

Applications of $A = SDS^{-1}$

$f: V \xrightarrow{\text{linear}} V$, $A_f = \text{any matrix representation of } f \text{ for a basis } \{v_1, v_2\}$

If eigenvalues of f are different, $\exists D$ diagonal, $\exists S$ invertible \rightsquigarrow eigenvalue $\{f(v_i)\}$

(same as those of A_f)

$$S \begin{pmatrix} \lambda_1 & \\ & \lambda_n \end{pmatrix}$$

s.t. $A = SDS^{-1}$

How can we use $A = SDS^{-1}$

① We want $\det(A)$: we know $\det(XY) = \det(X)\det(Y)$

If $A = SDS^{-1}$, then $\det(A) = \det(S)\det(D)\det(S^{-1})$

$$= \det(S)\det(D) \frac{1}{\det(S)}$$

$$\boxed{\det(A) = \det(D) = \lambda_1 \cdots \lambda_n}$$

product of all eigenvalues

② Taking powers of A : compute $A, A^2, A^3, \dots, A^{2024}, \dots, A^{10^{100}}$

Ex. $\begin{pmatrix} 2 & 2 \\ 5 & -1 \end{pmatrix} = A$, what is $A^3 = A \cdot A \cdot A$

$$= A^2 \cdot A = \begin{pmatrix} 2 & 2 \\ 5 & -1 \end{pmatrix} \begin{pmatrix} 2 & 2 \\ 5 & -1 \end{pmatrix} \cdot \begin{pmatrix} 2 & 2 \\ 5 & -1 \end{pmatrix}$$

$$= \begin{pmatrix} 14 & 2 \\ 5 & 1 \end{pmatrix} \begin{pmatrix} 2 & 2 \\ 5 & -1 \end{pmatrix}$$

$$= \begin{pmatrix} 32 & 26 \\ 65 & -1 \end{pmatrix} \rightsquigarrow \text{complicated}$$

If we use $A = SDS^{-1}$, what is A^3 ?

It is $A^3 = A \cdot A \cdot A = (SDS^{-1})(SDS^{-1})(SDS^{-1}) = SD^3S^{-1}$

Lemma 1: $A^n = SD^nS^{-1}$, note that $D^n = \begin{pmatrix} \lambda_1^n & \\ & \lambda_n^n \end{pmatrix}$

$$\text{Ex. } \begin{pmatrix} 2 & 2 \\ 5 & -1 \end{pmatrix}^3 = \begin{pmatrix} 2 & 1 \\ -3 & 0 \end{pmatrix} \begin{pmatrix} -3 & 0 \\ 0 & 4 \end{pmatrix}^3 \cdot \frac{1}{7} \begin{pmatrix} 1 & -1 \\ 5 & 2 \end{pmatrix}$$

$$= \begin{pmatrix} 2 & 1 \\ -3 & 0 \end{pmatrix} \begin{pmatrix} (-3)^3 & 0 \\ 0 & 4^3 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 5 & 2 \end{pmatrix}$$

$$= \begin{pmatrix} 2(-3)^3 & 0 \\ -5(3)^3 & 4^3 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 5 & 2 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{2}{7}(-3)^3 + 5/7(4)^3 & -2/7(-3)^3 + 3/7(4)^3 \\ -5/7(3)^3 + 5/7(4)^3 & 5/7(3)^3 + 3/7(4)^3 \end{pmatrix} \rightarrow \text{easy to compute}$$

③ Computing $\exp(A) = e^A$: recall, if $x \in \mathbb{R}$, then $e^x := \sum_{n=0}^{\infty} \frac{1}{n!} x^n = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \dots$

($n \times n$)

For a matrix A , define $e^A := \underbrace{Id}_{\text{matrix } X} + A + \frac{A^2}{2!} + \frac{A^3}{3!} + \frac{A^4}{4!} + \dots$

Lemma 2:

$\boxed{\text{If } A = SDS^{-1}, \text{ then } e^A = S \cdot e^D \cdot S^{-1}}$

Proof:

$$e^A = e^{SDS^{-1}} \stackrel{*}{=} Id + SDS^{-1} + \frac{(SDS^{-1})^2}{2!} + \frac{(SDS^{-1})^3}{3!} + \dots$$

$$\stackrel{\text{Lemma 1}}{=} Id + SDS^{-1} + \frac{SD^2S^{-1}}{2!} + \frac{SD^3S^{-1}}{3!} + \dots$$

$$= S(Id + D + \frac{D^2}{2!} + \frac{D^3}{3!} + \dots)S^{-1}$$

$$= Se^DS^{-1}$$

Application of computing exp of a matrix,

Ex. (22B week 1) $x(t)$, $x: \mathbb{R} \rightarrow \mathbb{R}$, we do not know $x(t)$, but we know something about $x'(t)$.

Eg. $x'(t) = 3x$, then $3t + c = x(t)$

$$x'(t) = 3x(t) \rightsquigarrow x(t) = e^{3t} \cdot c$$

In several

variables: $A \cdot \begin{pmatrix} x_1(t) \\ x_2(t) \\ \vdots \\ x_n(t) \end{pmatrix} = \begin{pmatrix} x'_1(t) \\ x'_2(t) \\ \vdots \\ x'_n(t) \end{pmatrix} \Leftrightarrow \begin{pmatrix} a_{11}x_1(t) + \dots + a_{1n}x_n(t) & x'_1(t) \\ a_{21}x_1(t) + \dots + a_{2n}x_n(t) & x'_2(t) \\ \vdots & \vdots \\ a_{n1}x_1(t) + \dots + a_{nn}x_n(t) & x'_n(t) \end{pmatrix}$

$$A \cdot x(t) = \vec{x}(t) \quad \therefore \boxed{\text{Sol: } \vec{x} = e^{At}}$$

④ Physical meaning of λ_i in quantum mechanics → vector spaces are ∞ -dim

In the basic setting, you have Schrödinger's eqn (analogy of $F=ma$)

$$\partial_t \psi(x, t) = \hat{H} \psi(x, t), \text{ where } H = KE + PE \quad \text{and} \quad \hat{H}(x, t) = \frac{\partial^2}{\partial x^2} + V(x) \quad \leftarrow \text{linear maps}$$

$\downarrow x = p$

Eigenvalues

→ probability for a certain eigenstate