcal{H}^n(M)$.

- Differential $m - n$ forms $\phi \in \mathcal{D}^{m-n}(U)$;

$$\phi(\omega) = \int_U \phi \wedge \omega.$$

- Rectifiable currents $\tau(M, \theta, \xi)$

$$\tau(M, \theta, \xi)(\omega) = \int_M \langle \omega(x), \xi(x) \rangle \theta(x) d\mathcal{H}^n(x)$$

Here: M is a rectifiable n -set, θ is a locally \mathcal{H}^n integrable function and $\xi(x)$ is the orientation of $T_x M$.

Transport paths between Radon measures

Definition. Given $\mu^+, \mu^- \in P(X)$, a normal 1-current T is called a *transport path* from μ^+ to μ^- if there exists a sequence of approximating graphs $\{a_i, b_i, G_i\}$ such that

$$a_i \rightharpoonup \mu^+, b_i \rightharpoonup \mu^-, G_i \rightharpoonup T$$

in the sense of distributions.

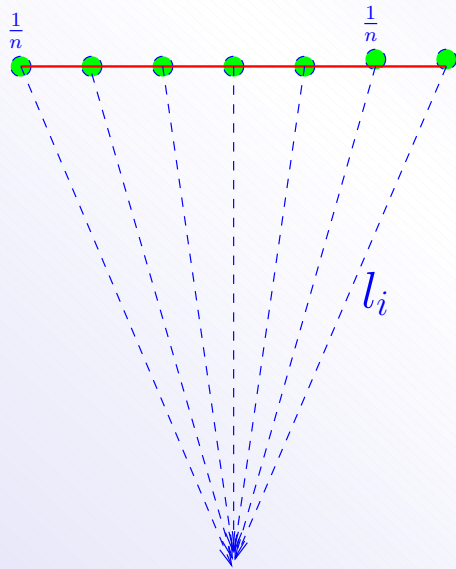
Note that we automatically have $\partial T = \mu^+ - \mu^-$ as distributions.

For each transport path T , we define

$$\mathbf{M}_\alpha(\mathbf{T}) := \inf_{\{a_i, b_i, G_i\}} \liminf_{\mathbf{i} \rightarrow \infty} \mathbf{M}_\alpha(\mathbf{G}_i).$$

Let $Path(\mu^+, \mu^-)$ be the family of all transport paths from μ^+ to μ^- .

Example: How to transport a Lebesgue measure to a Dirac measure?

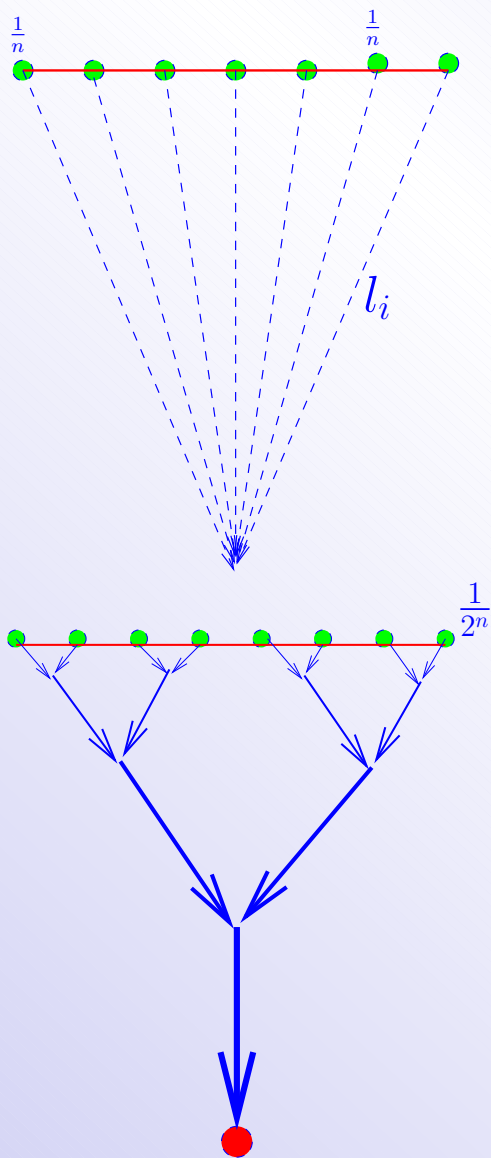


First attempt:

$$\sum_{i=1}^n \left(\frac{1}{n}\right)^{\alpha} l_i$$

$$\approx C \sum_{i=1}^n \left(\frac{1}{n}\right)^{\alpha} = C n^{1-\alpha} \rightarrow +\infty.$$

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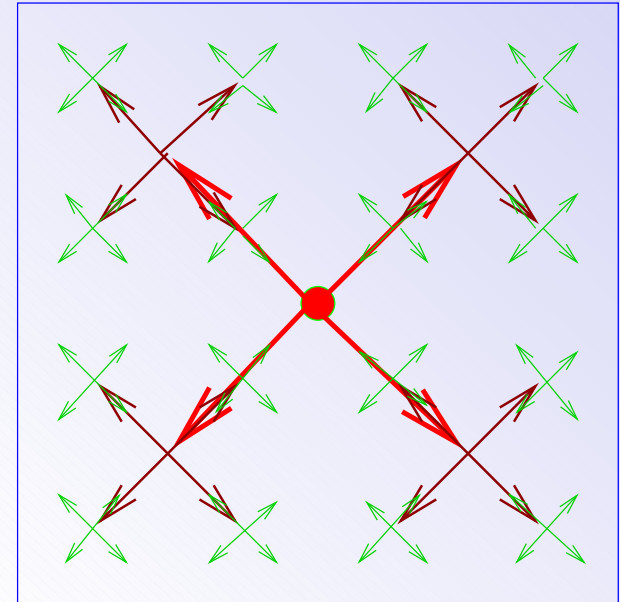
Second attempt:

$$\sum_{n=1}^{\infty} \sum_{i=1}^{2^n} \left(\frac{1}{2^n}\right)^\alpha l_i \approx C \sum_{n=1}^{\infty} \sum_{i=1}^{2^n} \left(\frac{1}{2^n}\right)^\alpha \frac{1}{2^n}$$

$$= C \sum_{n=1}^{\infty} \left(\frac{1}{2^n}\right)^\alpha = \frac{C}{1 - \frac{1}{2^\alpha}}$$

In higher dimension case, if $\alpha > 1 - \frac{1}{m}$, then

$$\begin{aligned}
 & \sum_{n=1}^{\infty} \sum_{i=1}^{(2^n)^m} \left(\frac{1}{(2^n)^m} \right)^\alpha l_i \\
 & \approx C \sum_{n=1}^{\infty} \sum_{i=1}^{(2^n)^m} \left(\frac{1}{(2^n)^m} \right)^\alpha \frac{1}{2^n} \\
 & = C \sum_{n=1}^{\infty} \left(\frac{1}{(2^n)^m} \right)^\alpha 2^{n(m-1)} \\
 & = C \sum_{n=1}^{\infty} \left(2^{m(1-\alpha)-1} \right)^n < +\infty
 \end{aligned}$$



Proposition. *[Finite Cost] (Xia, 2001) Suppose $\alpha > 1 - \frac{1}{m}$. For any $\mu \in P(X)$, there exists a $T \in \text{Path}(\mu, \delta_c)$ from μ to a Dirac measure δ_c with $\mathbf{M}_\alpha(\mathbf{T}) < +\infty$.*

Existence theorem (Xia, 2001)

Theorem. Given μ^+ and $\mu^- \in \mathcal{M}_\Lambda(X)$, $\alpha \in (1 - \frac{1}{m}, 1]$, there exists an \mathbf{M}_α mass minimizer S in the family $\text{Path}(\mu^+, \mu^-)$. Moreover, $\mathbf{M}_\alpha(\mathbf{S}) < \frac{\Lambda^\alpha}{2^{1-m(1-\alpha)} - 1} \frac{\sqrt{md}}{2}$.

Sketch of the proof:

- Pick $\{a_i, b_i, G_i\}$ with

$$\mathbf{M}_\alpha(\mathbf{G}_i) \searrow \inf\{\mathbf{M}_\alpha(\mathbf{T}) : \mathbf{T} \in \mathbf{Path}(\mu^+, \mu^-)\}$$

- We may assume $\{G_i\}$ has no cycles

$$M(G_i) \leq \mathbf{M}_\alpha(\mathbf{G}_i) < \mathbf{C} \text{ bounded.}$$

- By the compactness of normal currents,

$$G_{i_k} \rightharpoonup T \in \text{Path}(\mu^+, \mu^-)$$

- lower semicontinuity of \mathbf{M}_α .

A new distance on $P(X)$

Definition. Given μ^+ and $\mu^- \in P(X)$, define

$$d_\alpha(\mu^+, \mu^-) := \min\{\mathbf{M}_\alpha(\mathbf{T}) : \mathbf{T} \in \mathbf{Path}(\mu^+, \mu^-)\}.$$

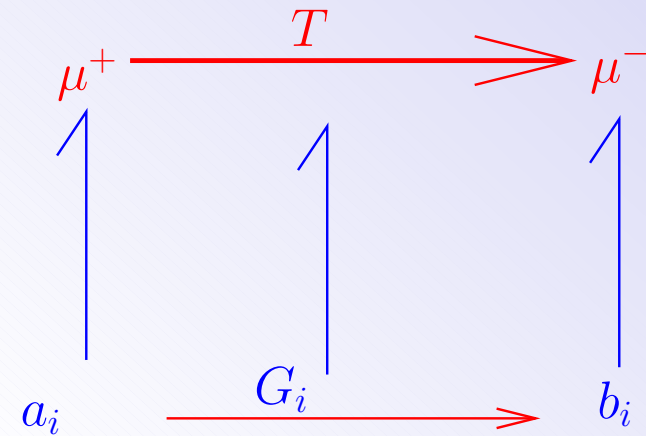
Theorem. (Xia, 2001) d_α is a distance on $P(X)$.

Remark: d_α is different from any of the Wassenstein distances.

Theorem. (Xia, 2001) d_α metrizes the weak * topology of $P(X)$.

Optimal transport paths

Lemma. If $G_i \in \text{Path}(a_i, b_i)$ is an \mathbf{M}_α minimizer, then $T \in \text{Path}(\mu^+, \mu^-)$ is also an \mathbf{M}_α minimizer in $\text{Path}(\mu^+, \mu^-)$.



Definition. A transport path $T \in \text{Path}(\mu^+, \mu^-)$ is called an *optimal transport path* if there exists a sequence of approximating graphs $\{a_i, b_i, G_i\}$ such that each $G_i \in \text{Path}(a_i, b_i)$ is an \mathbf{M}_α minimizer.

Error estimate

By the lemma, we can pick our **favorite** approximating atomic measures $\{a_i\}, \{b_i\}$.

We choose “dyadic approximation” $\{A_n(\mu)\}$.

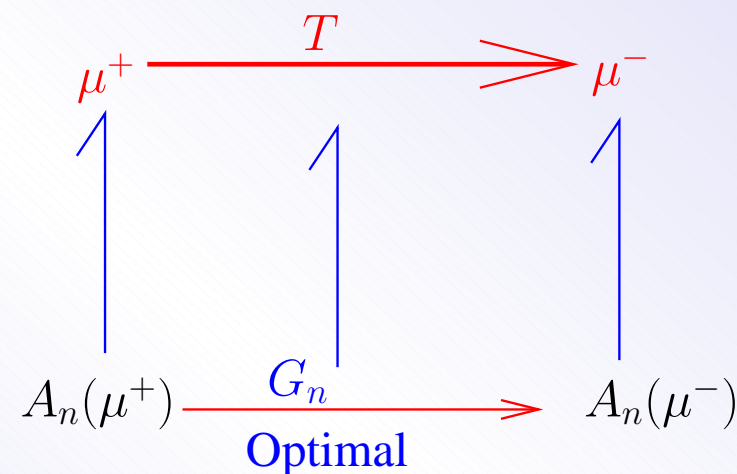
Proposition. For any $\mu \in P(X)$,

$$d_\alpha(\mu, A_n(\mu)) \leq C\lambda^n$$

with some constant $C > 0$ and $\lambda = 2^{m(1-\alpha)-1} \in (0, 1)$.

Corollary. If each G_n is optimal, then

$$M_\alpha(\mathbf{T}) \leq M_\alpha(\mathbf{G}_n) + 2C\lambda^n$$



Length Space Property

Theorem. (Xia, 2002) $(P(X), d_\alpha)$ is a length space.

That is, for any $\mu^+, \mu^- \in P(X)$, there exists a continuous map

$$\psi : [0, t] \rightarrow (P(X), d_\alpha)$$

with $t = d_\alpha(\mu^+, \mu^-)$ such that

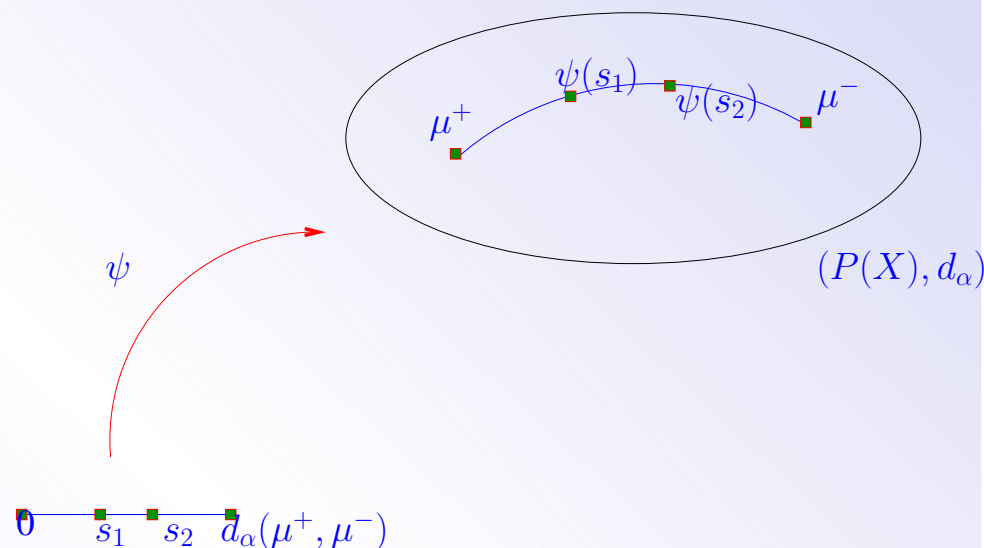
$$\psi(0) = \mu^+, \psi(T) = \mu^-$$

and for any $0 \leq s_1 < s_2 \leq t$,

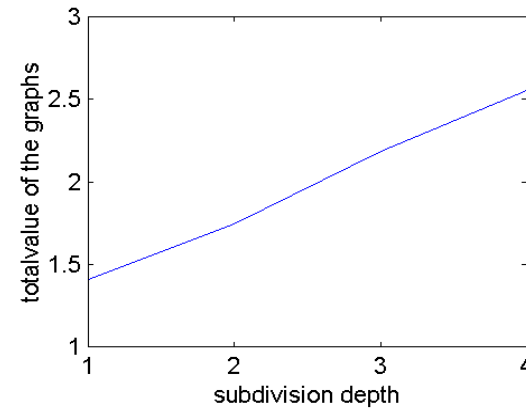
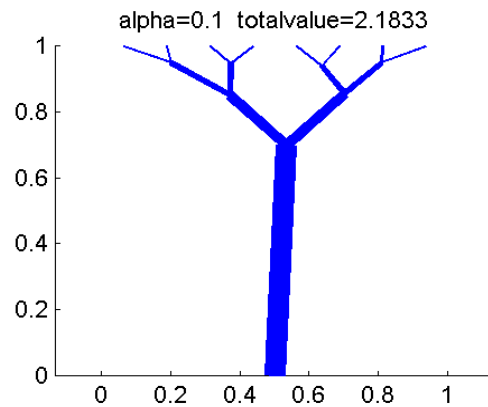
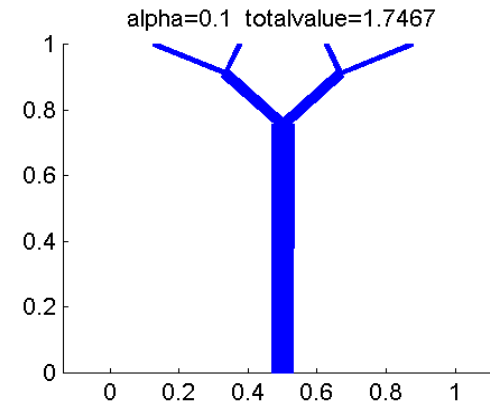
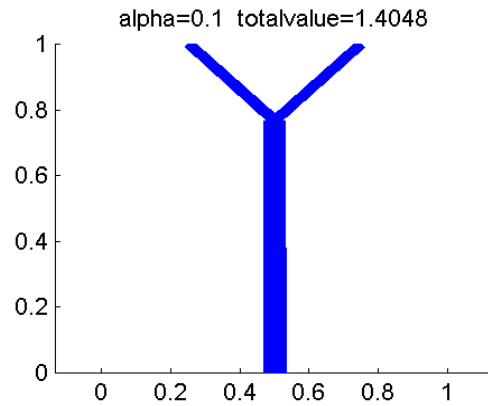
$$d_\alpha(\psi(s_1), \psi(s_2)) = s_2 - s_1.$$

In other words, an optimal transport path between Radon measures plays the role of a **geodesic** between two points.

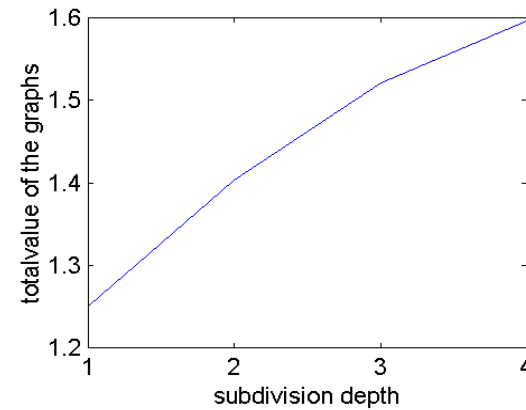
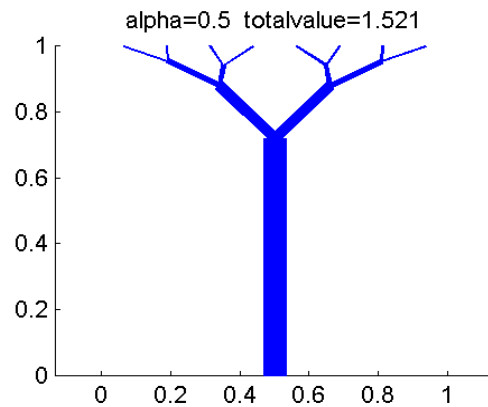
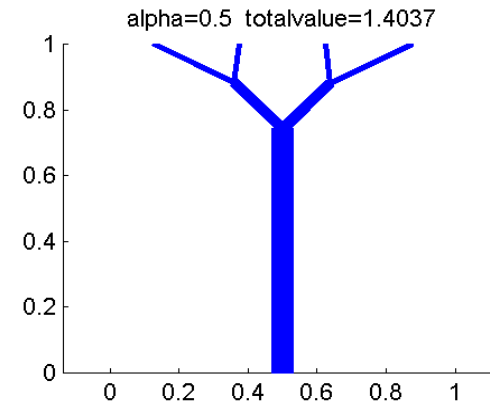
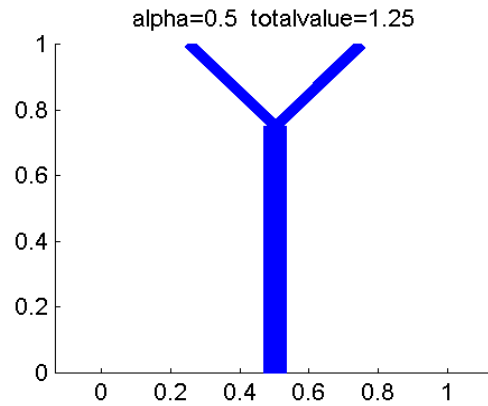
Later, we will see that in fact **each $\psi(s)$ is purely atomic for any $0 < s < t$.**



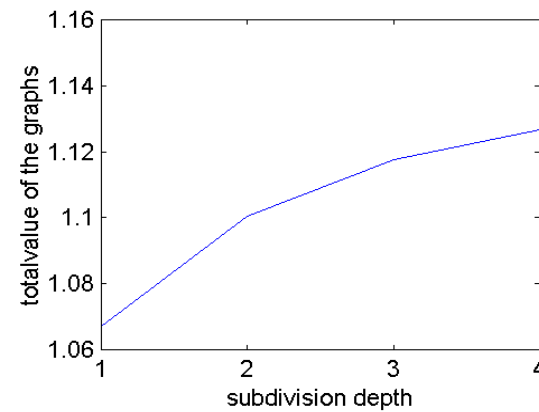
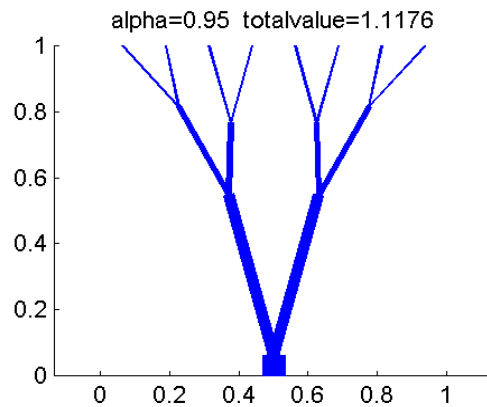
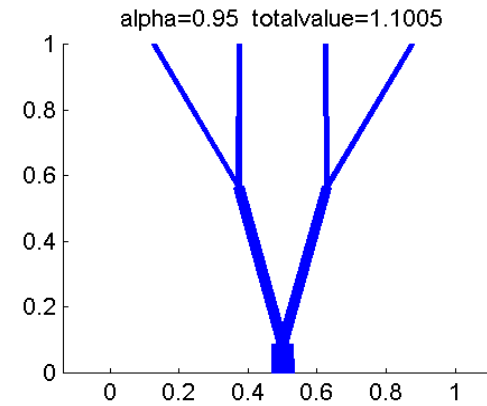
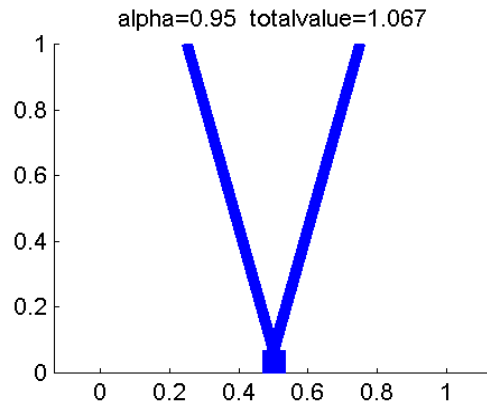
Atomic approximation ($\alpha = 0.1$)



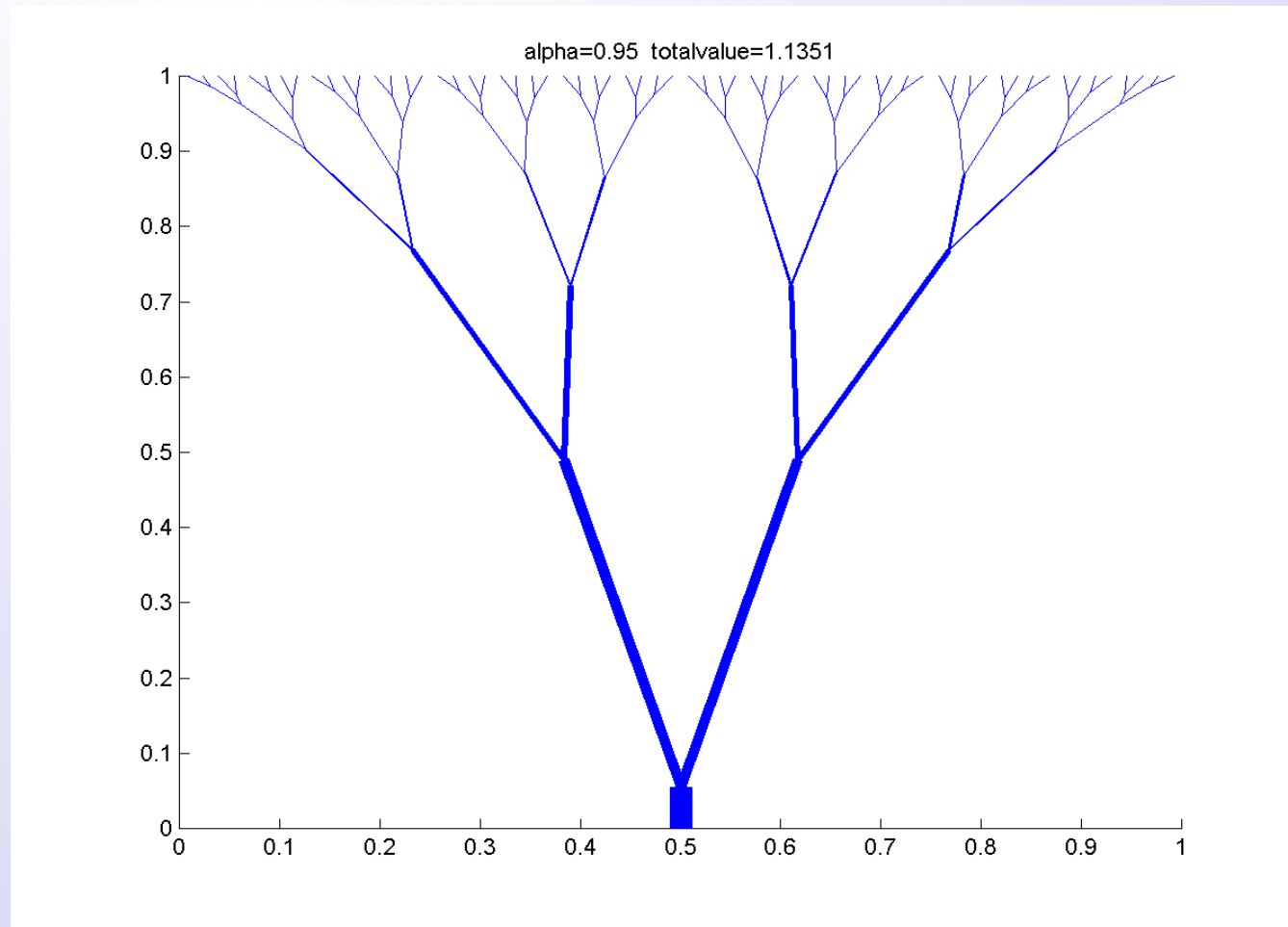
Atomic approximation ($\alpha = 0.5$)



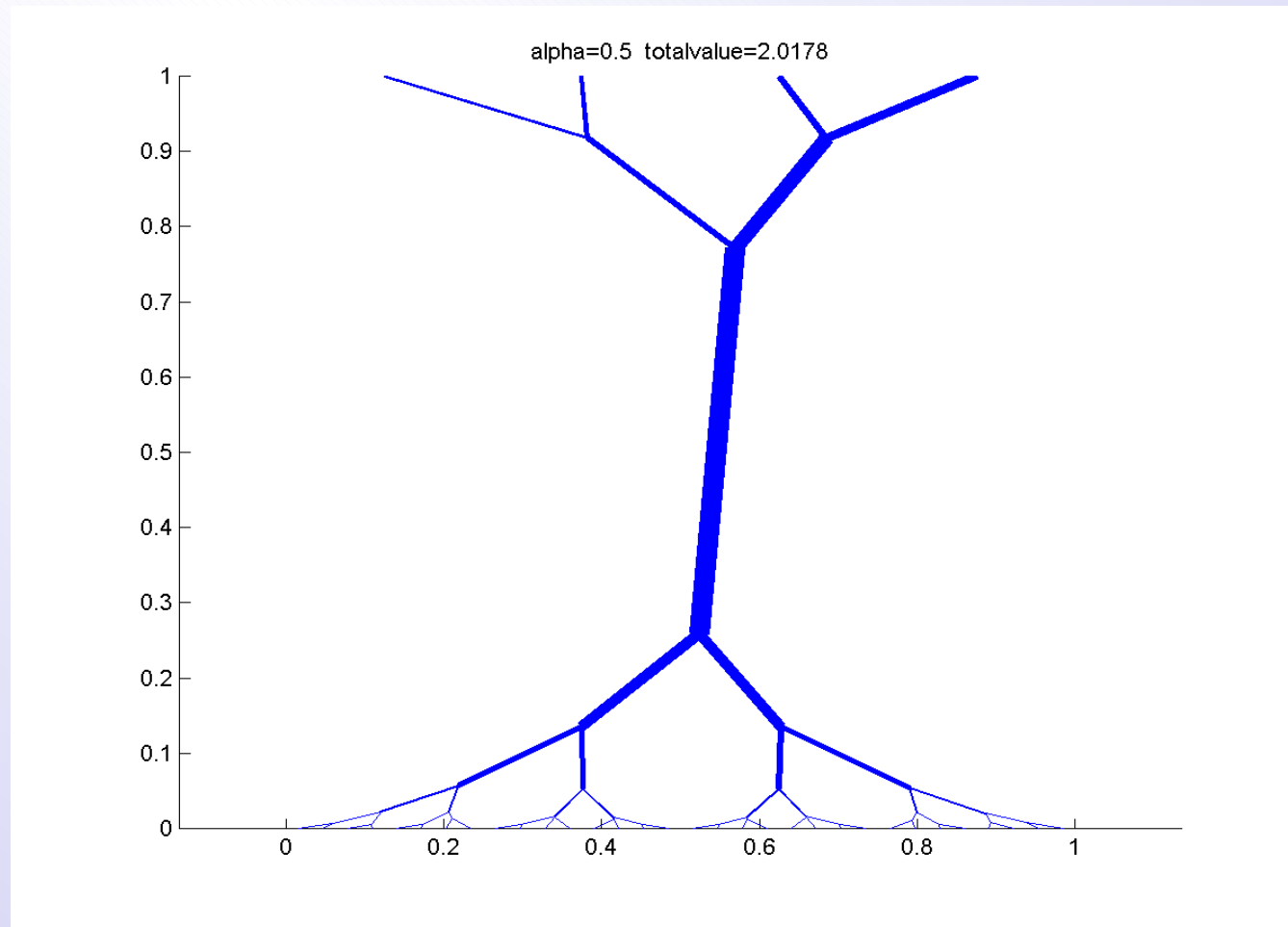
Atomic approximation ($\alpha = 0.95$)



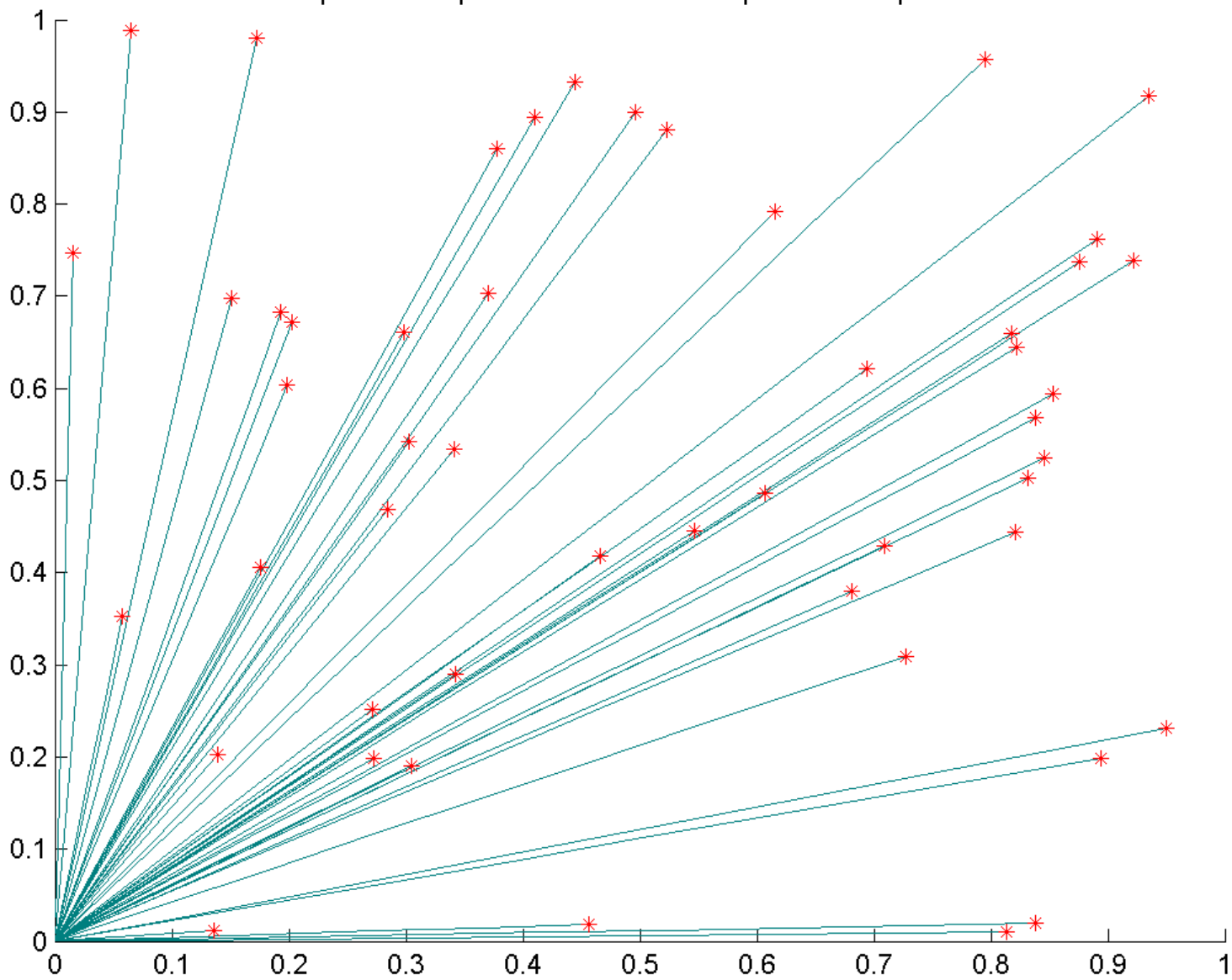
From Lebesgue to Dirac



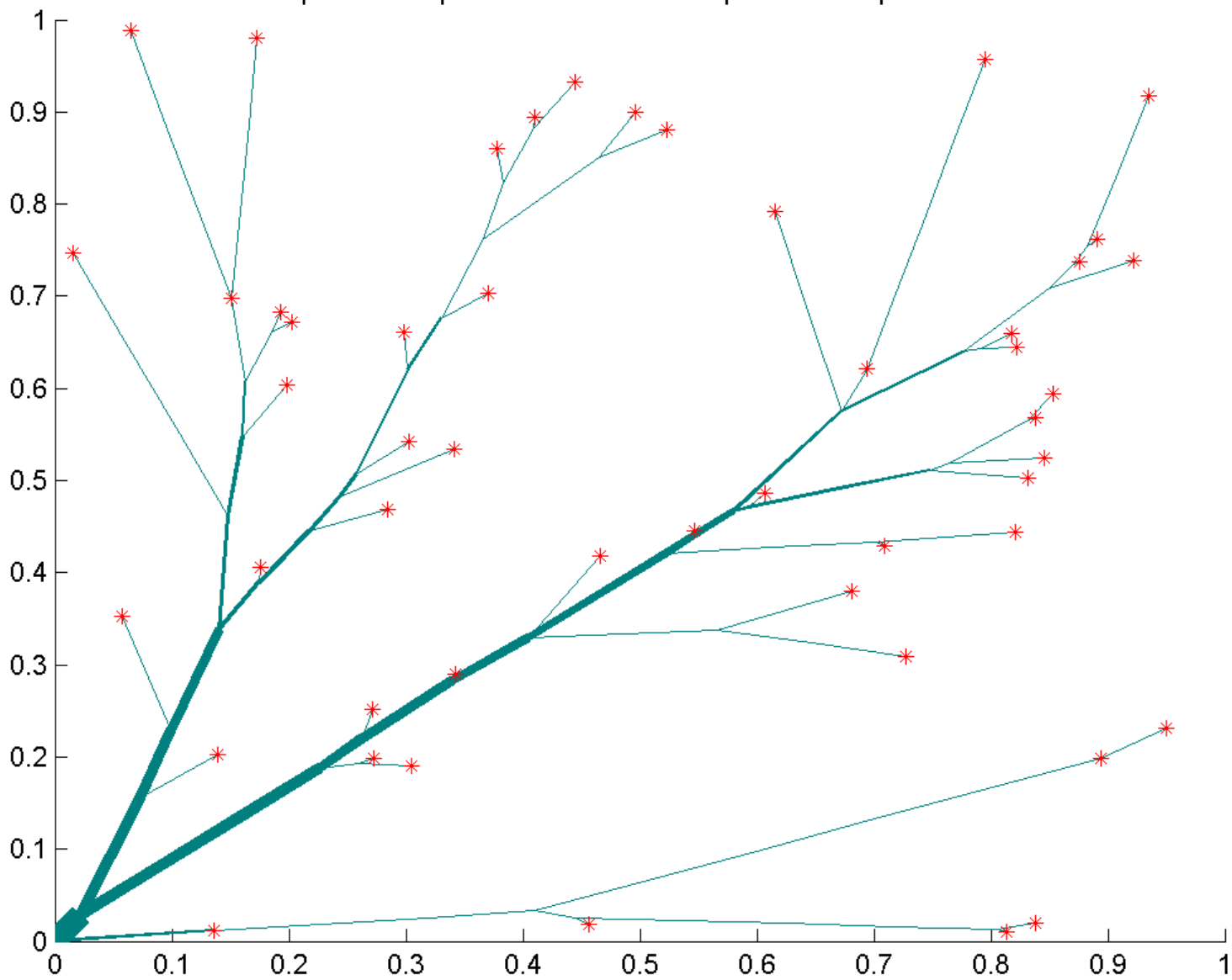
Transporting general measures



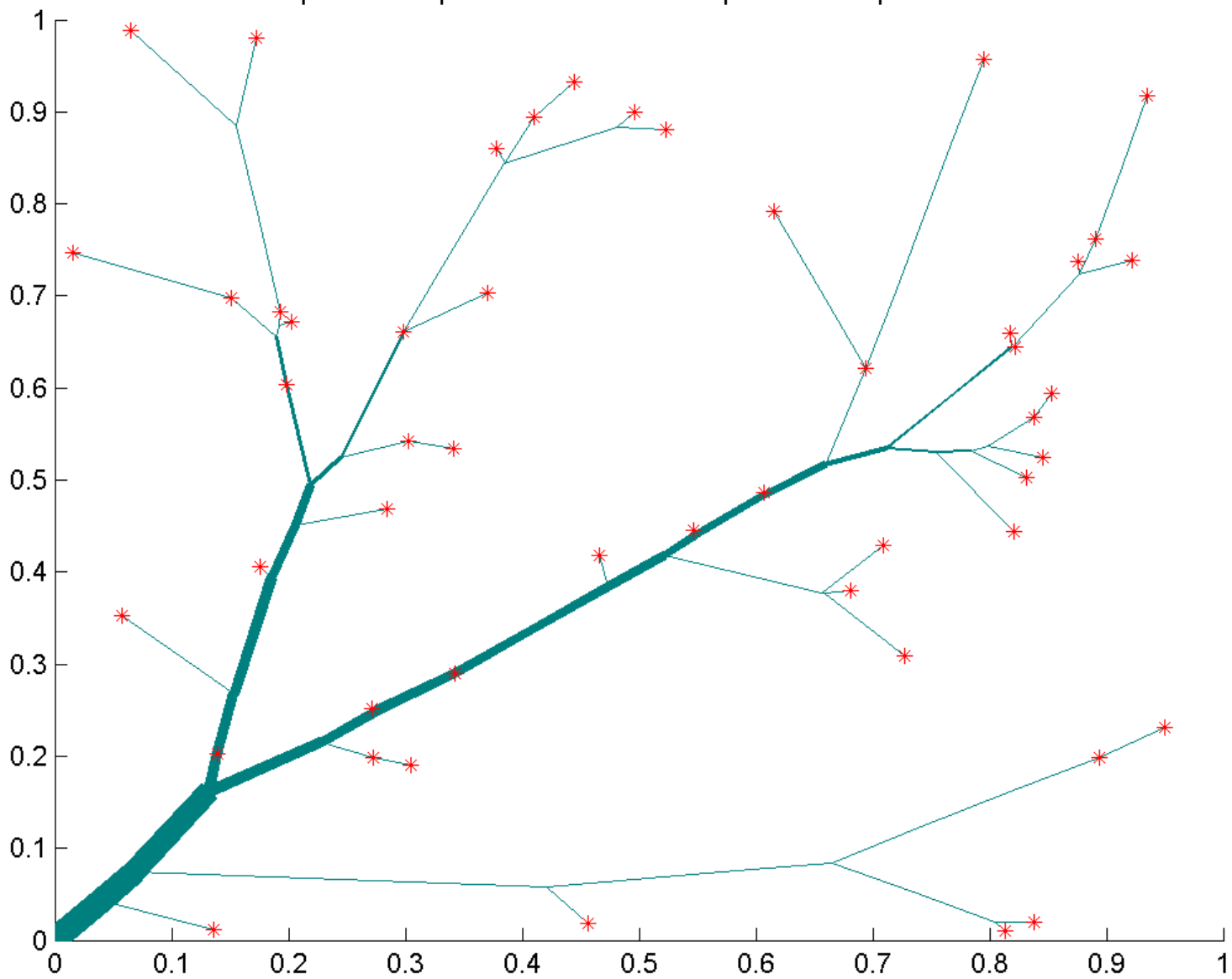
optimal transportation of 50 random points with alpha=1



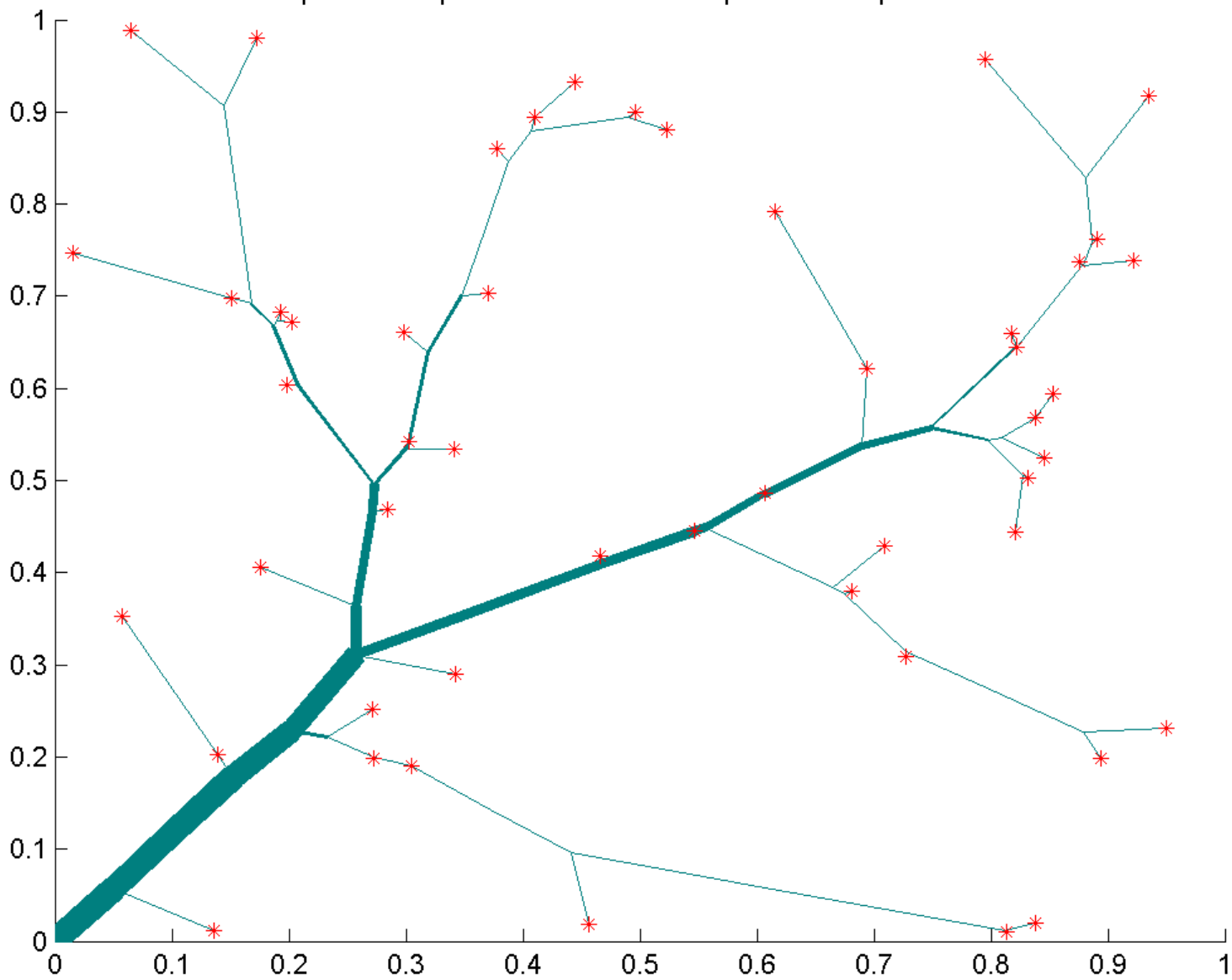
optimal transportation of 50 random points with alpha=0.95



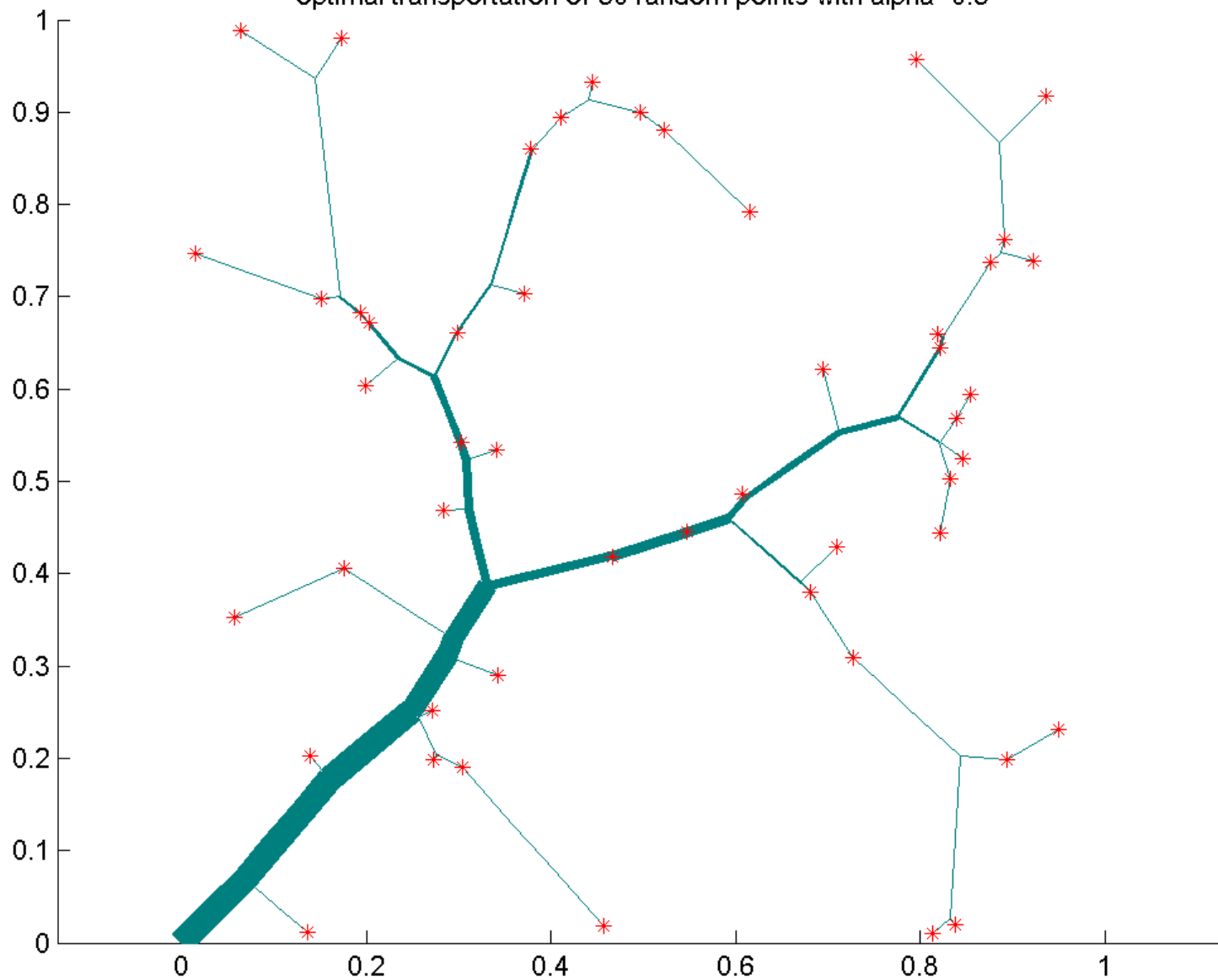
optimal transportation of 50 random points with alpha=0.85



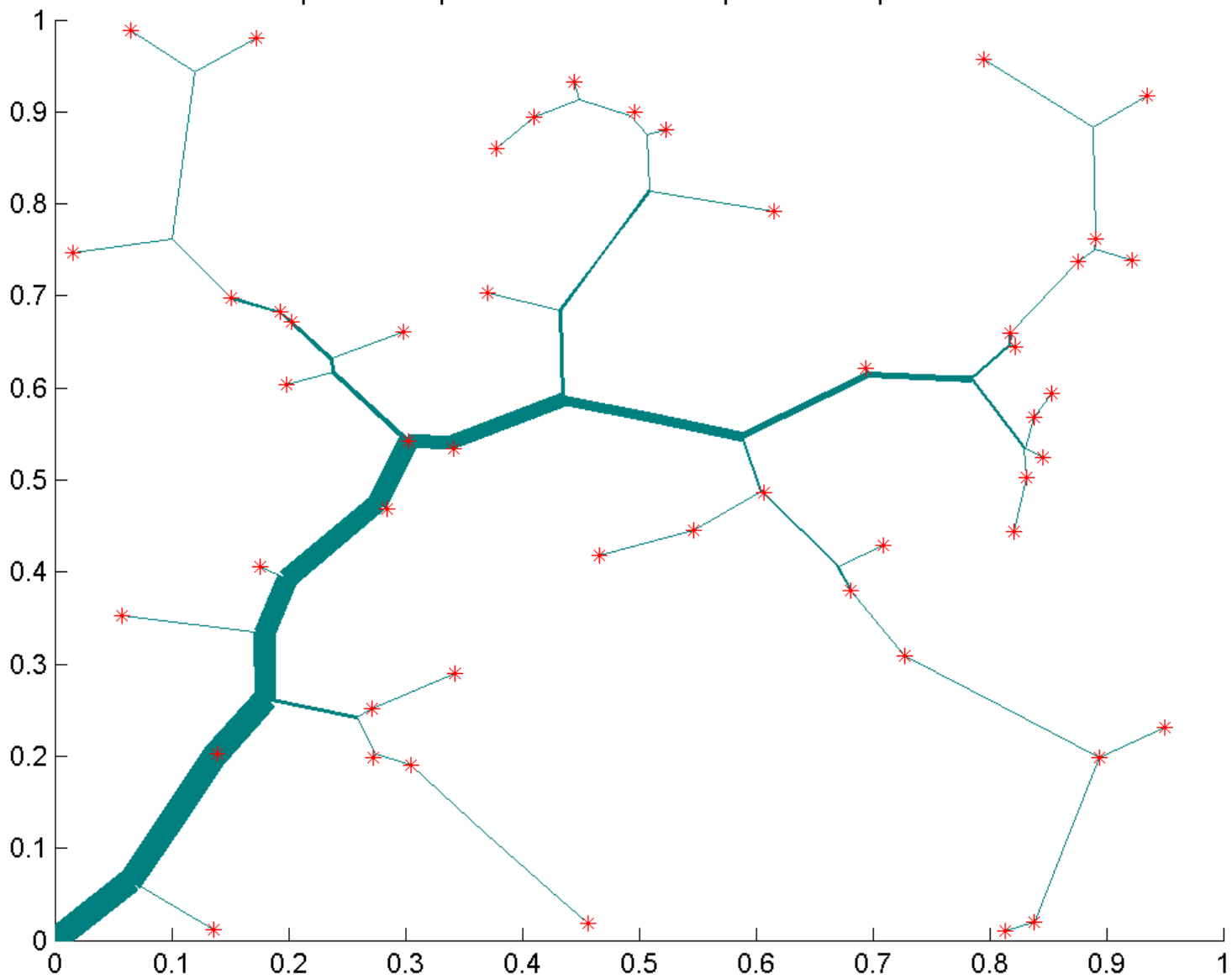
optimal transportation of 50 random points with alpha=0.75



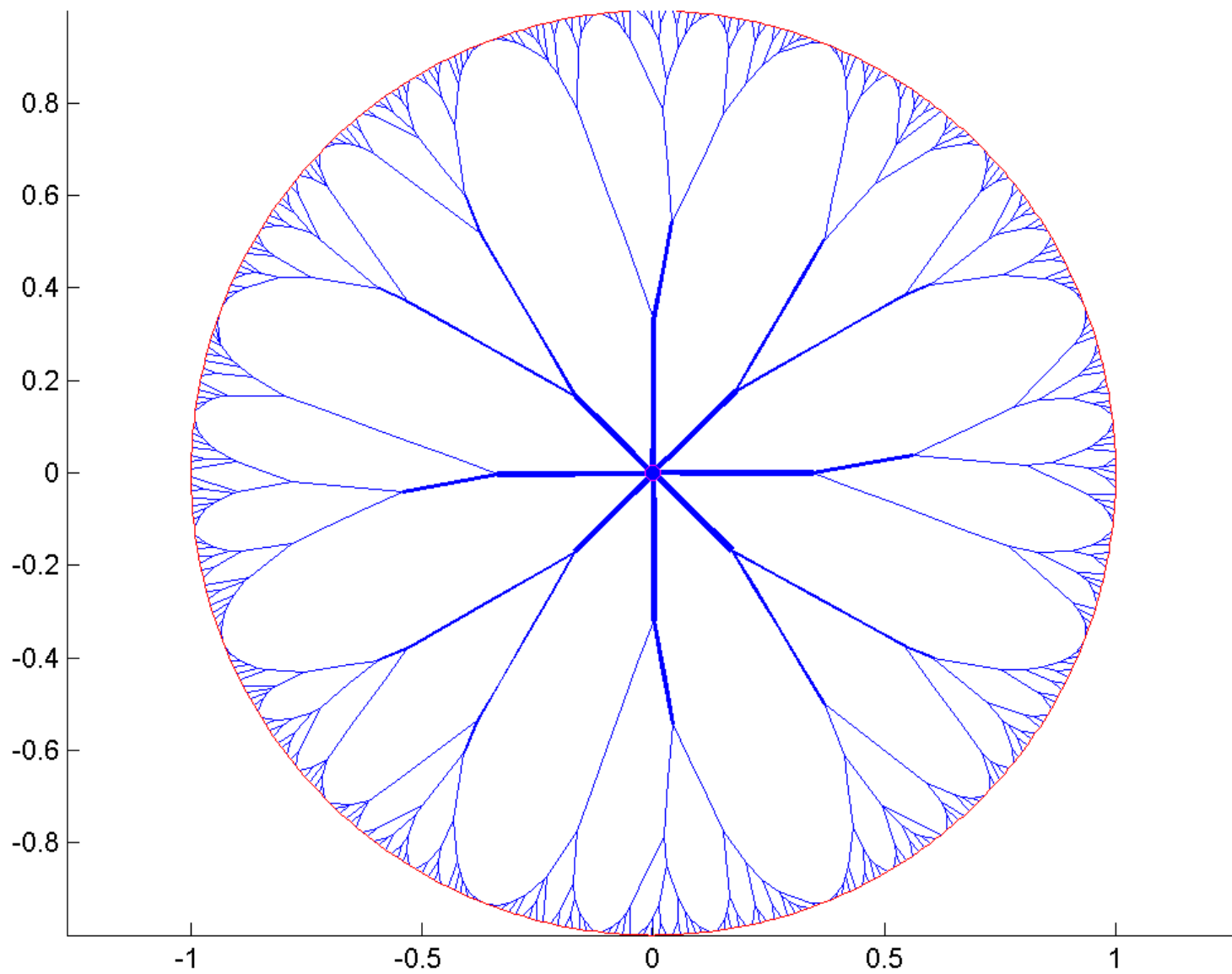
optimal transportation of 50 random points with alpha=0.5



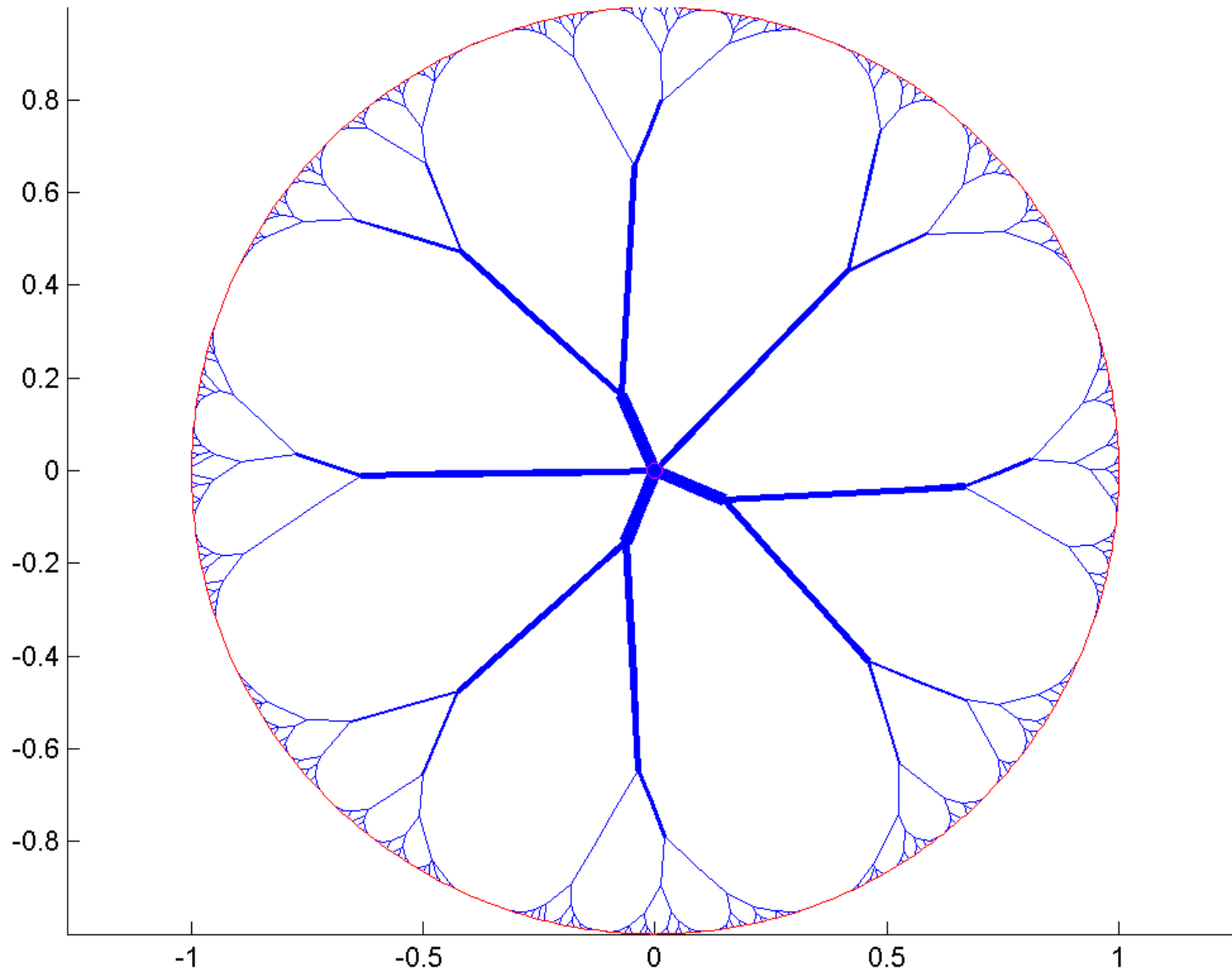
optimal transportation of 50 random points with alpha=0.25



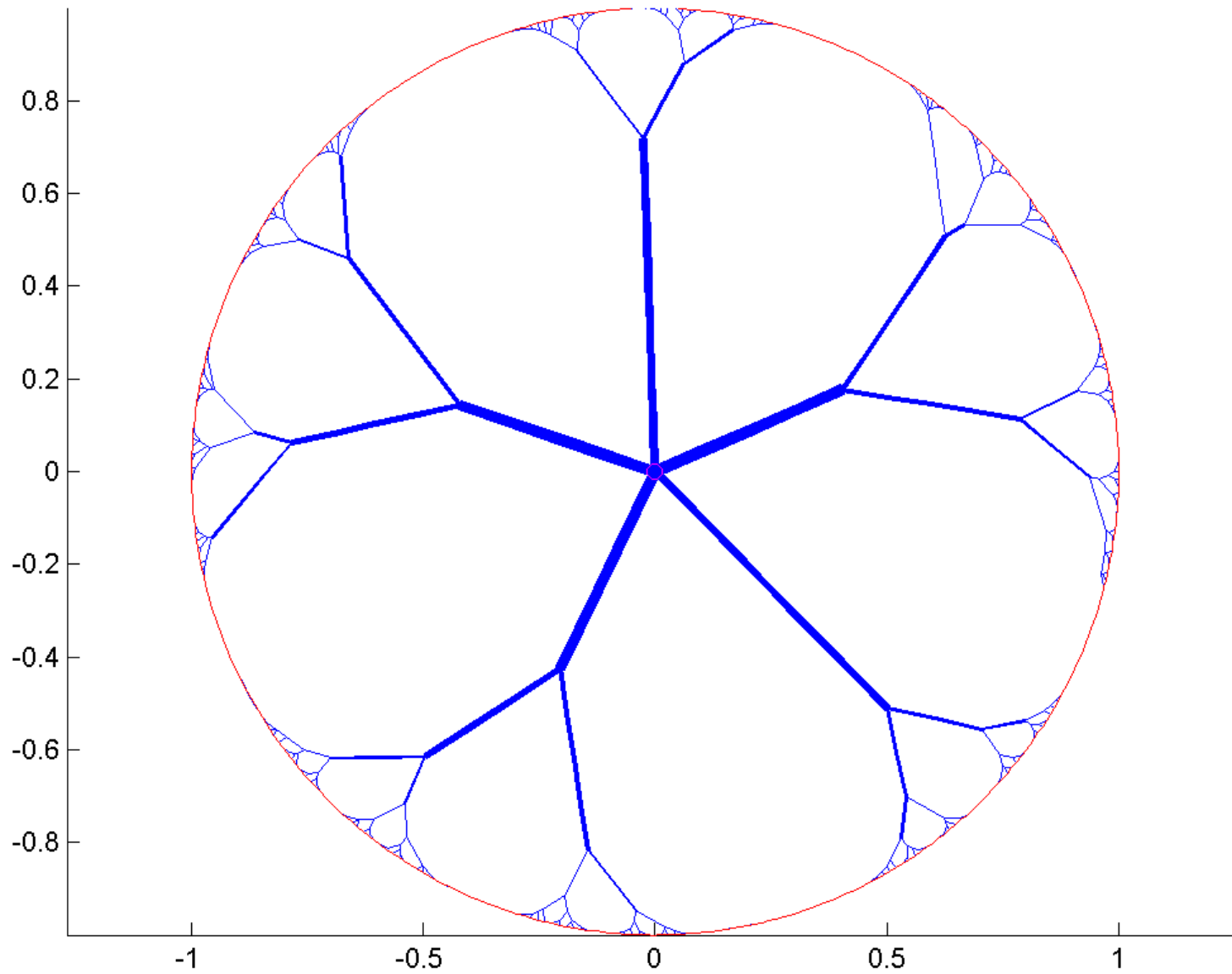
400 points, alpha=0.95, cost=1.1989



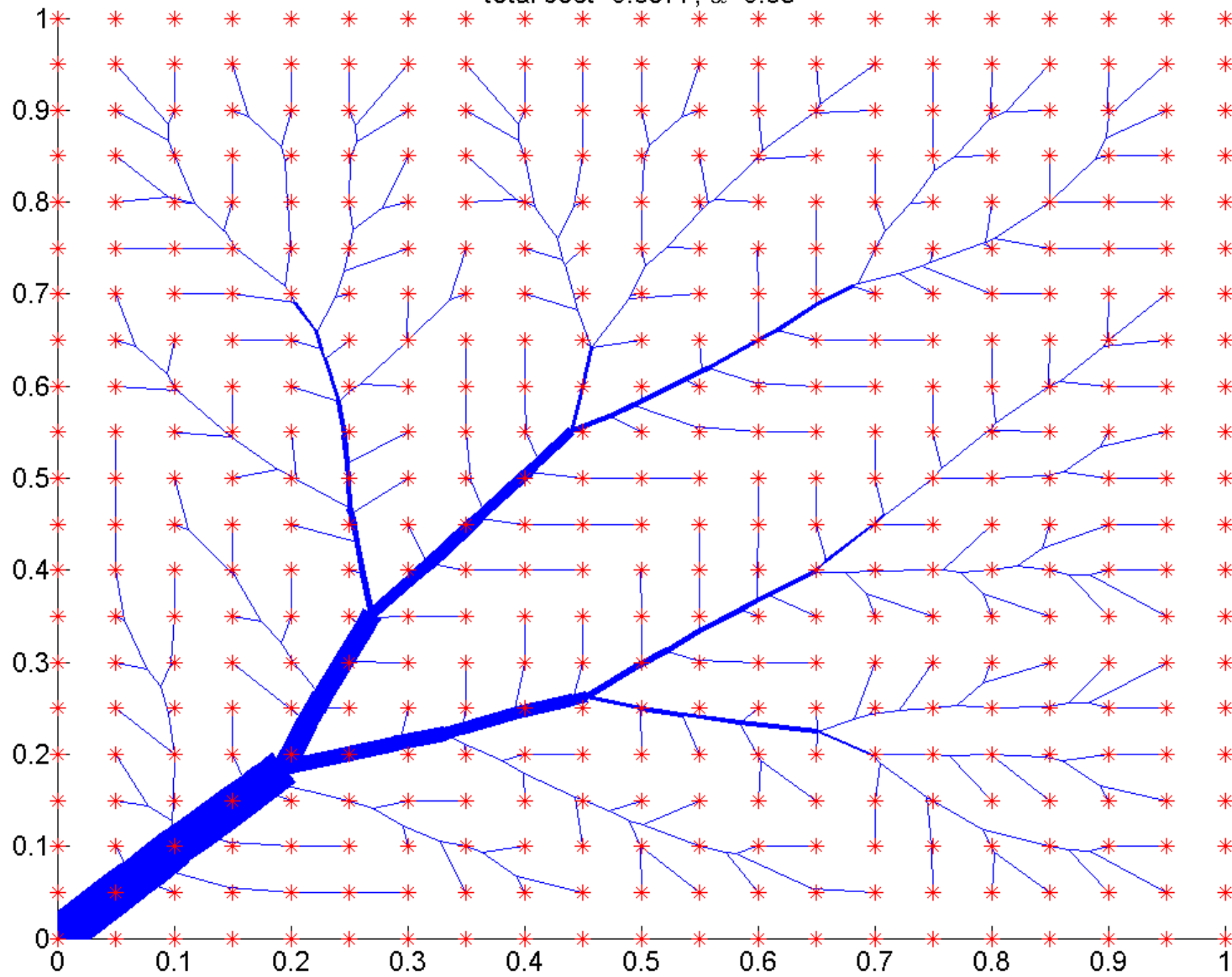
400 points, alpha=0.85, cost=1.5913



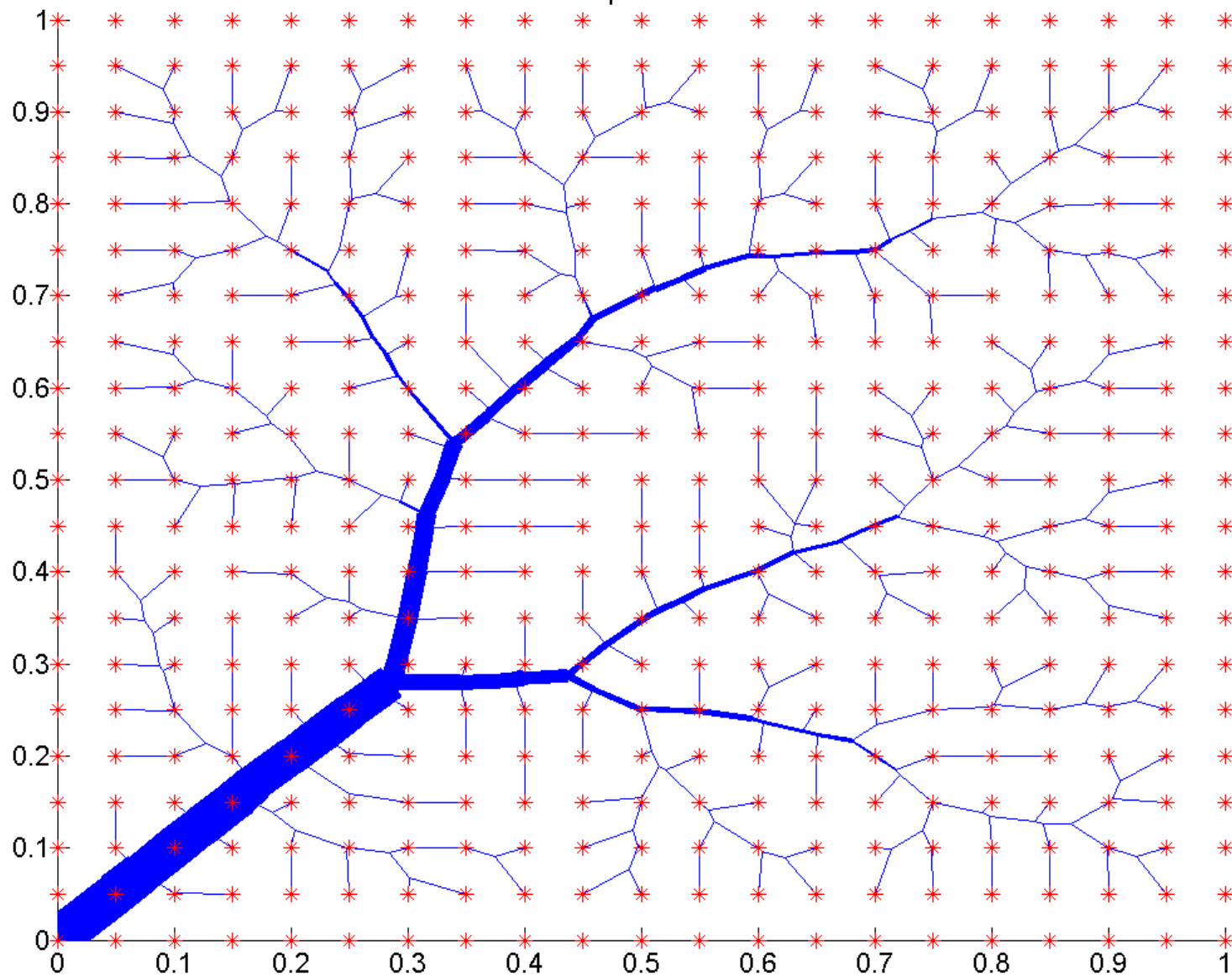
400 points, alpha=0.75, cost=2.0390



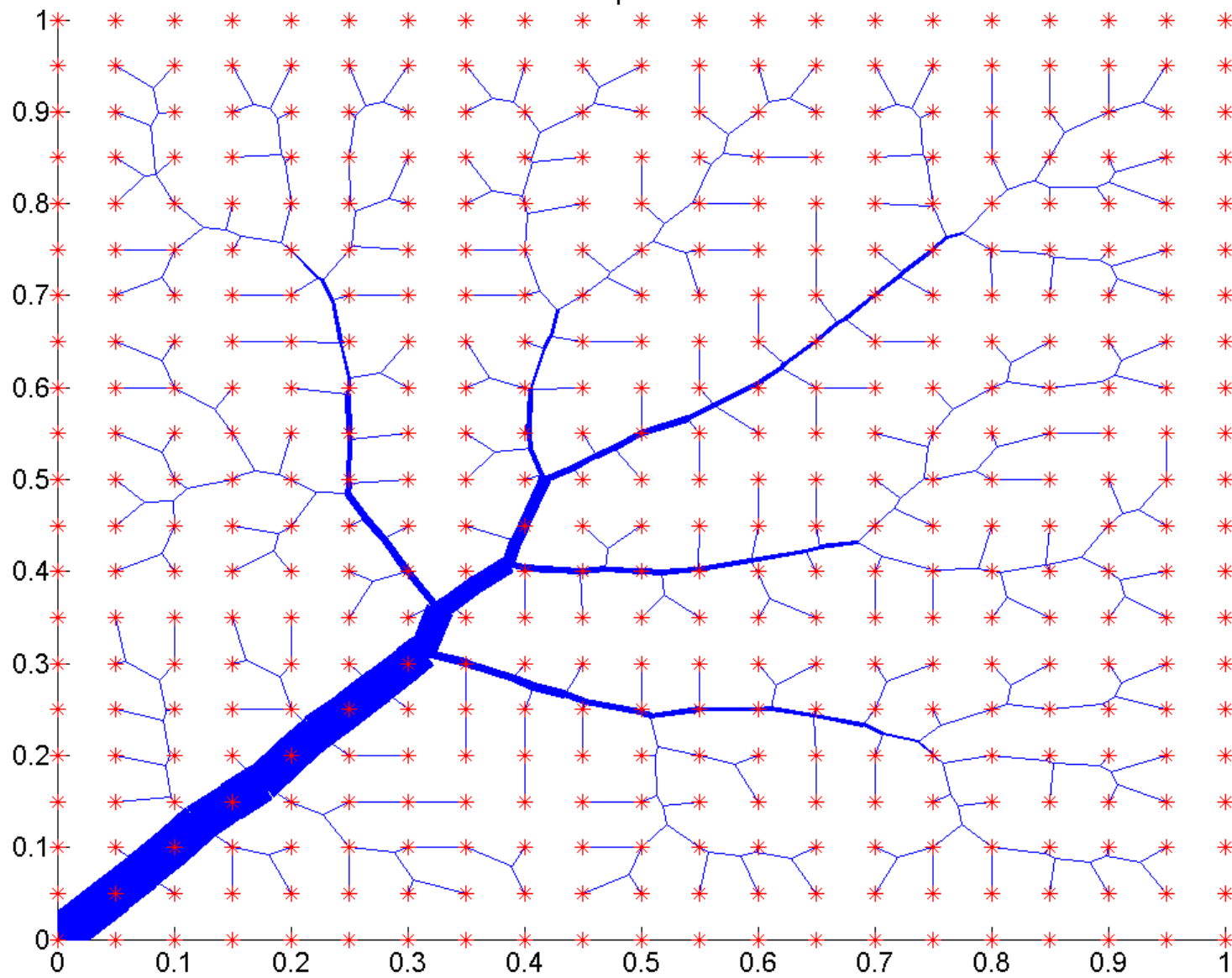
total cost=0.8977, $\alpha=0.85$



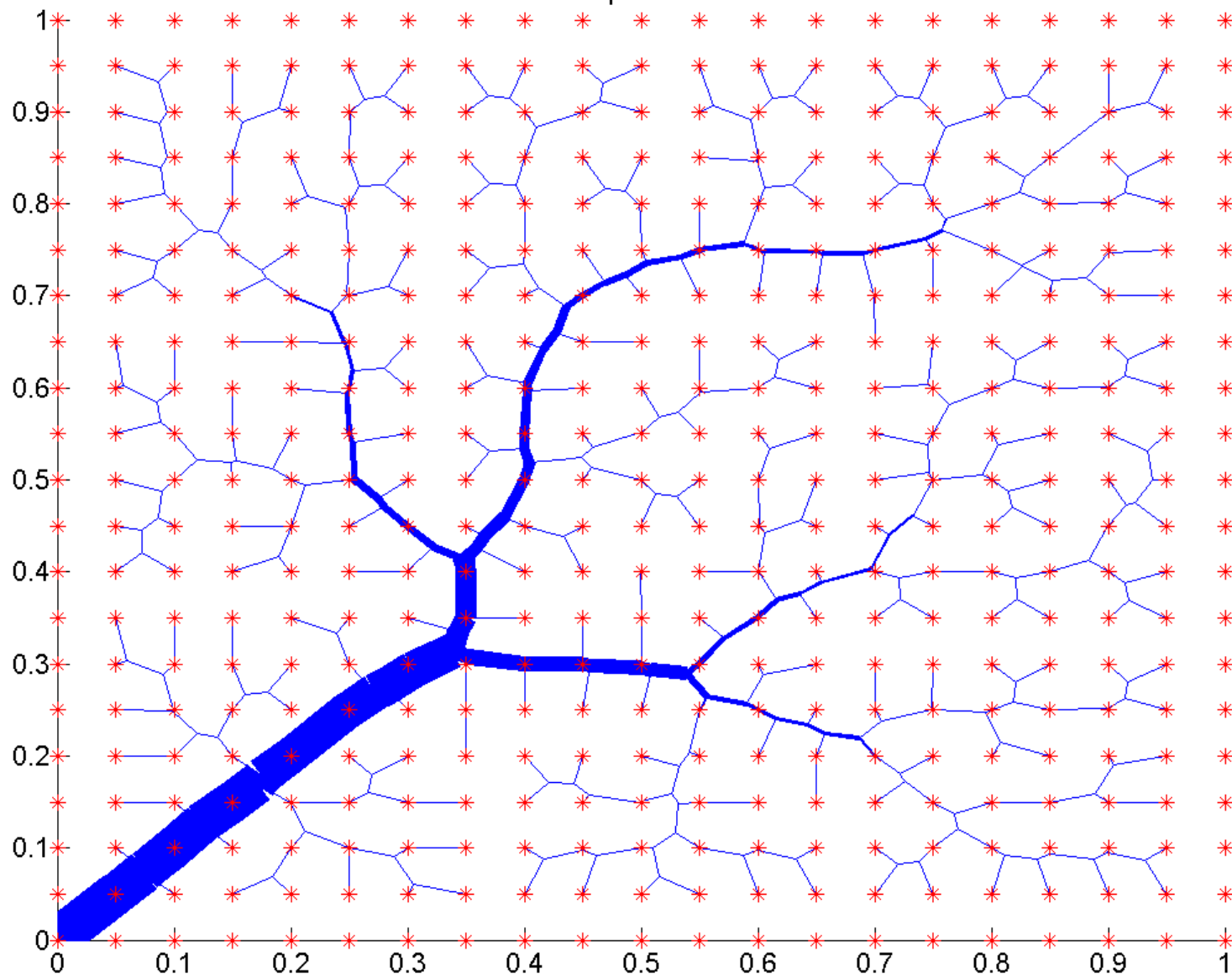
α equals 0.65



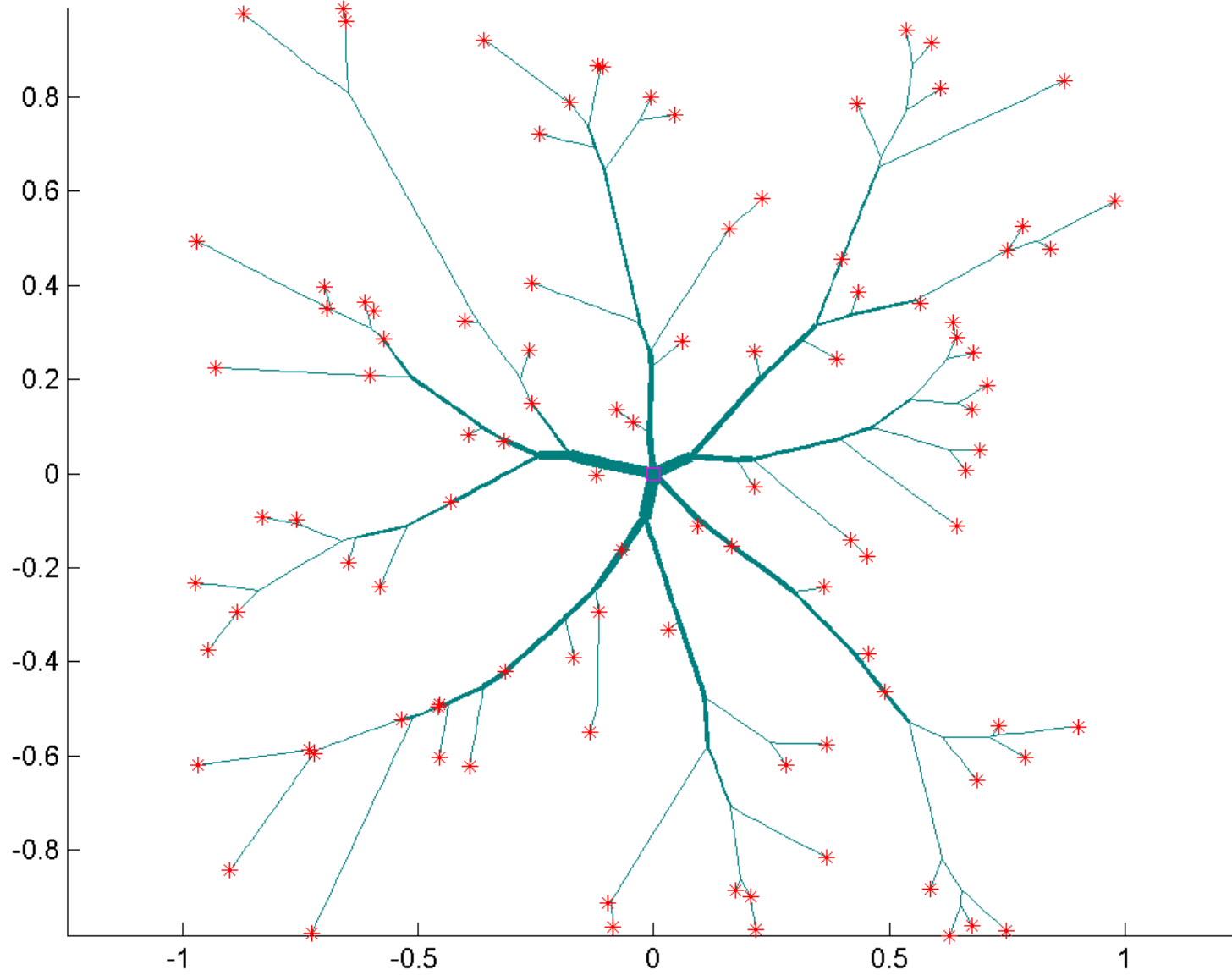
α equals 0.5

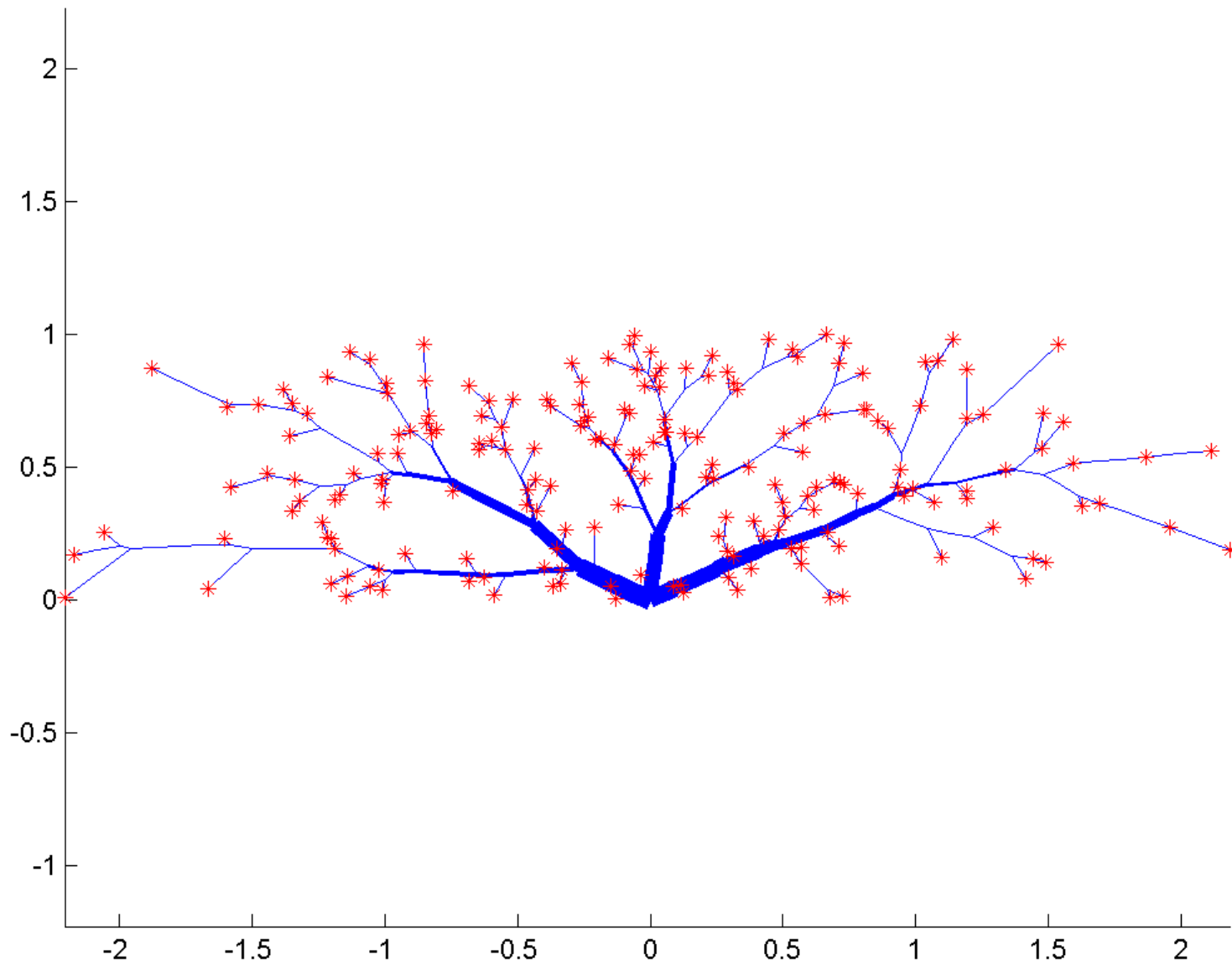


α equals 0.35

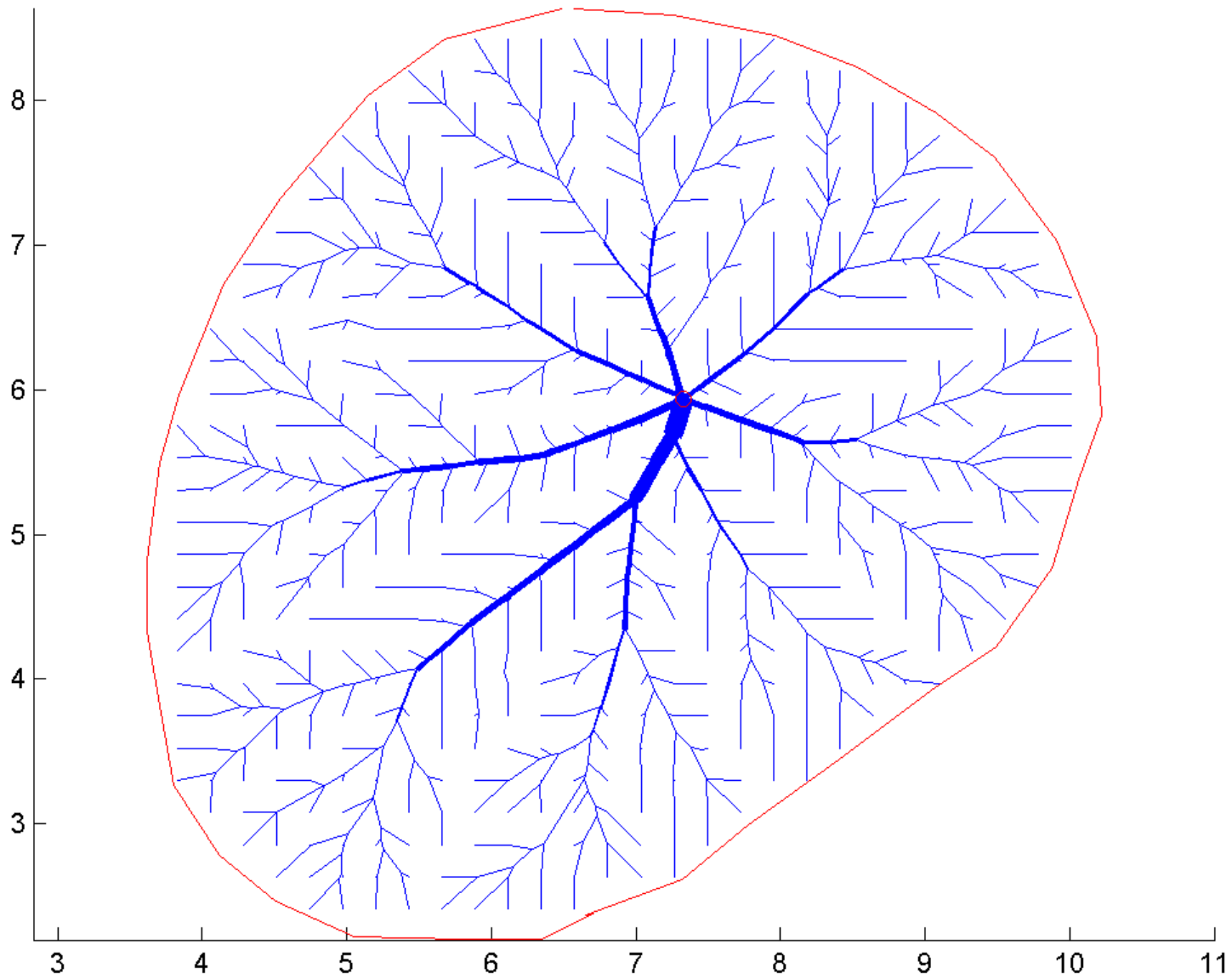


optimal transportation of 100 random points



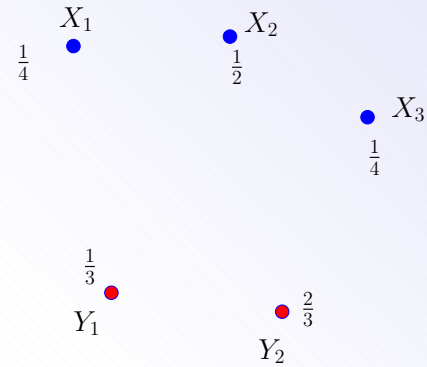


optimal transport path for Placental ID 1713



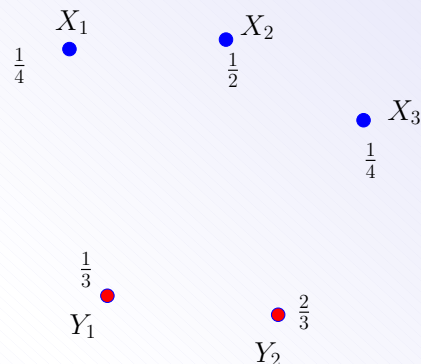
Transport Path & Transport Plan

Let a and b be any two atomic measures. For example,



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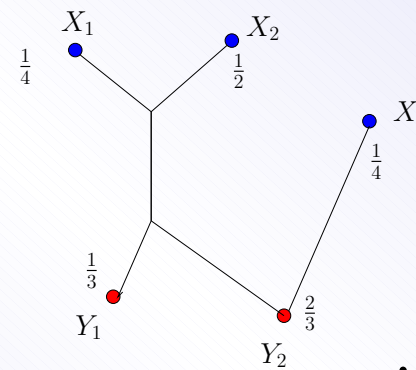
- Each transport plan $\gamma \in \text{Plan}(a, b)$ is given by a real valued matrix

$$U = (u_{ij}).$$

e.g.

$$U_1 = \begin{pmatrix} \frac{1}{4} & \frac{1}{12} & 0 \\ 0 & \frac{5}{12} & \frac{1}{4} \end{pmatrix} \text{ or } U_2 = \begin{pmatrix} 0 & \frac{1}{12} & \frac{1}{4} \\ \frac{1}{4} & \frac{5}{12} & 0 \end{pmatrix}$$

- Each transport path $G \in \text{Path}(a, b)$ gives a 1-current valued matrix $g(G) = (g_{ij})$. (no cycles!)



Compatible Pair of Transport Path & Plan

A transport path G and a transport plan γ are said to be **compatible** if

$$G = \sum u_{ij} \cdot g_{ij}.$$

A compatible pair gives a decomposition of G .

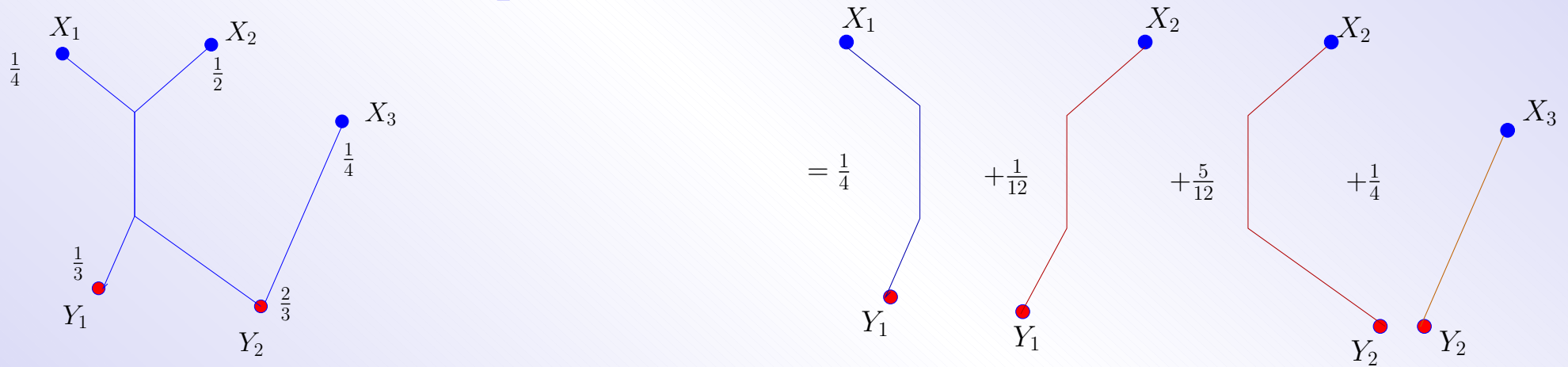
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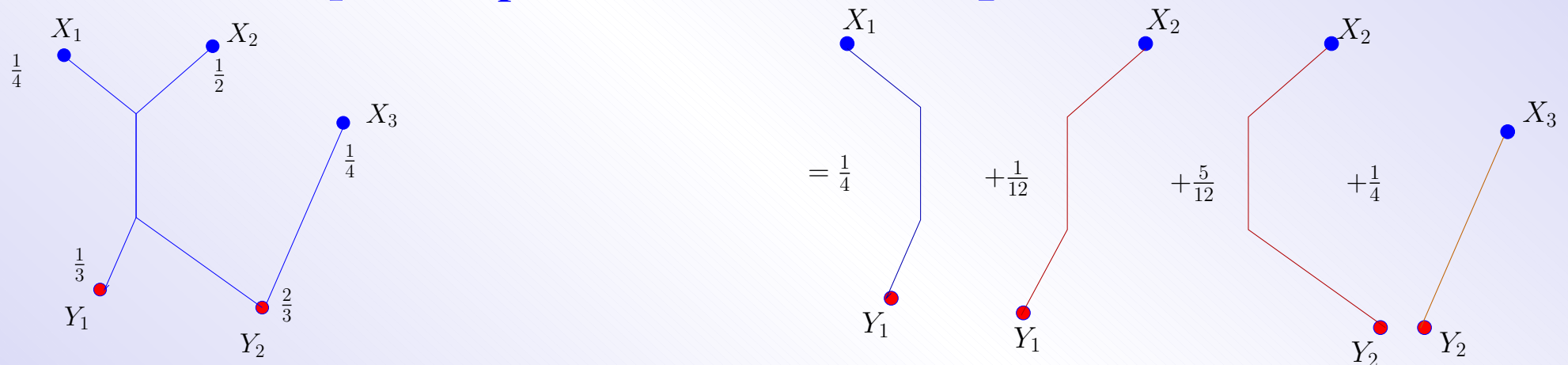
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A compatible pair of transport path and transport plan provides the necessary transporting information by its unique matrix representation $((u_{ij}), (g_{ij}))$.

u_{ij} = amount of mass from x_i to y_j , while g_{ij} = actual transport path.

Some Results (Xia, 2001)

- There exists $G \in Path(a, b)$ compatible with all $\gamma \in Plan(a, b)$.
- For any $G \in Path(a, b)$, there exists a $\gamma \in Plan(a, b)$ compatible with G .
- Given a transport plan $\gamma \in Plan(\mu^+, \mu^-)$, there exists an optimal transport path $T \in Path(\mu^+, \mu^-)$ with least finite M_α cost among all compatible pairs (T, γ) . (mailing problem)
- Given a transport path $T \in Path(\mu^+, \mu^-)$, there exists an optimal transport plan $\gamma \in Plan(\mu^+, \mu^-)$ with least $I(\gamma)$ cost among all compatible pairs (T, γ) .

How nice is an optimal transport path?

Let $T \in \text{Path}(\mu^+, \mu^-)$ be any transport path with $\mathbf{M}_\alpha(\mathbf{T}) < +\infty$, not necessarily optimal.

Theorem. (*rectifiability*)(Xia, 2001) T is a real multiplicity 1-rectifiable current $T = \tau(M, \theta, \xi)$ with $\partial T = \mu^+ - \mu^-$. Moreover,

$$\mathbf{M}_\alpha(\mathbf{T}) = \int_{\mathbf{M}} \theta(\mathbf{x})^\alpha d\mathcal{H}^1(\mathbf{x})$$

Idea of proof: Follows from the rectifiable slicing theorem.

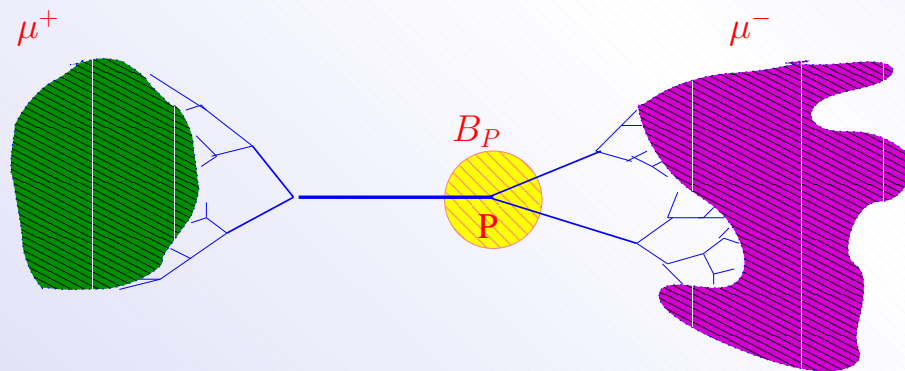
Now, assume that T is optimal. Let us see how nice T is.

Interior regularity: a local finiteness property (Xia, 2002)

Suppose one of μ^+ or μ^- is atomic. For any $p \in \text{spt}(T) \setminus \text{spt}(\partial T)$, there exists an open ball neighborhood B_p of p such that

$$T \lfloor B_p$$

is a cone at p consisting of finite union of segments with suitable multiplicities. These segments are balanced by a simple balance equation.



How about the boundary ?

Observation: The support of T may not necessarily be 1-dimensional nearby its boundary, which is the difference of the given two measures. This is because the boundary itself may even be **dense** in the space, as demonstrated by letting the initial measure to be the Lebesgue measure.

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But, how to read this information?



Boundary Regularity

To understand the boundary behavior, a suitable approach is to study the “**level sets**” of the rectifiable current $T = \tau(M, \theta, \xi)$ instead. For each $\lambda > 0$, let

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Theorem (Xia, 2003): Each level set of an optimal transport path is locally concentrated on a finite union of bilipschitz curves. These curves enjoy some nice properties similar to those satisfied by segments near an interior point.

Key Idea of Proof: Decomposition!

- For any optimal weighted directed graph $G \in Path(a, b)$, if $M^\alpha(a) + M^\alpha(b)$ is bounded above, then we can decompose a, b, G

$$a = a_P + a_R, b = b_P + b_R, G = P + R$$

so that $P \in Path(a_P, b_P), R \in Path(a_R, b_R)$, the total number of vertices and edges of P are uniformly bounded. The level set G_λ is contained in P . Edges of P are “nice”.

- Taking the limits to get the decomposition of optimal transport paths.

Advantage: Graphs are much easier to deal with. Just using combinatory.

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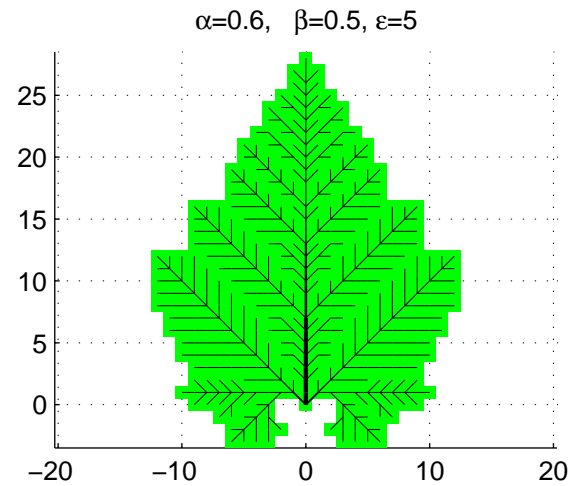
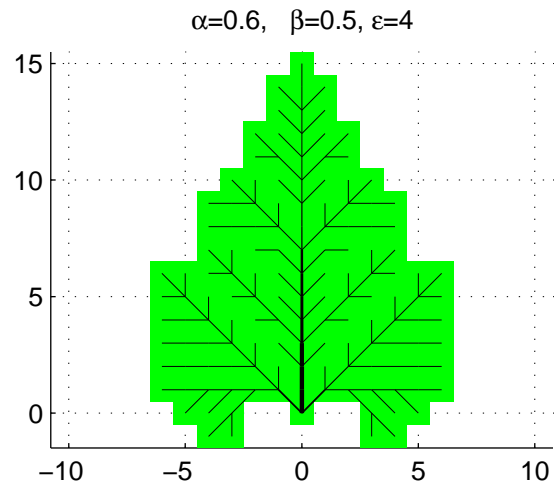
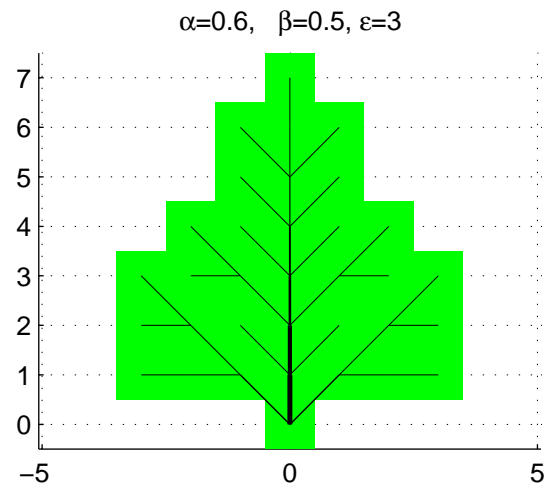
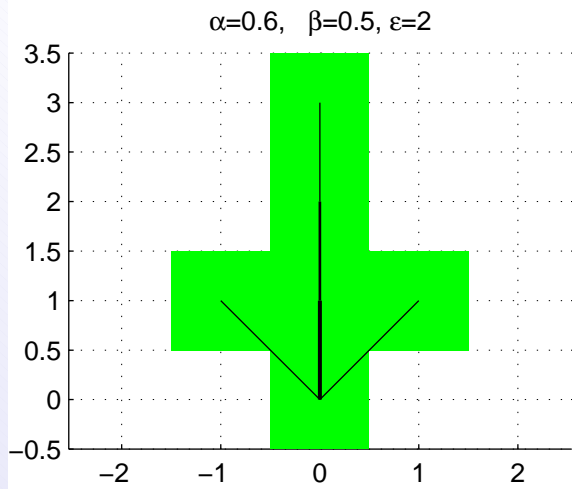
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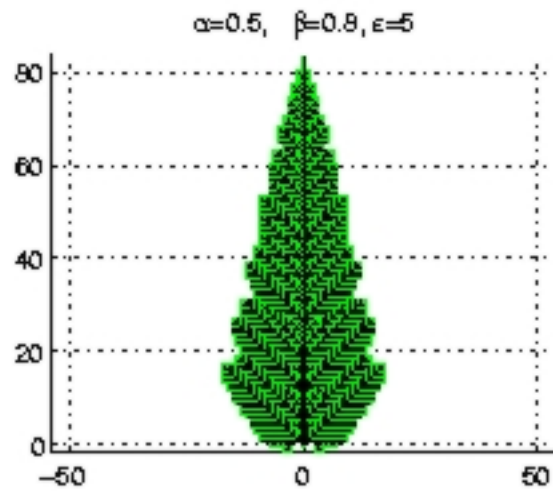
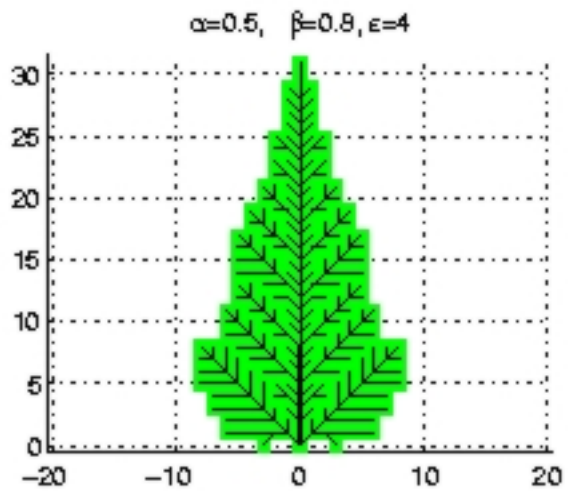
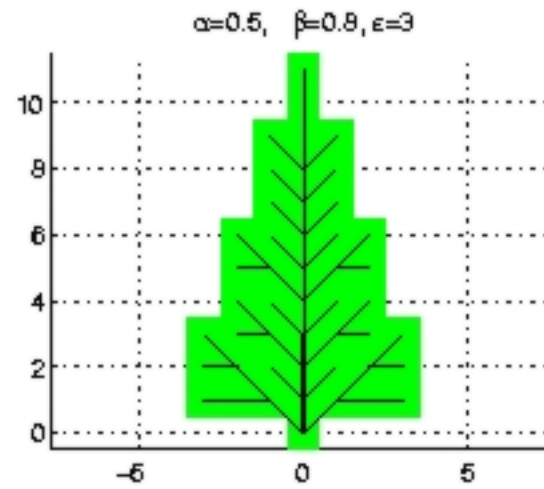
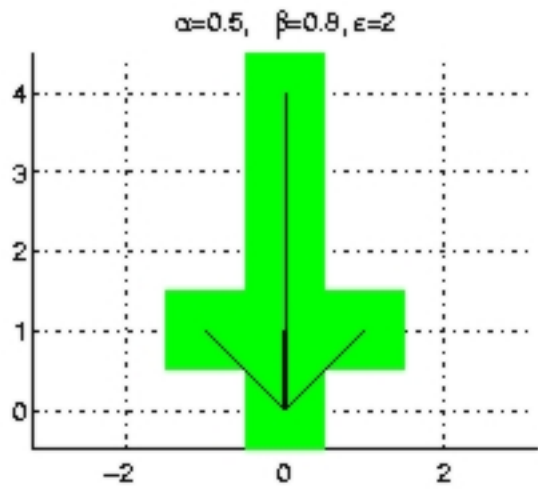
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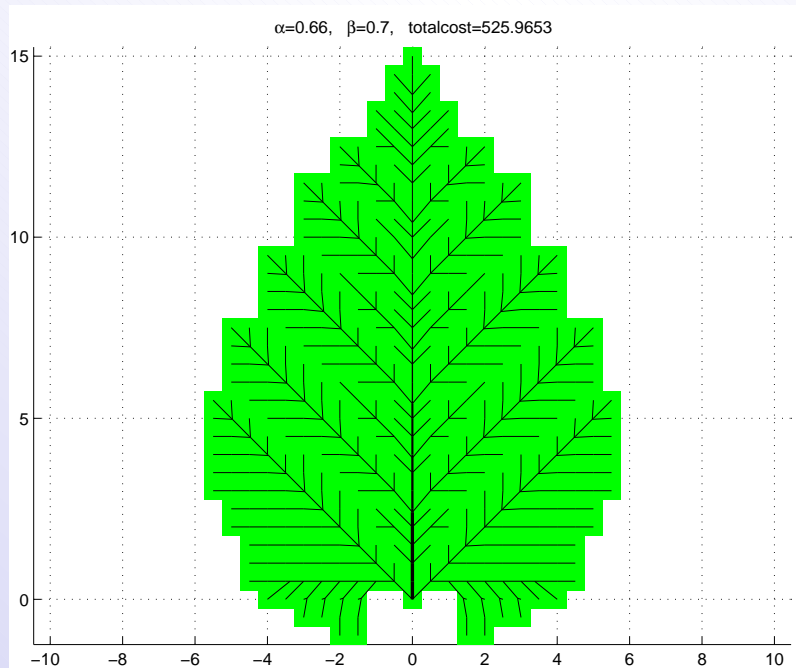
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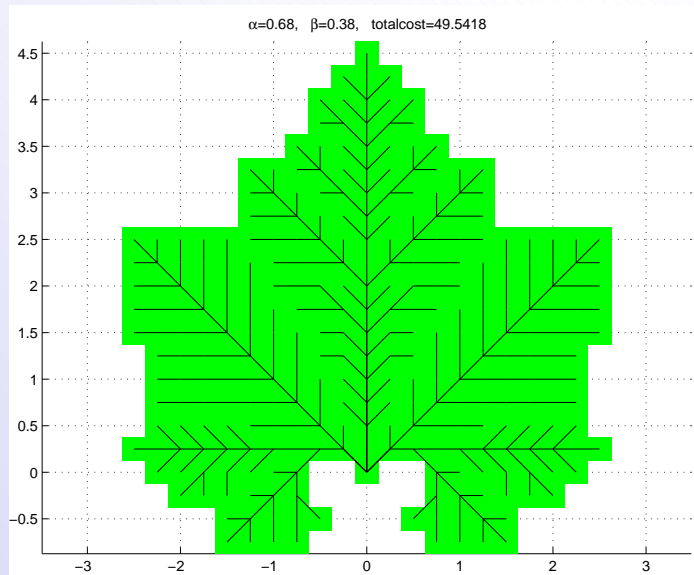
Feedback? A natural question: Can we use this idea to understand the dynamic formation of a tree leaf?

YES!! (Xia, 2004)





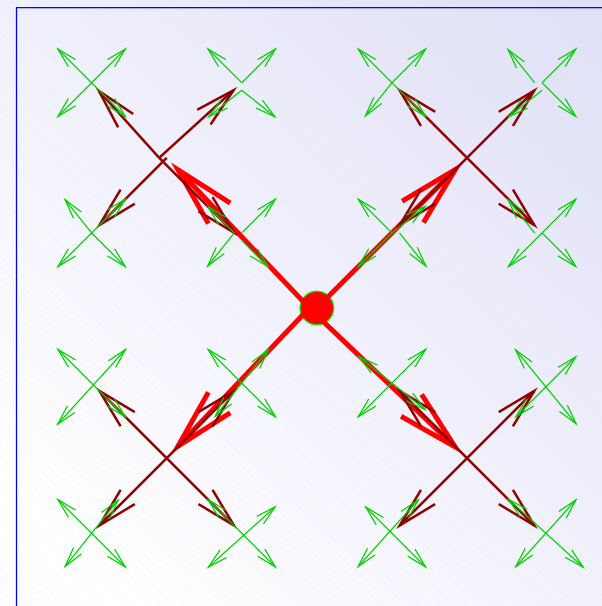




Question: Given a measure μ, ν , for which α , will we have $d_\alpha(\mu, \nu) < +\infty$?
 For simplicity, we choose $\nu = \text{Dirac mass}$.

Recall that if $\mu = \text{Lebesgue measure}$ and $\alpha > 1 - \frac{1}{m}$, then

$$\begin{aligned} & \sum_{n=1}^{\infty} \sum_{i=1}^{(2^n)^m} \left(\frac{1}{(2^n)^m} \right)^\alpha l_i \\ & \approx C \sum_{n=1}^{\infty} \sum_{i=1}^{(2^n)^m} \left(\frac{1}{(2^n)^m} \right)^\alpha \frac{1}{2^n} \\ & = C \sum_{n=1}^{\infty} \left(\frac{1}{(2^n)^m} \right)^\alpha 2^{n(m-1)} \\ & = C \sum_{n=1}^{\infty} \left(2^{m(1-\alpha)-1} \right)^n < +\infty \end{aligned}$$



Here, dimension $m = \inf_{\alpha < 1} \left\{ \frac{1}{1-\alpha} : d_\alpha(\mu, \delta_0) < +\infty \right\}$

Dimensional distance

For any $\mu, \nu \in P(X)$, let

$$D(\mu, \nu) = \inf_{\alpha < 1} \left\{ \frac{1}{1 - \alpha} : d_\alpha(\mu, \nu) < +\infty \right\}$$

Proposition. $(P(X), D)$ is a *pseudometric space*.

That is, D is a metric except that $D(\mu, \nu) = 0$ does not imply $\mu = \nu$.

e.g. $D(\delta_x, \delta_y) = 0$ for any $x, y \in X$ because $d_\alpha(\delta_x, \delta_y) = |x - y| < +\infty, \forall \alpha$.

Definition. For any μ and ν , we say $\mu \simeq \nu$ if $D(\mu, \nu) = 0$. That is, μ and ν are equivalent if and only if $d_\beta(\mu, \nu) < +\infty$ for any β . The equivalent class of μ is denoted by $[\mu]$.

Lemma. If $\mu_1 \simeq \mu_2$, then for any ν , $D(\mu_1, \nu) = D(\mu_2, \nu)$.

Thus, we may define

$$D([\mu], [\nu]) := D(\mu, \nu)$$

Dimensional Distance

Theorem. (Xia, 2007) D defines a metric on the equivalent classes of probability measures.

In general, we have

$$d_{Haus}(spt(\mu)) \leq D(\mu, \delta_0) \leq d_{box}(spt(\mu)).$$

Thus, when support of μ is nice enough, we get

$$\text{dimension of } spt(\mu) = \text{the distance } D(\mu, \delta_0).$$

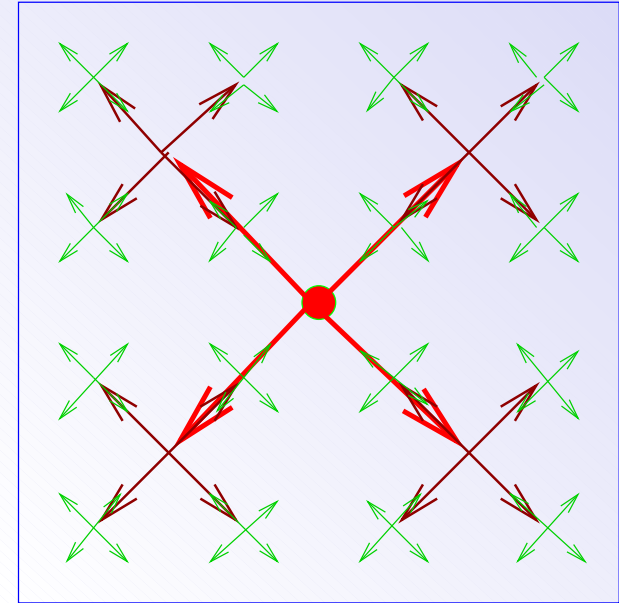
As a result, I call D **dimensional distance**.

Conclusion: **Dimension** of a set/measure is just the distance from it to a Dirac mass.

Example: μ = Lebesgue measure, ν = Dirac mass

If $\alpha > 1 - \frac{1}{m}$, i.e., $m > \frac{1}{1-\alpha}$ then

$$\begin{aligned} & \sum_{n=1}^{\infty} \sum_{i=1}^{(2^n)^m} \left(\frac{1}{(2^n)^m} \right)^\alpha l_i \\ & \approx C \sum_{n=1}^{\infty} \sum_{i=1}^{(2^n)^m} \left(\frac{1}{(2^n)^m} \right)^\alpha \frac{1}{2^n} \\ & = C \sum_{n=1}^{\infty} \left(\frac{1}{(2^n)^m} \right)^\alpha 2^{n(m-1)} \\ & = C \sum_{n=1}^{\infty} \left(2^{m(1-\alpha)-1} \right)^n < +\infty \end{aligned}$$



So, the **dimension** of $\mu = m = \inf_{\alpha < 1} \left\{ \frac{1}{1-\alpha} : d_\alpha(\mu, \delta_0) < +\infty \right\}$
 $= D(\mu, \nu)$, the **distance** from μ to δ_0

Example: μ = Cantor set, ν = Dirac mass

$$\begin{aligned} \sum_{n=1}^{\infty} 2^n \left(\frac{1}{2^n}\right)^\alpha \left(\frac{1}{3}\right)^n &= \sum_{n=1}^{\infty} \left(\frac{2^{1-\alpha}}{3}\right)^n < \infty \\ &\iff \frac{2^{1-\alpha}}{3} < 1 \\ &\iff 2^{1-\alpha} < 3 \\ &\iff \frac{1}{1-\alpha} > \frac{\ln 2}{\ln 3} \end{aligned}$$

Here again,

$$\begin{aligned} \text{the dimension of } \mu &= \frac{\ln 2}{\ln 3} = \inf_{\alpha < 1} \left\{ \frac{1}{1-\alpha} : d_\alpha(\mu, \delta_0) < +\infty \right\} \\ &= D(\mu, \nu), \text{ the distance from } \mu \text{ to } \delta_0 \end{aligned}$$

Note, here α is allowed to be **negative**.

Example: μ = Fat Cantor set, ν = Dirac mass

Examples: μ = Fat λ Cantor set (i.e. remove an interval of length λ from the middle of $[0, 1]$).

$$\begin{aligned} \sum_{n=1}^{\infty} 2^n \left(\frac{1}{2^n}\right)^\alpha \frac{1+\lambda}{4} \left(\frac{1-\lambda}{2}\right)^{n-1} &= \frac{1+\lambda}{2(1-\lambda)} \sum_{n=1}^{\infty} \left(2^{1-\alpha} p\right)^n < \infty \\ &\iff 2^{1-\alpha} p < 1 \\ &\iff 2^{1-\alpha} < \frac{1}{p} \\ &\iff \frac{1}{1-\alpha} > -\frac{\ln 2}{\ln p} = \frac{\ln 2}{\ln 2 - \ln(1-\lambda)} \end{aligned}$$

where $p = \frac{1-\lambda}{2}$.

Again, we have dimension of $\mu = \inf_{\alpha < 1} \left\{ \frac{1}{1-\alpha} : d_\alpha(\mu, \delta_0) < +\infty \right\}$

Example: μ = self-similar set, ν = Dirac mass

Example: A = finite union of A_i for $i = 1, \dots, k$. Each A_i is a σ -rescale of A .

$$\begin{aligned} \sum_{n=1}^{\infty} k^n \left(\frac{1}{k^n}\right)^{\alpha} \sigma^{n-1} L &= \frac{L}{\sigma} \sum_{n=1}^{\infty} \left(k^{1-\alpha} \sigma\right)^n < +\infty \\ &\iff k^{1-\alpha} \sigma < 1 \\ &\iff \frac{1}{1-\alpha} > \frac{\ln k}{\ln \sigma} \end{aligned}$$

Therefore, $D(\mu) = -\frac{\ln k}{\ln \sigma}$.

Here again, self-similar dimension of $\mu = \inf_{\alpha < 1} \left\{ \frac{1}{1-\alpha} : d_{\alpha}(\mu, \delta_0) < +\infty \right\}$

Thank You and Enjoy the Nature

