

## MAT 239: PROBLEM SET 2

DUE TO FRIDAY OCT 11 2024

ABSTRACT. This problem set corresponds to the second week of the course MAT-239 Fall 2024. It is due Friday Oct 11 at 23:59h submitted via Gradescope. Each problem worth 25 points, for a total of 100 points.

**Task:** Solve the *four* problems below and submit it through Gradescope by Friday Oct 11 at 10am. Be rigorous and precise in writing your solutions.

**Problem 1.** (42 points) For each of the smooth manifolds  $X \subseteq \mathbb{R}^N$  and points  $x \in X$ , compute the tangent space  $T_x X$  as a linear subspace of  $\mathbb{R}^N$ .

(1)  $X = S^2 := \{x \in \mathbb{R}^3 : |x| = 1\} \subseteq \mathbb{R}^3$  at the points:  $(1, 0, 0)$ ,  $(0, 1, 0)$ ,  $\frac{1}{\sqrt{3}}(1, 1, 1)$ .

(2)  $X = T^2 := (S^1)^2 \subseteq \mathbb{R}^4$  at the points:  $(1, 0; 1, 0)$ ,  $(0, 1; \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$ .

(3)  $X = im(f) \subseteq \mathbb{R}^3$  where  $f : \mathbb{R} \rightarrow \mathbb{R}^3$  is given by

$$f(t) = (t^3 - 3t, t^4 - 4t^2, t^5 - 10t)$$

at the points  $(0, 0, 0)$ ,  $(-2, -3, -9) \in X$ .

(4) The genus 2 surface  $X = \{(x, y, z) \in \mathbb{R}^3 : ((x^2 + y^2)^2 - x^2 + y^2)^2 + z^2 = 0.02\} \subseteq \mathbb{R}^3$  at the point  $(0, 0, 1/5\sqrt{2}) \in X$ .

(5)  $X = \{A \in M_n(\mathbb{R}) : \det(A) \neq 0\} \subseteq \mathbb{R}^{n^2}$  at the point  $A = I$ , where  $I$  denotes the identity matrix and we have identified  $M_n(\mathbb{R}) \cong \mathbb{R}^{n^2}$  via the standard entries of an  $(n \times n)$  matrix.

(6)  $X = \{A \in M_n(\mathbb{R}) : \det(A) = 1\} \subseteq \mathbb{R}^{n^2}$  at the points  $A = I$  and  $A = -I$ .<sup>1</sup>

(7) (Optional)  $X = \{A \in M_n(\mathbb{R}) : AA^t = I\} \subseteq \mathbb{R}^{n^2}$  at the point  $A = I$ .

**Problem 2.** (20 points) Solve the following parts:

(1) Prove that the map  $\exp : \mathbb{R} \rightarrow S^1$  given by  $x \mapsto \exp(ix)$  is a local diffeomorphism but not a global diffeomorphism.

(Here we have identified  $S^1 = \{z \in \mathbb{C} : |z| = 1\}$ .)

(2) Find all the points  $(x, y) \in \mathbb{R}^2$  such that the map

$$f(x, y) = (x^3 + yx, y)$$

is *not* a local diffeomorphism.

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<sup>1</sup>In Problem 4 below we will see that  $X$  is a smooth manifold: you may assume this for now.

(3) Consider the map

$$f_k : \mathbb{C} \longrightarrow \mathbb{C}, \quad z \mapsto z^k.$$

Show that, as a smooth map from  $\mathbb{R}^2 \cong \mathbb{C}$  to  $\mathbb{R}^2 \cong \mathbb{C}$ ,  $f_k$  is a local diffeomorphism everywhere except for the origin.

(4) Consider  $X_k = \{(z, w) \in \mathbb{C}^2 : w^k + z^2 = 1\} \subseteq \mathbb{C}^2$  and the map

$$f : X_k \longrightarrow \mathbb{C}, \quad (z, w) \mapsto w.$$

Find all the points in  $X_k$  such that  $f$  is *not* a local diffeomorphism.

**Problem 3.** (18 points) Let  $\mathfrak{so}(3) := \{V \in M_3(\mathbb{R}) : V + V^t = 0\} \subseteq \mathbb{R}^6$  be the set of skew-symmetric and  $SO(3) := \{A \in M_3(\mathbb{R}) : AA^t = I\} \subseteq \mathbb{R}^6$  the set of orthogonal matrices. Consider the map

$$\exp : \mathfrak{so}(3) \longrightarrow SO(3), \quad V \mapsto \exp(V).$$

- (1) Show that  $\exp$  is well-defined, i.e. that its target is indeed  $SO(3)$ .
- (2) Show that  $\exp : \mathfrak{so}(3) \longrightarrow SO(3)$  is a local diffeomorphism at the origin  $V = 0 \in \mathbb{R}^6$ , i.e. at the zero matrix.
- (3) Find a local chart centered at any matrix  $A \in SO(3)$  by using (2).

**Problem 4.** (20 points) For this problem you can use the *regular value theorem*.<sup>2</sup>:

- (a) Show (again!) that  $S^n \subseteq \mathbb{R}^{n+1}$  is a smooth submanifold.
- (b) Find all the values  $a \in \mathbb{R}$  such that  $X = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 - z^2 = a\}$  is a smooth submanifold.
- (c) Show that  $X = \{A \in M_n(\mathbb{R}) : \det(A) = 1\} \subseteq \mathbb{R}^{n^2}$  is a smooth submanifold.
- (d) Show that  $X = \{A \in M_n(\mathbb{R}) : AA^t = I\} \subseteq \mathbb{R}^{n^2}$  is a smooth submanifold.

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<sup>2</sup>We will cover it on Monday as a consequence of the Inverse Function Theorem.