

Path Independence & Conservative Vector Fields

Defn Let $\vec{F}$ be a vector field defined on region D & let A & B be any two points in D . If

$$\int_{C_1} \vec{F} \cdot \vec{T} ds = \int_{C_2} \vec{F} \cdot \vec{T} ds$$

for any two paths C_1 & C_2 from point A to point B , then we call $\vec{F}$ a conservative vector field. We also call $\int_C \vec{F} \cdot \vec{T} ds$ path independent in D for all curves C that trace a path from A to B .

Defn If $\vec{F}$ is a vector field & there exists a scalar function f such that $\vec{F}$ is gradient field of f (i.e. $\vec{F} = \nabla f$) $\Rightarrow$ f is called a potential function of $\vec{F}$.

Fundamental Theorem for Line Integrals

Let $f(x, y, z)$ be a scalar function & let $\vec{\nabla} f = f_x \vec{i} + f_y \vec{j} + f_z \vec{k}$ be its gradient field defined on path $C: \vec{r}(t) = g(t)\vec{i} + h(t)\vec{j} + k(t)\vec{k}$ for $a \leq t \leq b$.

Let $A = \vec{r}(a)$ & $B = \vec{r}(b)$

$$\Rightarrow \int_C \vec{\nabla} f \cdot \vec{T} ds = f(\vec{r}(t)) \Big|_a^b = f(B) - f(A)$$

$$\text{or } \int_C \vec{F} \cdot d\vec{r} = \int_C \vec{\nabla} f \cdot d\vec{r} = f(B) - f(A)$$

Thm 1 Let $\vec{F}$ be vector field defined on region D .
 $\vec{F}$ is conservative iff $\vec{F}$ is a gradient field of some function f (i.e. $\vec{F} = \nabla f$).

Thm 2 A vector field $\vec{F}$ is conservative iff
 $\oint_C \vec{F} \cdot \vec{T} ds = 0$ for every closed curve C .

Note: Combining Thm 1 & Thm 2, we have the following equivalencies:

$$\begin{aligned} \vec{F} = \nabla f \text{ on } D & \quad (\Leftrightarrow) \quad \vec{F} \text{ conservative on } D & \quad (\Leftrightarrow) \quad \oint_C \vec{F} \cdot \vec{T} ds = 0 \\ \text{(There exists potential} & & \quad \forall \text{ closed curves} \\ \text{function of } \vec{F}) & & \quad C \text{ in } D \end{aligned}$$

Component Test for Conservative Fields

Let $\vec{F}(x, y, z) = M(x, y, z)\vec{i} + N(x, y, z)\vec{j} + P(x, y, z)\vec{k}$ be a vector field $\Rightarrow \vec{F}$ is conservative iff

$$P_y = N_z, \quad M_z = P_x, \quad \& \quad N_x = M_y$$