

Surface IntegralsDefn

- Let S be surface parametrized by $\vec{r}(u,v): \mathbb{R}^2 \rightarrow \mathbb{R}^3$, (Refer to previous handout) where $\vec{r}$ maps R to S .
- Let $f(P)$ be function defined on S
- Let $S_1, S_2, \dots, S_n$ be subdivision of S w/ corresponding surface areas $\Delta\sigma_1, \Delta\sigma_2, \dots, \Delta\sigma_n$.
- Let $P_i = (x_i, y_i, z_i)$ be arbitrary pt. in $S_i \quad \forall i=1, \dots, n$
- Let mesh be $\Delta\sigma_i = \max_{1 \leq i \leq n} \{\Delta\sigma_i\}$

Then the surface integral of f over surface S is

$$\iint_S f(x,y,z) d\sigma := \lim_{\Delta\sigma \rightarrow 0} \sum_{i=1}^n f(x_i, y_i, z_i) \Delta\sigma_i$$

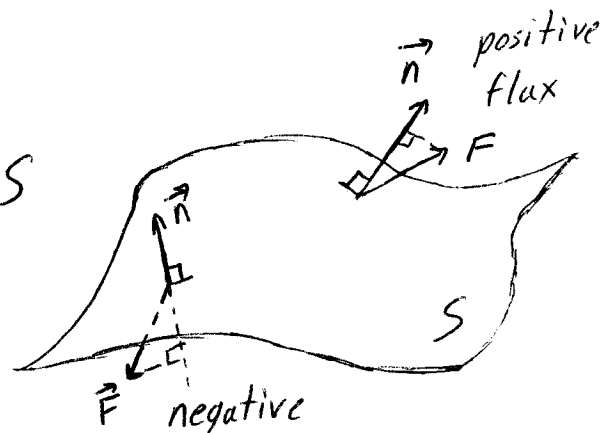
Method of Evaluation

$$\iint_S f(x,y,z) d\sigma = \iint_R f(x,y,z) |\vec{r}_u \times \vec{r}_v| dA = \iint_R f(\vec{r}(u,v)) |\vec{r}_u \times \vec{r}_v| dA$$

Note: For implicit functions, you must use the 'implicit function exchange rate' instead of $|\vec{r}_u \times \vec{r}_v|$ (Refer to previous handout)

Defn The flux of vector field $\vec{F} = M\vec{i} + N\vec{j} + P\vec{k}$ across surface S in the direction $\vec{n}$ (This vector is a chosen unit normal vector) is

$$\text{Flux} = \iint_S \vec{F} \cdot \vec{n} dS$$



Note: If $S: F(x,y,z)=C$ (ie. implicit function) flux

$$\Rightarrow \vec{n} = \frac{\vec{\nabla} F}{|\vec{\nabla} F|} \text{ (this } F \text{ is different from } \vec{F} \text{ a v-field)}$$

Applications of Surface Integrals

Let $\delta(P) = \delta(x, y, z)$ be density ($\frac{\text{mass}}{\text{area}}$ units) defined on S

1) Surface Area = $SA := \iint_S 1 d\sigma$

2) Mass = $M := \iint_S \delta(P) d\sigma$

3) 1st Moments about Arbitrary Planes

- About plane $x = \bar{x}$: $M_{x=\bar{x}} = \iint_S (x - \bar{x}) \delta(P) d\sigma$
- About plane $y = \bar{y}$: $M_{y=\bar{y}} = \iint_S (y - \bar{y}) \delta(P) d\sigma$
- About plane $z = \bar{z}$: $M_{z=\bar{z}} = \iint_S (z - \bar{z}) \delta(P) d\sigma$

4) 1st Moments about Coordinate Planes

$$M_{yz} = \iint_S x \delta(P) d\sigma, \quad M_{xz} = \iint_S y \delta(P) d\sigma, \quad M_{xy} = \iint_S z \delta(P) d\sigma$$

Note: $M_{yz} = M_{x=0}$, $M_{xz} = M_{y=0}$, $M_{xy} = M_{z=0}$

5) Center of Mass $(\bar{x}, \bar{y}, \bar{z})$

$$\bar{x} = \frac{M_{yz}}{M}, \quad \bar{y} = \frac{M_{xz}}{M}, \quad \bar{z} = \frac{M_{xy}}{M}$$

6) Centroid $(\bar{x}, \bar{y}, \bar{z})$

$$\bar{x} = \frac{\iint_S x d\sigma}{\text{Area}}, \quad \bar{y} = \frac{\iint_S y d\sigma}{\text{Area}}, \quad \bar{z} = \frac{\iint_S z d\sigma}{\text{Area}}$$

7) Moments of Inertia (2nd Moments)

- About line L or pt. P_0 : $I = \iint_S r^2 \delta(P) d\sigma$
w/ $r := r(x, y, z)$ is distance from line L or pt. P_0
- About x -axis: $I_x = \iint_S (y^2 + z^2) \delta(P) d\sigma$
- About y -axis: $I_y = \iint_S (x^2 + z^2) \delta(P) d\sigma$
- About z -axis: $I_z = \iint_S (x^2 + y^2) \delta(P) d\sigma$