

Lecture 9: Basics of PDEs III

Note Title

★ The Potential Egn.

$$\left\{ \begin{array}{l} \Delta u = 0 \quad \text{in } \Omega \subset \mathbb{R}^d \text{ with some B.C.} \\ \rightarrow \text{Laplace's egn.} \\ \Delta u = f \quad \text{in } \Omega \subset \mathbb{R}^d \text{ with some B.C.} \\ \rightarrow \text{Poisson's egn.} \end{array} \right.$$

They show up as the **stationary** distribution (i.e., $t \rightarrow \infty$) of the corresponding heat egn. But \exists other numerous physical phenomena described by these egn's.

\Rightarrow See, e.g., **R.P. Feynman: Lectures on Physics**, vol. II, Chap. 12.

beautiful book!

Examples include: electrostatics; heat flow; stretched membrane; diffusion of neutrons; irrotational fluid flow; illumination of a plane by uniform light; Brownian motion (Kakutani; Hersh & Griego); ...

Feynman said: this happens because "it's the **underlying unity of nature**."

In particular, if "things" are reasonably smooth in space, distributed homogeneously and isotropically, then $\Delta u = 0$ or $\Delta u = f$ show up often!

These egn's also played significant role in my research on image compression and led to my patents in US & Japan! See, e.g., my papers whose title contain 'polyharmonic', 'PHLST', or 'PHLCT'.

Thm (Uniqueness)

Consider the heat eqn. with B.C. & I.C.

$$(*) \begin{cases} u_t = \frac{k}{\rho\sigma} \Delta u + \frac{1}{\rho\sigma} f(r, t) & \text{in } \Omega \\ \alpha u + \beta u_\nu = \phi(r, t) & \text{on } \partial\Omega \\ u(r, t_0) = \psi(r) & \text{in } \Omega \end{cases}$$

where $f \in C(\Omega \times [t_0, \infty))$, $\phi \in C(\partial\Omega \times [t_0, \infty))$, $\psi \in C(\Omega)$.

If $u(r, t) \in C^2(\bar{\Omega})$ in r and $\in C^1[t_0, \infty)$ in t , is a sol. of $(*)$, then it's unique.

(Proof) Consider another possible sol. of $(*)$, say $v(r, t)$, and the difference $\zeta(r, t) := u(r, t) - v(r, t)$.

Then, we have

$$(**) \begin{cases} \zeta_t = \frac{k}{\rho\sigma} \Delta \zeta & \text{in } \Omega \\ \alpha \zeta + \beta \zeta_\nu = 0 & \text{on } \partial\Omega \\ \zeta(r, t_0) = 0 & \text{in } \Omega \end{cases}$$

Since $\zeta \in C^1[t_0, \infty)$ in t variable,

$Z(t) := \iiint_{\Omega} \zeta^2 dV \geq 0$ is also in $C^1[t_0, \infty)$.

Note $Z(t_0) = 0$ since $\zeta(r, t_0) = 0$.

$$\text{Now, } Z'(t) = 2 \iiint_{\Omega} \zeta \zeta_t dV$$

$$\begin{aligned} Z''(t) &= 2 \iiint_{\Omega} (\zeta_t^2 + \zeta \zeta_{tt}) dV \\ &= \frac{k}{\rho\sigma} \Delta \zeta_t \text{ via } (**). \end{aligned}$$

So, $\iiint_{\Omega} \zeta \zeta_{tt} dV = \frac{k}{\rho\alpha} \iiint_{\Omega} \zeta \Delta \zeta_t dV$

Green's
2nd
Id.

$$= \frac{k}{\rho\alpha} \left[\iiint_{\Omega} \zeta_t \Delta \zeta dV + \iint_{\partial\Omega} \left(\zeta \frac{\partial \zeta_t}{\partial \nu} - \zeta_t \frac{\partial \zeta}{\partial \nu} \right) dS \right]$$

via (**) $\frac{\rho\alpha}{k} \zeta_t$ $-\frac{\alpha}{\beta} \zeta_t$ $-\frac{\alpha}{\beta} \zeta$

$= 0$

$$= \iiint_{\Omega} \zeta_t^2 dV$$

Hence, $Z''(t) = 4 \iiint_{\Omega} \zeta_t^2 dV$

Now, consider

$$Z \cdot Z'' - (Z')^2 = 4 \iiint_{\Omega} \zeta^2 dV \cdot \iiint_{\Omega} \zeta_t^2 dV - 4 \left(\iiint_{\Omega} \zeta \zeta_t dV \right)^2$$

$$= 4 \left\{ \underbrace{\|\zeta\|^2 \cdot \|\zeta_t\|^2 - |\langle \zeta, \zeta_t \rangle|^2}_{\geq 0} \right\}$$

by Cauchy-Schwarz!

So, $\begin{cases} Z \cdot Z'' - (Z')^2 \geq 0, \forall t \geq t_0 \text{ and} \\ Z(t_0) = 0, Z(t) \geq 0, \forall t \geq t_0. \end{cases}$

Now, we can see that $Z(t)$ is **logarithmically convex**, i.e., $(\log Z)'' = \frac{Z \cdot Z'' - (Z')^2}{Z^2} \geq 0$.

So, $Z(\theta t_0 + (1-\theta)t_1) \leq \underbrace{Z(t_0)}_{=0}^\theta Z(t_1)^{1-\theta}, \forall \theta \in [0,1], \forall t_1 \geq t_0$

But $Z(t) \geq 0$. Hence we must have

$Z(t) \equiv 0 \forall t \geq t_0$, i.e., $\zeta(r, t) \equiv 0$ in Ω & $\forall t \geq t_0$
 $\Rightarrow u(r, t)$ is a unique sol. ///

★ Well-Posed Problems (J. Hadamard, 1902)

— Consist of a PDE in a domain together with a set of I.C. and/or B.C. or some other auxiliary cond's that enjoy the following fundamental properties:

- (i) **Existence**: \exists at least one sol. satisfying all these cond's.
- (ii) **Uniqueness**: \exists at most one sol.
- (iii) **Stability**: The unique sol. depends in a stable manner on the data (= I.C./B.C.)
 \Leftrightarrow If data are changed a little, the corresponding sol. changes only a little.

Notice that if you impose too many auxiliary cond's, then there may not be any sol. (non-existence) while if there are too few aux. cond's, then there may be many sol's (non-uniqueness).

String, heat, potential eqn's with those I.C. & B.C. we considered are all well-posed.

Then what are examples of **ill-posed** problems?

Ex. 1 Consider the following potential eqn.:

$$(*) \begin{cases} \Delta u = 0 & \text{in } \Omega = \mathbb{H} = \text{the upper half-plane } \subset \mathbb{R}^2, \\ u|_{\partial\Omega} = 0 & \partial\Omega = \{y=0\} \end{cases}$$

Specifying $\frac{\partial u}{\partial \nu}|_{\partial\Omega}$ (i.e., overspecification) leads to ill-posedness !!

Why??

⇒ Consider $u_n(x, y) := \frac{1}{n} e^{-\sqrt{n}} \sin nx \sinh ny$, $n \in \mathbb{N}$.
 This fcn satisfies (*), but

$$\frac{\partial u_n}{\partial \nu}(x, 0) = -\frac{\partial u_n}{\partial y}(x, 0) = -e^{-\sqrt{n}} \sin nx \xrightarrow{n \rightarrow \infty} 0$$

But, $u_n(x, y) = \frac{1}{2} \sin nx \left(\frac{e^{ny-\sqrt{n}}}{n} - \frac{e^{-ny-\sqrt{n}}}{n} \right) \xrightarrow{n \rightarrow \infty} 0 \quad \forall y > 0$
 Similarly, $\frac{\partial u_n}{\partial \nu} = -e^{-\sqrt{n}} \sin nx \cosh ny \xrightarrow{n \rightarrow \infty} 0 \quad \forall y > 0$

⇒ Inconsistent with B.C. ⇒ ill-posed!

Ex. 2 Backward Heat Egn.

$$\begin{cases} u_t = u_{xx} & \text{in } \Omega = (0, \pi) \\ \text{I.C. : } u(x, 0) = f(x) & \text{in } \Omega \\ \text{B.C. : } u(0, t) = u(\pi, t) = 0 \end{cases}$$

⇒ of course, it's well-posed for $t \geq 0$.

But consider $u(x, t)$, $t < 0$, i.e., suppose we want to know the past temp. that could have led up to the concentration $f(x)$ at $t=0$, which is **antidiffusion**.

{ Diffusion ⇒ smoothing
 { Antidiffusion ⇒ **sharpening**, clearly unstable!

Yet, people have been developing algorithms (and tricks) to stabilize antidiffusion problems.

⇒ image enhancement, sharpening, deblurring!

See the reference page for more.