

4-manifolds

Thursday, May 7, 2020 2:00 PM

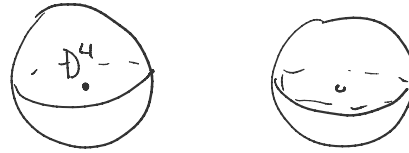
Handles: 4-dimensional K-handle $D^K \times D^{4-K}$

attached along $\partial D^K \times D^{4-K}$
 $S^{K-1} \times D^{4-K}$

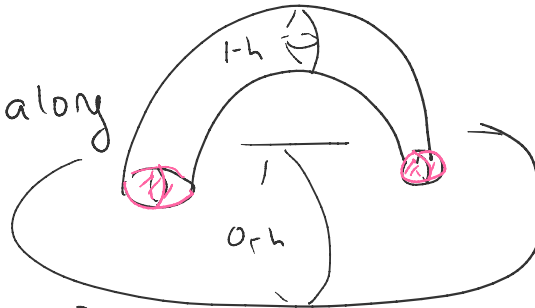
$K = 0, 1, 2, 3, 4$

0-handle : $D^0 \times D^4$

attached along $\partial D^0 = \emptyset$
 S^{-1}



1-handle : $D^1 \times D^3$ attached along $S^0 \times D^3$

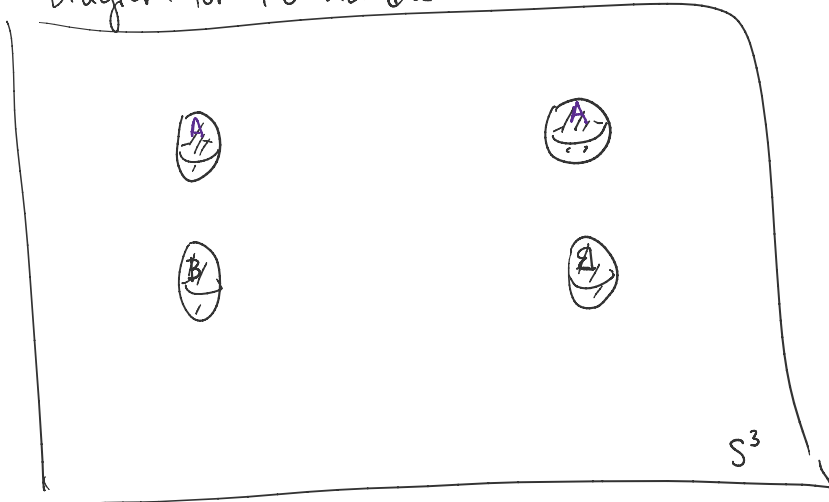


Note boundary of 0-handle is S^3

Usually assume have a single 0-handle

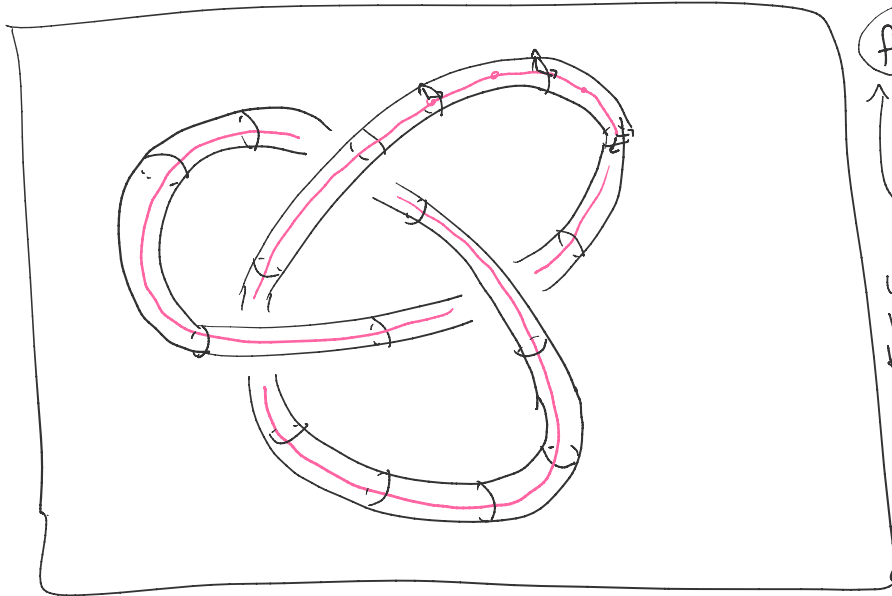
Glue 1-handles to $\partial(0\text{-handle}) = S^3 \leftarrow$ page we draw in

Diagram for 1 0-handle and 2 1-handles



2-handles $D^2 \times D^2$ glued along $S^1 \times D^2 \leftarrow$ solid torus

Beginner Case no 1-handles attaching 2-handles to a 0-handle



$f: S^1 \times D^2 \rightarrow S^3$
 ↑ smooth embedding
 $\begin{matrix} x_2 \\ \downarrow \\ S^1 \times \mathbb{R} \end{matrix}$
 to encode 4-manifold
 what do we need to remember to recover f up to isotopy?

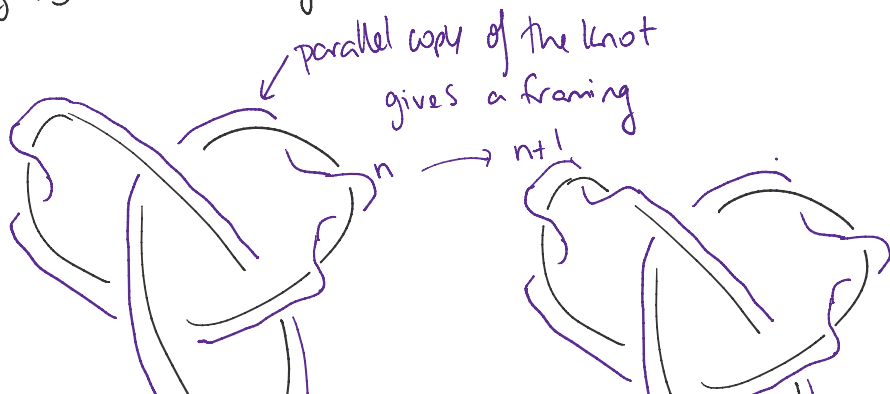
$f(S^1 \times \text{disk})$ is a knot keep track of this knot up to isotopy
 to keep track of normal disk neighborhood embedding,
 need a framing

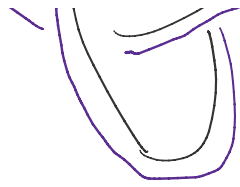
For each point in S^1 can compare $\partial_{x_1}, \partial_{x_2}$ on $S^1 \times D^2$
 \downarrow
 $df(\partial_{x_1}), df(\partial_{x_2})$ on $f(S^1 \times D^2)$
 compare with chosen coordinate system for each pt in S^1
 get a linear transformation taking one coord system to other

$$S^1 \longrightarrow \underline{GL(2, \mathbb{R})} \longrightarrow SO(2, \mathbb{R}) \cong S^1$$

End conclusion: Normal bundle information of f is encoded
 by an element of $\pi_1(SO(2, \mathbb{R})) = \pi_1(S^1) \cong \mathbb{Z}$

A framing is an integer.





Convention: 0-framing is Seifert framing

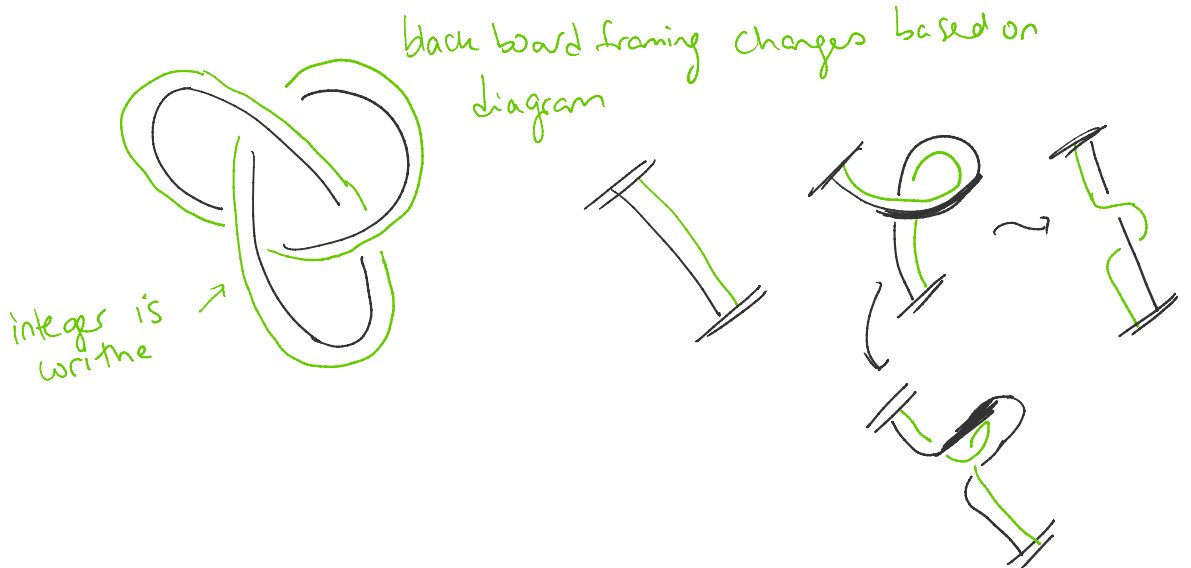
Place a Seifert surface for knot



Want parallel copy of K lying on Seifert surface

Each crossing contributes what looks like twisting in 0-framing

From a diagram -- blackboard framing



2-handle $D^2 \times D^2$
 $S^1 \times D^2$

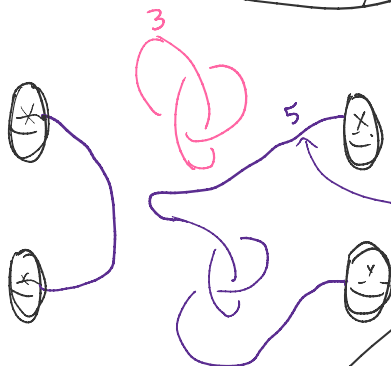
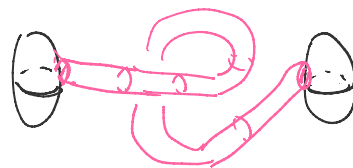
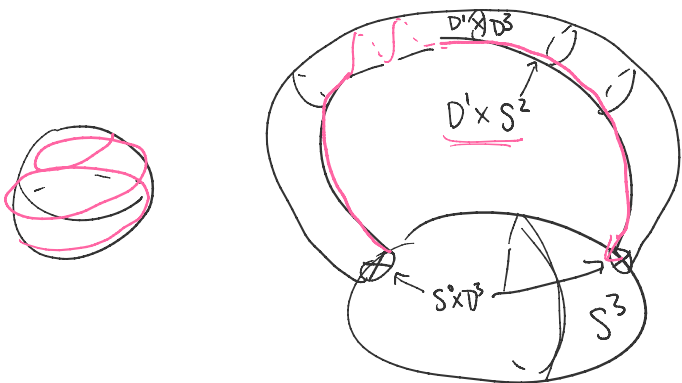


To get from both of these configurations...

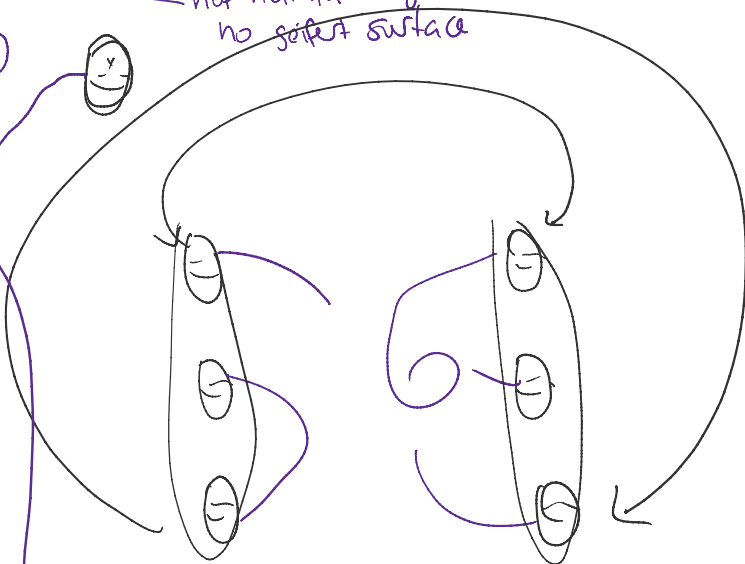
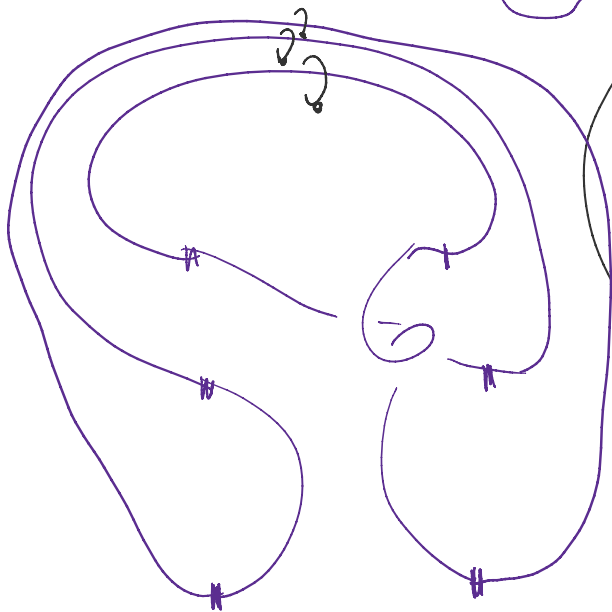
If I have both 0-handles and 1-handles



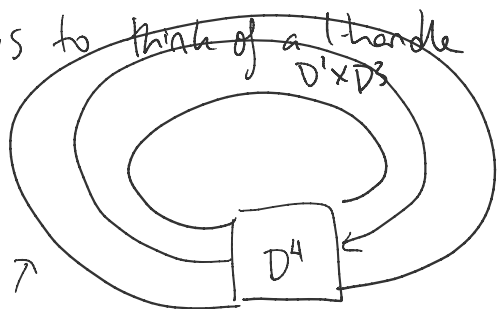
2-handle attached by gluing $S^1 \times D^2$ into $\partial(0\text{-h} \cup 1\text{-h's})$



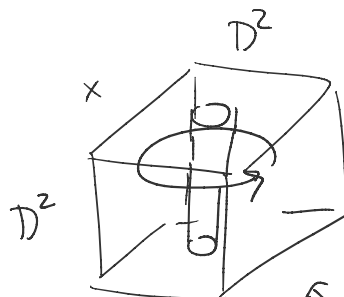
not null homologous
no Seifert surface

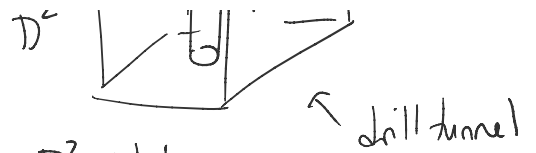


2 ways to think of a 1-handle $D^1 \times D^3$

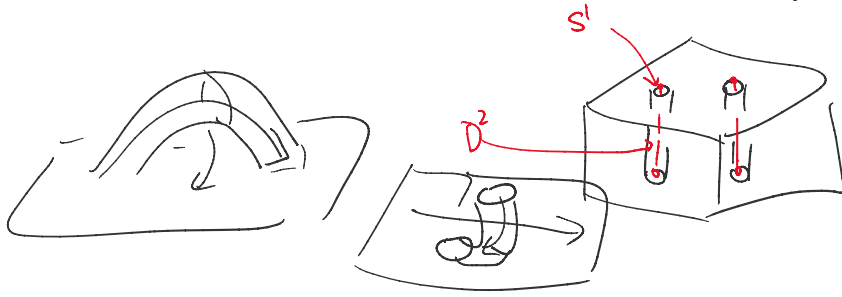


1:12

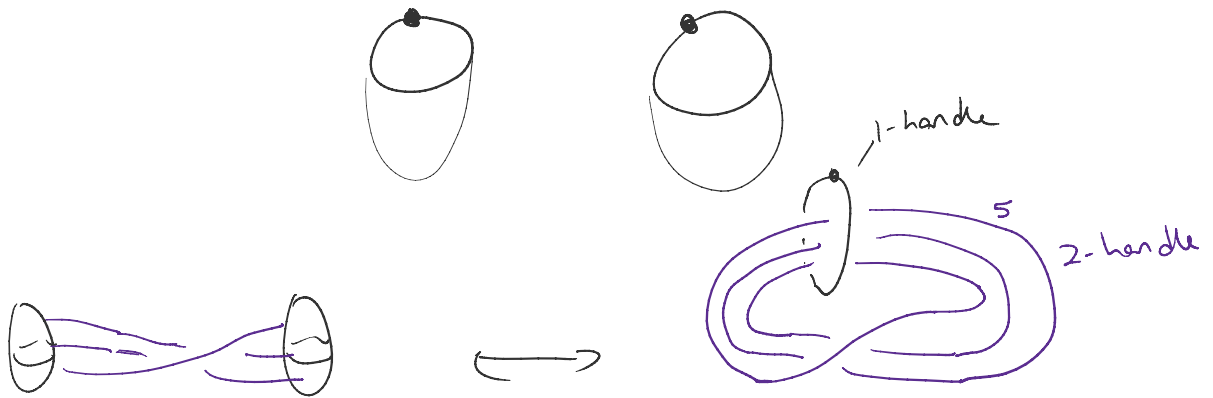




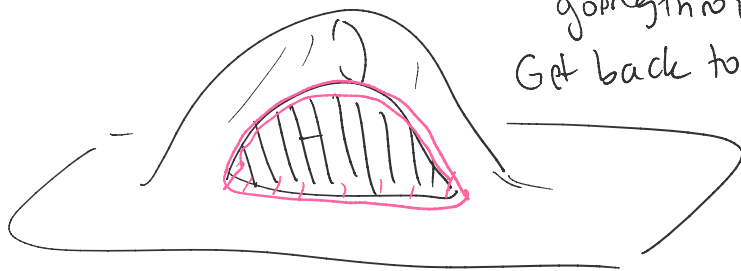
Drill out $D^2 \times \text{hole}$
core $D^2 \times \text{pt}$

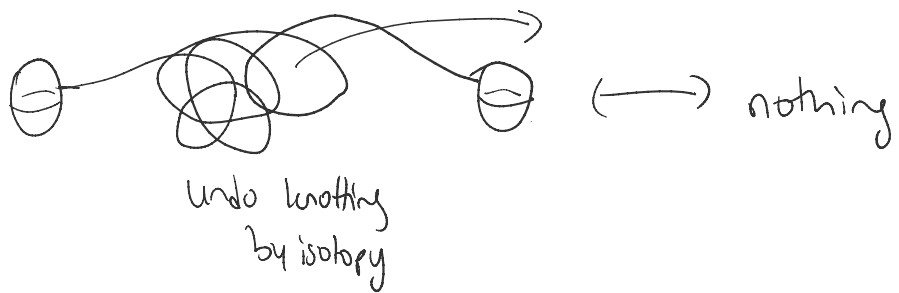


Can keep track of 1-handles by specifying a disk in 0-handle
to drill out with unknotted boundary in S^3

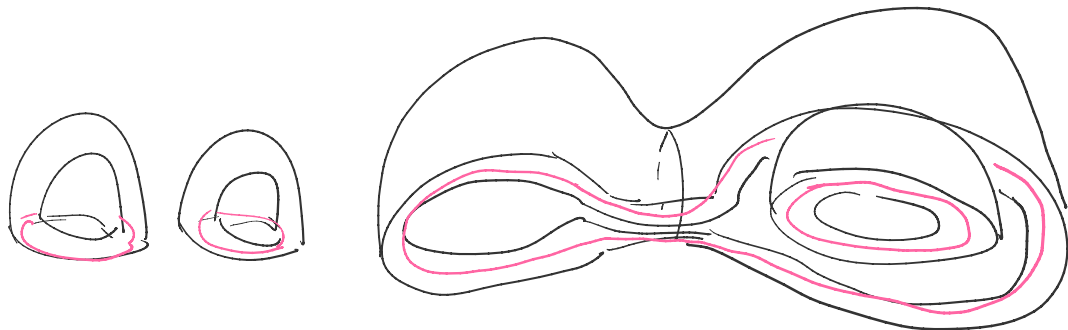
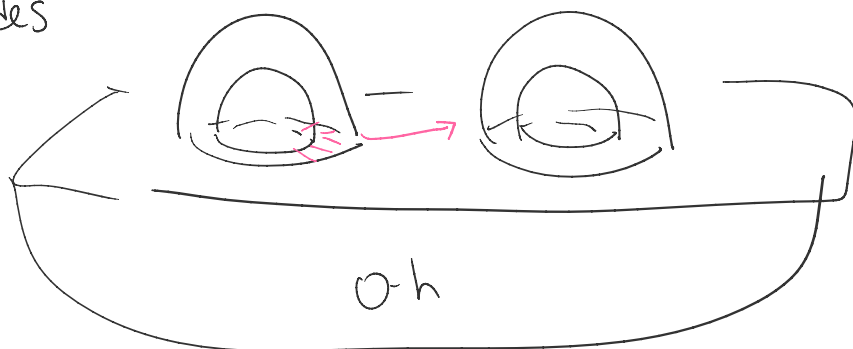


Attach 1-handle then 2-handle
going through 1-handle exactly once
Get back to equivalent to attaching nothing

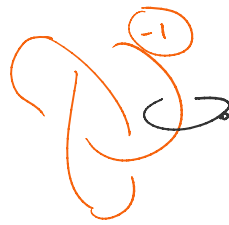




Handle slides

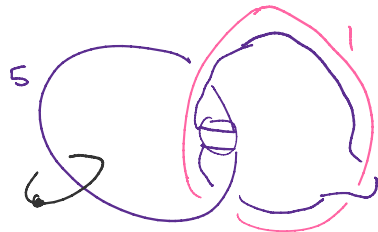
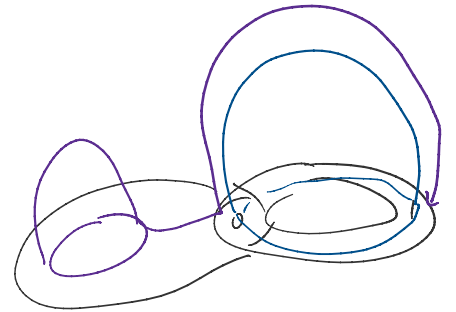
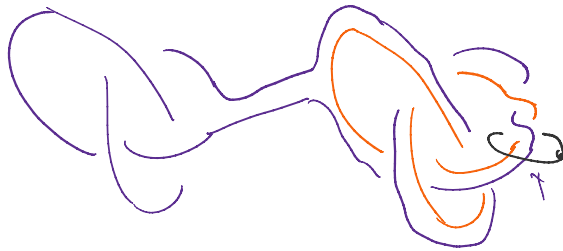
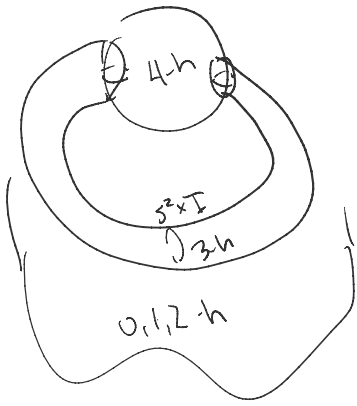


4-manifolds:



handle slide

preserves diffeo type of 4-manifold



$$\begin{matrix} A \\ B \end{matrix} \rightarrow \begin{matrix} A \pm B \\ B \end{matrix}$$

framing
↓

$$\begin{array}{l|l} A \cdot B = 0K & (A \pm B) \cdot B = A \cdot B \pm B \cdot B \\ 2 A^2 = \text{framing}_A & (A \pm B)^2 = A^2 + 2A \cdot B + B^2 \\ 1 B^2 = \text{framing}_B & 2 + 2 \cdot 1 + 1 \end{array}$$

Attaching a²-handle this changes the boundary 3-manifold by Dehn surgery