

Lecture #6

Diffeomorphisms

Theorem If $\varphi: M \rightarrow N$ is a local diffeomorphism at P , then

$$d\varphi: T_P M \rightarrow T_{\varphi(P)} N$$

is a vector space isomorphism.

Conversely, if $d\varphi: T_P M \rightarrow T_{\varphi(P)} N$ is an isomorphism

for some differentiable map at P , then φ is a local diffeomorphism at P .

For the converse apply the inverse function theorem to the differentiable map

$$\tilde{\varphi}: \mathbb{R}^n \rightarrow \mathbb{R}^n \text{ via } \tilde{\varphi} = \varphi_P \circ \varphi \circ \varphi_P^{-1}$$

where $(U_\alpha, \varphi_\alpha) \in (V_\beta, \psi_\beta)$ are charts at $P, \varphi(P)$

and use the fact that the Jacobian is the matrix of the map $d\varphi$ in the coordinate basis.

For the forward direction, $d\varphi^{-1}$ is easily checked to be the required inverse $\square$

The tangent bundle is a manifold

Let $TM = \{(P, v_P) : P \in M, v_P \in T_P M\}$

We call TM the tangent bundle. To see

that TM is a manifold we need to build

an atlas. Start with an atlas $\{(U_\alpha, \varphi_\alpha = (x^1, \dots, x^n))\}$

for M . At each $P \in M$, $T_P M$ has a basis $\{\frac{\partial}{\partial x^i} \big|_P\}$.

Take as chart map

$$\psi_\alpha = (P, v_P = v^i \frac{\partial}{\partial x^i} \big|_P) \mapsto (x^1, \dots, x^n; v^1, \dots, v^n)$$

$$V_\alpha = \{(P, v_P) : P \in U_\alpha, v_P \in T_P M\} \quad \cap \quad \mathbb{R}^{2n}$$

From chart to chart $v_\alpha^i = \frac{\partial x_\beta^i}{\partial x_\alpha^j} v_\beta^j$ is a linear transformation.

Clearly differentiable.

The Jacobian of a diffeomorphism $\mathbb{R}^n \rightarrow \mathbb{R}^n$

VECTOR FIELDS

"Sections of the tangent bundle".

A vector field is a map

$$\begin{array}{ccc} X: M & \longrightarrow & TM \\ \downarrow \omega & & \downarrow \omega \\ P & \longmapsto & (P, v_P) \end{array}$$

and say X is differentiable if it is differentiable as a map b/w manifolds.

In a chart $\varphi^{-1} = (x^1, \dots, x^n)$

$$X(P) = X^i(P) \frac{\partial}{\partial x^i} \Big|_P$$

and differentiability of X requires differentiability of the component functions

$$P \longmapsto X^i(P)$$

Notice that a vector field defines a mapping

$$\begin{array}{ccc} X: \mathcal{D} & \longrightarrow & \mathcal{F} \\ \downarrow & & \downarrow \\ \text{differentiable} & & \text{functions} \\ \text{functions on } M & & \text{on } M \end{array} \quad \text{via } (Xf)(P) = X^i(P) \frac{\partial f}{\partial x^i}(P) = (X(f))(P)$$

the directional derivative of f in the direction of X at P .

Suppose X, Y are differentiable vector fields

and $f: M \rightarrow \mathbb{R}$ is C^∞ then $X(f)$ and $Y(f)$

are both differentiable functions. Hence

we may consider $X(Y(f))$.

Calculate in a chart

$$\begin{aligned}
 X(Y(f)) &= X\left(Y^i \frac{\partial f}{\partial x^i}\right) \\
 &= X^j \frac{\partial}{\partial x^j} \left(Y^i \frac{\partial f}{\partial x^i}\right) \quad (\text{should put a bar over the } Y^i) \\
 &= X^j Y^i \frac{\partial^2 f}{\partial x^j \partial x^i} + X^j \frac{\partial Y^i}{\partial x^j} \frac{\partial f}{\partial x^i}
 \end{aligned}$$

$\xrightarrow{\text{not a vector field}}$
 $\nwarrow$ Acts like a vector field

$$\begin{aligned}
 \Rightarrow (XY - YX)(f) &\equiv [X, Y](f) \\
 &= \left(X^j \frac{\partial Y^i}{\partial x^j} - Y^j \frac{\partial X^i}{\partial x^j}\right) \frac{\partial f}{\partial x^i}
 \end{aligned}$$

$\equiv$ a vector field. The vector field $[X, Y]$ is called the (Lie) bracket of X and Y .
 It is differentiable when X & Y are.

Properties of $[\cdot, \cdot]: \Lambda^2 \mathcal{X}(M) \longrightarrow \mathcal{X}(M)$

- (i) $[X, Y] = -[Y, X]$ antisymmetry
- (ii) $[aX + bY, Z] = a[X, Z] + b[Y, Z]$ Linear
- (iii) $[[X, Y], Z] + \text{cyclic} = 0$ Jacobi
- (iv) $[fX, gY] = fg[X, Y] + fX(g)Y - gY(f)X$
Leibniz

Given a vector field X



we can search for integral curves such
 that for any $p \in \mathcal{X}$, $v_p = \gamma'(t_p)$ where $\gamma(t_p) = p$

To solve this problem we must study a system of ODE: In coordinates x^i

$$X = X^i \frac{\partial}{\partial x^i} \quad \text{and} \quad x^i(t) = (\varphi_x \circ \gamma)^i(t)$$

so components are

$$X^i(\gamma(t)) = \frac{dx^i(t)}{dt}$$

with some initial condition, the start of the integral curve $x^i(0) = \varphi_x^i(p)$.

Small time existence of solutions to the system $X^i(x) = \dot{x}^i$ is guaranteed by Picard's theorem.

The curves $\gamma_t(p)$ allow us to define a Lie derivative $(\mathcal{L}_X f)(p) = \lim_{t \rightarrow 0} \frac{f(\gamma_t(p)) - f(p)}{t}$

Exercises ① Find out what it means for a manifold to be orientable.

Give examples of an orientable and a non-orientable differentiable structure.

② Check the properties of the Lie bracket.

