

Lecture #17 The Gradient

Under a change of coordinates a vector $u = u^i \partial_i$ obeys

$$u = u^i(x) \frac{\partial}{\partial x^i} = u'^j(x') \frac{\partial}{\partial x'^j} = u'^j(x') \underbrace{\frac{\partial x^i}{\partial x'^j}}_{\text{Jacobian}} \frac{\partial}{\partial x^i}$$

$$\Rightarrow u^i = \frac{\partial x^i}{\partial x'^j} u'^j$$

$$\Rightarrow \frac{\partial u^i}{\partial x^k} = \frac{\partial x'^l}{\partial x^k} \frac{\partial}{\partial x'^l} \left(\frac{\partial x^i}{\partial x'^j} u'^j \right)$$

$$= \underbrace{\frac{\partial x'^l}{\partial x^k} \frac{\partial x^i}{\partial x'^j} \frac{\partial u'^j}{\partial x'^l}}_{\text{TRANSFORMATION OF A (1)-TENSOR}} + \underbrace{\frac{\partial x'^l}{\partial x^k} \frac{\partial^2 x^i}{\partial x'^l \partial x'^j}}_{\text{NOT TENSOR}} u'^j$$

So modify

$$\nabla u = (\partial_i u^j + T^j_{ik} u^k)$$

Where

$$T_{jk}^i = \underbrace{\frac{\partial x^i}{\partial x'^l} \frac{\partial x'^m}{\partial x^j} \frac{\partial x'^n}{\partial x^k} T_{jk}^{l'm}}_{\substack{(1) - \text{TENSOR} \\ \text{TRANSFORMATION}}}$$

Note if $J = \left(\frac{\partial x}{\partial x'} \right)$ is the Jacobian and we call $T = (T_{jk}^i) = dx^i dx'^j T_{jk}^i$ then

$$\boxed{T = J^{-1} T J - J^{-1} dJ}$$

or even sweeter

$$T - d = J^{-1} (T - d) J$$

as an operator statement.

This is called the transformation of a $gl(n, M)$ -valued connection.

A (particular) solution for T is the Christoffel symbols

$$T_{jk}^i = \frac{1}{2} g^{il} (\partial_j g_{kl} + \partial_k g_{jl} - \partial_l g_{jk})$$

which are not the components of a $(2,1)$ -tensor
thanks to the partial derivatives of g .

We can add any $(2,1)$ -tensor to T and obtain
a solution for T transforming correctly
(homogeneous solution).

When $T = \Gamma$, we call ∇ the affine
connection, else we say that ∇ is torsionful.

Torsion can result in two evils

- * Failure of parallelograms to close
- * Failure of metric to be parallel.

Example: You have actually been using a torsion-free covariant derivative ∇_μ where $\nabla = dx^\mu \nabla_\mu$ for a long time without knowing it.

This is because in Cartesian coordinates $\Gamma_{ik}^j = 0$.

Even in polar coordinates this is no longer so:

$$(\mathbb{R}^2, ds^2 = dr^2 + r^2 d\theta^2)$$

$$dr^2 = dr g_{rr} dr + d\theta g_{\theta\theta} d\theta$$

$$\Rightarrow \begin{cases} g_{rr} = 1 \\ g_{\theta\theta} = r^2 \end{cases} \Rightarrow (g_{ij}) = \begin{pmatrix} 1 & 0 \\ 0 & r^2 \end{pmatrix} \Rightarrow (g^{ij}) = \begin{pmatrix} 1 & 0 \\ 0 & \frac{1}{r^2} \end{pmatrix}$$

Non-vanishing Christoffels:

$$\Rightarrow 2\Gamma_{r\theta\theta} = 2\partial_\theta g_{r\theta} - \partial_r g_{\theta\theta} = -2r \Rightarrow \Gamma_{\theta\theta}^r = -r$$

$$2\Gamma_{\theta r\theta} = \partial_r g_{\theta\theta} + \partial_\theta g_{r\theta} - \partial_\theta g_{\theta r} = \partial_r r^2 = 2r \Rightarrow \Gamma_{r\theta}^\theta = \frac{1}{r}$$

Lets compute the Laplacian, consider a function f .

Then $\nabla f \equiv df$ is a 1-form $\Rightarrow g^{-1}(\nabla f, \cdot)$ is a vector.

$$\begin{aligned} \text{Explicitly } g^{-1}(\nabla f, \cdot) &= \left(\frac{\partial}{\partial r} \otimes \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial \theta} \otimes \frac{\partial}{\partial \theta} \right) \left(\frac{\partial f}{\partial r} dr + \frac{\partial f}{\partial \theta} d\theta \right) \\ &= \frac{\partial f}{\partial r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial f}{\partial \theta} \frac{\partial}{\partial \theta} \quad \underline{\text{A VECTOR}} \end{aligned}$$

Now $\nabla : \text{vectors} \mapsto (1)$ -tensors

But there is a canonical method to produce a scalar from a (1) -tensor called trace

$$T_j^i dx^j \otimes \frac{\partial}{\partial x^i} \xrightarrow{\text{trace}} T_j^i \langle dx^j, \frac{\partial}{\partial x^i} \rangle = T_i^i$$

For a general vector u , $\text{trace}(\nabla u) \equiv \text{div}(u) = \nabla_i u^i$

We call $\text{div}(g^{-1}(\nabla f, \cdot)) = \Delta f = \nabla_i \nabla^i f$ the Laplacian of f .

$$\begin{aligned} \text{Here } \text{div}(u) &= \nabla_r u^r + \nabla_\theta u^\theta \\ &= \partial_r u^r + \cancel{\Gamma_{rk}^r} u^k + \partial_\theta u^\theta + \Gamma_{\theta r}^\theta u^r \\ &= \partial_r u^r + \partial_\theta u^\theta + \frac{1}{r} u^r \end{aligned}$$

But putting $(u^r, u^\theta) = (\partial_r f, \frac{1}{r^2} \partial_\theta f)$ gives

$$\Delta f = \partial_r^2 f + \frac{1}{r^2} \partial_\theta^2 f + \frac{1}{r} \partial_r f$$

$$= \frac{1}{r} \partial_r (r \partial_r f) + \frac{1}{r^2} \partial_\theta^2 f \quad \text{The standard Laplacian in Polar coordinates}$$

Note that $\Delta f = \text{div}(g^{-1}(\nabla f, \cdot))$ generalizes to any tensor and is called the Bochner Laplacian.

LINEAR CONNEXION / GRADIENT

$$\nabla: \Gamma(T^p_{\frac{1}{2}} M) \longrightarrow \Gamma(T^p_{\frac{1}{2}+1} M)$$

$$\begin{array}{ccc} \psi & & \psi \\ T & \longrightarrow & \nabla T \end{array}$$

such that

$$(i) \quad \nabla(T+S) = \nabla T + \nabla S$$

$$(ii) \quad \nabla(fT) = df \otimes T + f \nabla T \quad f: M \rightarrow \mathbb{R}$$

$$(iii) \quad \nabla(T \otimes S) = \nabla T \otimes S + T \otimes \nabla S$$

$$(iv) \quad \nabla \langle \omega, \omega \rangle = \langle \nabla_\nu \omega, \omega \rangle + \langle \omega, \nabla_\nu \omega \rangle$$

If $\{e_a\}$, $\{\theta^b\}$ are dual, but not necessarily orthonormal bases

$$\boxed{\nabla e_a \equiv \gamma_{ab}^c \theta^b \otimes e_c}$$

where the functions γ_{hi}^l are called connection coefficients.

* When $e_a = \frac{\partial}{\partial x^a}$, coordinate vector fields, and ∇ is torsion free, $\gamma_{ab}^c = \Gamma_{ab}^c$, the Christoffel symbols.

* γ_{hi}^l are NOT tensor components.