

# 3D TOMOGRAPHIC PHASE RETRIEVAL AND UNWRAPPING

ALBERT FANNJIANG

ABSTRACT. This paper develops uniqueness theory for 3D phase retrieval with finite, discrete measurement data for strong phase objects and weak phase objects, including:

(i) *Unique determination of (phase) projections from diffraction patterns* – General measurement schemes with coded and uncoded apertures are proposed and shown to ensure unique conversion of diffraction patterns into the phase projection for a strong phase object (respectively, the projection for a weak phase object) in each direction separately without the knowledge of relative orientations and locations. (ii) *Uniqueness for 3D phase unwrapping* – General conditions for unique determination of a 3D strong phase object from its phase projection data are established, including, but not limited to, random tilt schemes densely sampled from a spherical triangle of vertexes in three orthogonal directions and other deterministic tilt schemes. (iii) *Uniqueness for projection tomography* – Unique determination of an object of  $n^3$  voxels from generic  $n$  projections or  $n + 1$  coded diffraction patterns is proved.

This approach has the practical implication of enabling classification and alignment, when relative orientations are unknown, to be carried out in terms of (phase) projections, instead of diffraction patterns.

The applications with the measurement schemes such as single-axis tilt, conical tilt, dual-axis tilt, random conical tilt and general random tilt are discussed.

## 1. INTRODUCTION

Diffraction is crucial in structure determination via high-resolution X-ray and electron microscopies due to the high sensitivity of the phase contrast mechanism [5,35,44,85]. Compared to real-space imaging with lenses, like that in transmission electron microscopy, lensless diffraction methods are aberration-free and have the potential to deliver equivalent resolution using fewer photons/electrons [19,47].

Although single crystal X-ray diffraction is the most commonly used technique for 3D structure determination, the limited crystallinity of many materials often makes obtaining sufficiently large and well-ordered crystals for X-ray diffraction challenging [45]. This obstacle has inspired the development of coherent diffractive imaging for non-periodic structures.

X-ray and electron diffractions for non-periodic objects can be realized in two imaging modalities: diffraction tomography and single-particle imaging/reconstruction (Figure 1). The former involves a sizable object capable of enduring illuminations from various directions, while the latter handles multiple copies of a particle, such as a biomolecule, in different orientations [3,10,12,54,67,86]. These two modalities are mathematically equivalent, except that in single-particle reconstruction, the uncertainty levels vary concerning the relative orientations and locations between the object and the measurement set-up and depend on the sample delivery methods [13,20,50,69,80,91].

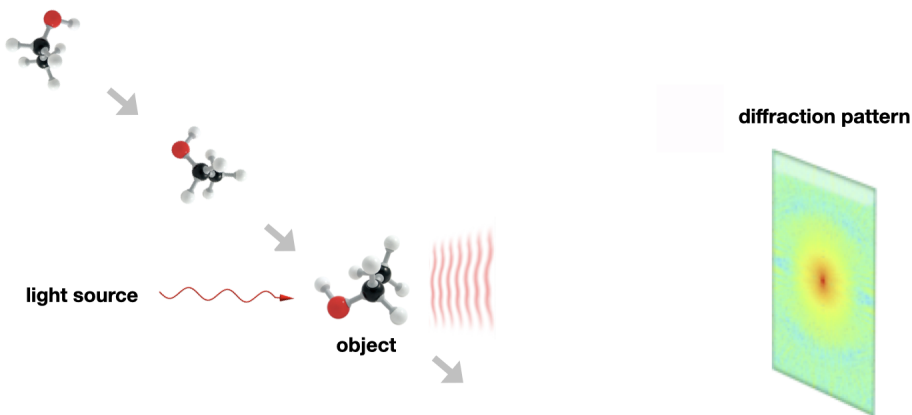


FIGURE 1. Serial crystallography: A stream of identical particles in various orientations scatter the incident wave with diffraction patterns measured in far field.

Since the wavelengths of X-ray and electron waves are extremely short, only intensity measurement data can be collected. Consequently, we refer to the two imaging modalities with X-rays and electrons as 3D phase retrieval, to emphasize this aspect.

Phase retrieval is the process of estimating the phase of a wave from intensity measurements because phase information cannot be directly measured in most imaging systems. In contrast, phase unwrapping is necessary when the phase of a wave is already known but is 'wrapped' due to its cyclical nature. The phase of a wave, typically measured modulo  $2\pi$ , repeats every  $2\pi$  with values recorded between  $-\pi$  and  $\pi$ , or between 0 and  $2\pi$ . When the actual phase exceeds this range, it 'wraps' around, creating ambiguities in the phase data. Phase unwrapping resolves these ambiguities to recover the true phase map.

Our goal is to develop a theory of uniqueness for 3D phase retrieval with finite, discrete measurement data for both strong phase and weak phase objects. To accomplish this, we propose pairwise diffraction measurement schemes and analyze the conditions necessary for the unique determination of the phase projection for a strong phase object, and the projection for a weak phase object in each direction. For a strong phase object, the provided phase projection data contain only the wrapped phase information, so we propose a framework and tilt schemes to address the resulting 3D phase unwrapping problem. For a weak phase object, we analyze the resulting problem of projection tomography and derive explicit conditions for the unique determination of the object of  $n^3$  voxels from  $n$  projection data or  $n + 1$  coded diffraction patterns.

## 2. FORWARD MODEL

Let  $n(\mathbf{r}) \in \mathbb{C}$  denote the complex refractive index at the point  $\mathbf{r} \in \mathbb{R}^3$ . The real and imaginary components of  $n(\mathbf{r})$  describe the dispersive and absorptive aspects of the wave-matter interaction. The real part is related to electron density in the case of X-rays and Coulomb field in the case of electron waves.

Suppose that  $z$  is the optical axis in which the incident plane wave  $e^{i\kappa z}$  propagates. For a quasi-monochromatic wave field  $u$  such as coherent X-rays and electron waves, it is useful to

write  $u = e^{i\kappa z}v$  to factor out the incident wave and focus on the modulation field (i.e. the envelope), described by  $v$ .

The modulation field  $v$  satisfies the paraxial wave equation [70]

$$(1) \quad i\kappa \frac{\partial}{\partial z}v + \frac{1}{2}\Delta_{\perp}v + \kappa^2 f v = 0, \quad f := (n^2 - 1)/2$$

where  $\Delta_{\perp} = \nabla_{\perp}^2$ ,  $\nabla_{\perp} = (\partial_x, \partial_y)$ , derived from the fundamental wave equation by the so called small-angle approximation (hence the term ‘‘paraxial wave’’) which requires the wavelength  $\lambda$  to be smaller than the maximal distance  $d$  over which the fractional variation of  $f$  is negligible [51].

In view of different scaling regimes involved in the set-up (Figure 1 and 2), we now break up the forward model into two components: First, a large Fresnel number regime from the entrance pupil to the exit plane; Second, a small Fresnel number regime from the exit plane to the detector plane.

For the exit wave, consider the large Fresnel number regime

$$(2) \quad N_{\text{F}} = \frac{d^2}{\lambda \ell} \gg 1$$

where  $\ell$  is the linear size of the object. By rescaling the coordinates

$$z \longrightarrow \ell z, \quad (x, y) \longrightarrow d(x, y)$$

we non-dimensionalize (1) as

$$i \frac{\partial}{\partial z}v + \frac{1}{4\pi} N_{\text{F}}^{-1} \Delta_{\perp}v + \kappa \ell f v = 0,$$

which has a diminishing diffraction term  $\Delta_{\perp}$  under (2).

After dropping the  $\Delta_{\perp}$  term, the reduced equation in terms of the original coordinates before rescaling is

$$i \frac{\partial}{\partial z}v + \kappa f v = 0,$$

which can be solved by integrating along the optical axis as

$$(3) \quad v(\mathbf{r}) = e^{i\kappa\psi(\mathbf{r})},$$

$$(4) \quad \psi(x, y, z) = \int_{-\infty}^z f(x, y, z') dz'.$$

Alternatively, (3)-(4) can be derived by stationary phase analysis [51] or the high-frequency Rytov approximation [65].

The exit wave is given by  $u = e^{i\kappa z}v$  evaluated at the object’s rear boundary (say,  $z = 0$ ). At  $z = +\infty$ , (4) is called the *ray transform*, or simply the *projection*, of the object  $f$  in the  $z$  direction and (3) will be called the *phase projection* in this paper which equals the exit wave, up to a constant phase factor [66].

By allowing significant phase fluctuations with arbitrary  $\kappa|\psi|$ , (3)-(4) represents an improvement over the *weak-phase-object approximation*

$$(5) \quad e^{i\kappa\psi} \approx 1 + i\kappa\psi$$

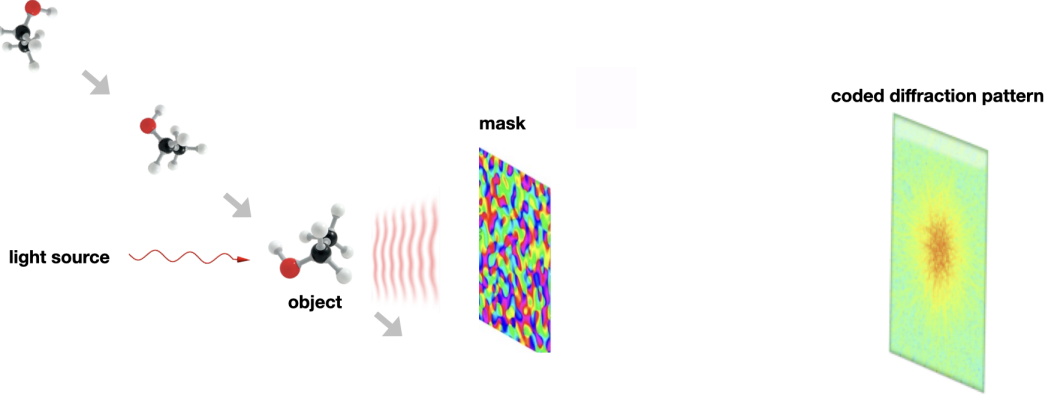


FIGURE 2. Serial crystallography with a coded aperture

often used in cryo-electron microscopy (cryo-EM) [1, 33, 39]. Following the nomenclature in [39] and [83], we call (3)-(4) the *strong-phase-object* approximation, noting, however, that  $f$  is a complex-valued function in general (thus not a “phase” object *per se*). The strong-phase-object approximation is often invoked in X-ray diffractive imaging (see, e.g. [23, 40, 41, 87]).

However, the exit wave described by the phase projection (3) yields only the information of the projection of  $f$  modulo  $2\pi/\kappa$ , and therein arises the problem of *phase unwrapping*, which is fundamentally unsolvable unless additional prior information is known (see Section 8) and poses a major road block to the implementation of diffraction tomography. The solution for phase unwrapping is critical in revealing the depth dimension of the object. In contrast, phase unwrapping problem is not present in computed tomography [65], which neglects diffraction, or , cryo-EM which operates under the weak-phase-object approximation (5).

After passing through the object and the mask  $\mu$  immediately behind, the exit wave (3)-(4) becomes the masked exit wave  $\mu e^{i\kappa\psi}$  at the exit plane  $z = 0$  and then undergoes the free space propagation (with  $n = 1, f = 0$ ) for  $z > 0$  described by

$$i\frac{\partial}{\partial z}v + \frac{1}{2\kappa}\Delta_{\perp}v = 0, \quad v(x, y, 0) = \mu e^{i\kappa\psi}.$$

The solution is given by convolution with the Fresnel kernel as

$$v(x, y, z) = \frac{1}{i\lambda z} \int_{\mathbb{R}^2} e^{\frac{i\kappa}{2z}(|x-x'|^2+|y-y'|^2)} \mu(x', y') e^{i\kappa\psi(x', y', 0)} dx' dy'$$

and hence, after writing out the quadratic phase term,

$$(6) \quad u(x, y, z) = \frac{e^{i\kappa z}}{i\lambda z} e^{\frac{i\kappa}{2z}(x^2+y^2)} \int_{\mathbb{R}^2} e^{-\frac{i\kappa}{z}(xx'+yy')} e^{\frac{i\kappa}{2z}(|x'|^2+|y'|^2)} \mu(x', y') e^{i\kappa\psi(x', y', 0)} dx' dy'.$$

Let the detector plane  $z = L$  to be sufficiently far away from the exit plane  $z = 0$  so that the Fresnel number is small:

$$(7) \quad N_F = \frac{\ell^2}{\lambda L} \ll 1.$$

Then the second integrand (the quadratic phase factor) in (6) is approximately 1 because the integration is carried out in the support of  $\mu$  which is taken to be a square of size  $\ell$  around the origin. On the other hand, the first integrand in (6) (the cross phase factor) has the effect of the Fourier transform  $\mathcal{F}$  if the coordinates are properly rescaled to reflect the fact that the detector area is usually much larger than  $\ell^2$ .

Since only the intensities of  $u$  are measured, the phase factors  $e^{i\kappa z} e^{\frac{i\kappa}{2z}(x^2+y^2)}$  in (6) drop out and

$$(8) \quad |u(x, y, L)|^2 = |v(x, y, L)|^2 \sim |\mathcal{F}[\mu e^{i\kappa\psi}]|^2,$$

up to a scale factor  $(\lambda L)^{-1}$ , which can be neglected in our analysis.

Depending on the context we shall refer to either a diffraction pattern or a projection as a “snapshot”.

### 3. OUTLINE AND CONTRIBUTION

This paper presents a *discrete* framework for analyzing *discrete, finite* measurement data analogous to (8) and develops a uniqueness theory for 3D phase retrieval and unwrapping.

Our main contribution in this paper is as follows:

- 1) **(Phase) projection recovery.** We introduce pairwise measurement schemes (Section 5) with both coded and un-coded apertures and derive precise conditions for unique determination of (i) the phase projection for strong phase objects (Theorem 6.1 & 6.2) and (ii) the projection, up to a phase factor, for weak phase objects (Theorem 7.1 & 7.2).
- 2) **Phase unwrapping.** We propose a framework for analyzing the phase unwrapping problem when the given data are phase projections (Section 8) and derive generic conditions for unique phase unwrapping (Theorem 8.1). We provide explicit tilt schemes for phase unwrapping, including, but not limited to, random tilt schemes densely sampled from a spherical triangle with vertexes in three orthogonal directions (Section 9.1) and other well known deterministic tilt schemes (Section 9.2)
- 3) **Projection tomography.** We show that any generic set of  $n$  projections or generic set of  $n + 1$  coded diffraction patterns uniquely determine the object (Theorem 10.1 & 10.4).

Our numerical simulation with noisy data shows that the ratio of relative reconstruction error to the noise level in the data *per direction* is slightly above 1, illustrating the feasibility of item 1) above (Section 11).

Next let us turn to the discrete set-up needed for the tasks above (Section 4 and 4.2).

### 4. DISCRETE SET-UP

Imagine an object defined on a cube of size  $\ell$  in  $\mathbb{R}^3$ . If we want to discretize the object, what would be a proper grid spacing? Obviously, the finer the grid the higher the fidelity of the discretization. The grid system, however, would be unnecessarily large if the grid spacing is

much smaller than the resolution length which is the smallest feature size resolvable by the imaging system.

In a diffraction-limited imaging system such as X-ray crystallography the resolution length is roughly  $\lambda/2$ . In a radiation-dose-limited system such as electron diffraction, the resolution length can be considerably larger than  $\lambda/2$ .

Now suppose we choose  $\lambda/2$  to be the grid spacing (the voxel size). For this grid system to represent accurately the object continuum, it is necessary that the grid spacing is equal to or smaller than the maximal distance  $d$  over which the fractional variation of the object is negligible. On the other hand, the underlying assumption for the paraxial wave equation (1) is exactly  $\lambda \leq d$  [51]. Hence the fractional variation of the object within a voxel as well as between adjacent grid points is negligible, two desirable properties of a grid system. In other words, the grid system with spacing  $\lambda/2$  gives an accurate representation of the object continuum under the assumption of the paraxial wave equation without resulting in unnecessary complexity.

We will, however, let the discrete object to take independent, arbitrary value in each voxel, except for Section 8 where we assume the so called Itoh condition that the difference in the object between two adjacent grid points is less than  $\pi/\kappa$  in order to obtain uniqueness for phase unwrapping.

Let  $\lambda/2$  be the unit of length and the grids (the voxels) be labelled by integer triplets  $(i, j, k)$ . In this length unit, the wavenumber  $\kappa$  has the value  $\pi$  (i.e.  $\pi/\kappa = 1$ ). The number  $n$  of grid points in each dimension is about  $2\ell/\lambda$  which may be large for a strong phase object.

Let  $\llbracket k, l \rrbracket$  denote the integers between and including the integers  $k$  and  $l$ . Let  $O_n$  denote the class of discrete complex-valued objects

$$(9) \quad O_n := \{f : f(i, j, k) \in \mathbb{C}, i, j, k \in \mathbb{Z}_n\}$$

where

$$(10) \quad \mathbb{Z}_n = \begin{cases} \llbracket -n/2, n/2 - 1 \rrbracket & \text{if } n \text{ is an even integer;} \\ \llbracket -(n-1)/2, (n-1)/2 \rrbracket & \text{if } n \text{ is an odd integer.} \end{cases}$$

To fix the idea, we consider the case of odd  $n$  in the paper.

Following the framework in [4] we discretize the projection geometry given in Section 2.

We define three families of line segments, the  $x$ -lines,  $y$ -lines, and  $z$ -lines. The  $x$ -lines, denoted by  $\ell_{(1,\alpha,\beta)}(c_1, c_2)$  with  $|\alpha|, |\beta| < 1$ , are defined by

$$(11) \quad \ell_{(1,\alpha,\beta)}(c_1, c_2) : \begin{bmatrix} y \\ z \end{bmatrix} = \begin{bmatrix} \alpha x + c_1 \\ \beta x + c_2 \end{bmatrix} \quad c_1, c_2 \in \mathbb{Z}_{2n-1}, \quad x \in \mathbb{Z}_n$$

To avoid wraparound of  $x$ -lines with , we can zero-pad  $f$  in a larger lattice  $\mathbb{Z}_p^3$  with  $p \geq 2n-1$ . This is particularly important when it comes to define the ray transform by a line sum (cf. (16)-(18)) since wrap-around is unphysical.

Similarly, a  $y$ -line and a  $z$ -line are defined as

$$(12) \quad \ell_{(\alpha,1,\beta)}(c_1, c_2) : \begin{bmatrix} x \\ z \end{bmatrix} = \begin{bmatrix} \alpha y + c_1 \\ \beta y + c_2 \end{bmatrix} \quad c_1, c_2 \in \mathbb{Z}_{2n-1}, \quad y \in \mathbb{Z}_n,$$

$$(13) \quad \ell_{(\alpha,\beta,1)}(c_1, c_2) : \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \alpha z + c_1 \\ \beta z + c_2 \end{bmatrix} \quad c_1, c_2 \in \mathbb{Z}_{2n-1}, \quad z \in \mathbb{Z}_n,$$

with  $|\alpha|, |\beta| < 1$ .

Let  $\tilde{f}$  be the continuous interpolation of  $f$  given by

$$(14) \quad \tilde{f}(x, y, z) = \sum_{i \in \mathbb{Z}_n} \sum_{j \in \mathbb{Z}_n} \sum_{k \in \mathbb{Z}_n} f(i, j, k) D_p(x - i) D_p(y - j) D_p(z - k), \quad x, y, z, \in \mathbb{R},$$

where  $D_p$  is the  $p$ -periodic Dirichlet kernel given by

$$(15) \quad D_p(t) = \frac{1}{p} \sum_{l \in \mathbb{Z}_p} e^{i2\pi lt/p} = \begin{cases} 1, & t = mp, \quad m \in \mathbb{Z} \\ \frac{\sin(\pi t)}{p \sin(\pi t/p)}, & \text{else.} \end{cases}$$

In particular,  $[D_p(i - j)]_{i,j \in \mathbb{Z}_p}$  is the  $p \times p$  identity matrix. Because  $D_p$  is a continuous  $p$ -periodic function, so is  $\tilde{f}$ . However, we will only use the restriction of  $\tilde{f}$  to one period cell  $[-(p-1)/2, (p-1)/2]^3$  to define the discrete projections and avoid the wraparound effect.

We define the discrete projections as the following line sums

$$(16) \quad f_{(1,\alpha,\beta)}(c_1, c_2) = \sum_{i \in \mathbb{Z}_n} \tilde{f}(i, \alpha i + c_1, \beta i + c_2),$$

$$(17) \quad f_{(\alpha,1,\beta)}(c_1, c_2) = \sum_{j \in \mathbb{Z}_n} \tilde{f}(\alpha j + c_1, j, \beta j + c_2)$$

$$(18) \quad f_{(\alpha,\beta,1)}(c_1, c_2) = \sum_{k \in \mathbb{Z}_n} \tilde{f}(\alpha k + c_1, \beta k + c_2, k)$$

with  $c_1, c_2 \in \mathbb{Z}_{2n-1}$ .

The 3D discrete Fourier transform  $\hat{f}$  of the object  $f \in O_n$ , is given by

$$(19) \quad \hat{f}(\xi, \eta, \zeta) = \sum_{i,j,k \in \mathbb{Z}_n} f(i, j, k) e^{-i2\pi(\xi i + \eta j + \zeta k)/p} = \sum_{i,j,k \in \mathbb{Z}_p} f(i, j, k) e^{-i2\pi(\xi i + \eta j + \zeta k)/p}$$

where the range of the Fourier variables  $\xi, \eta, \zeta$  can be extended from the discrete interval  $\mathbb{Z}_p$  to the continuum  $[-(p-1)/2, (p-1)/2]$ . Note that by definition,  $\hat{f}$  is a  $p$ -periodic band-limited function. The associated 1-D and 2-D (partial) Fourier transforms are similarly defined  $p$ -periodic band-limited functions.

**4.1. Fourier slices and common lines.** The Fourier slice theorem concerns the 2-D discrete Fourier transform  $\hat{f}_{(1,\alpha,\beta)}$  defined as

$$(20) \quad \hat{f}_{(1,\alpha,\beta)}(\eta, \zeta) = \sum_{j,k \in \mathbb{Z}_n} f_{(1,\alpha,\beta)}(j, k) e^{-i2\pi(\eta j + \zeta k)/p},$$

and the 3-D discrete Fourier transform given in (19).

It is straightforward, albeit somewhat tedious, to derive the discrete Fourier slice theorem which plays an important role in our analysis.

**Proposition 4.1.** [4] (*Discrete Fourier slice theorem*) For a given family of  $x$ -lines  $\ell_{(1,\alpha,\beta)}$  with fixed slopes  $(\alpha, \beta)$  and variable intercepts  $(c_1, c_2)$ . Then the 2D discrete Fourier transform  $\widehat{f}_{(1,\alpha,\beta)}$  of the  $x$ -projection  $f_{(1,\alpha,\beta)}$ , given in (16), and the 3D discrete Fourier transform  $\widehat{f}$  of the object  $f$  satisfy the equation

$$(21) \quad \widehat{f}_{(1,\alpha,\beta)}(\eta, \zeta) = \widehat{f}(-\alpha\eta - \beta\zeta, \eta, \zeta), \quad \eta, \zeta \in \mathbb{Z}.$$

Likewise, we have

$$(22) \quad \widehat{f}_{(\alpha,1,\beta)}(\xi, \zeta) = \widehat{f}(\xi, -\alpha\xi - \beta\zeta, \zeta), \quad \xi, \zeta \in \mathbb{Z};$$

$$(23) \quad \widehat{f}_{(\alpha,\beta,1)}(\xi, \eta) = \widehat{f}(\xi, \eta, -\alpha\xi - \beta\eta), \quad \xi, \eta \in \mathbb{Z}.$$

**Remark 4.2.** For the general domain  $\mathbb{R}^2$ , it is not hard to derive the following results

$$(24) \quad \widehat{f}_{(1,\alpha,\beta)}(\eta, \zeta) = \sum_{j,k \in \mathbb{Z}_p} \widehat{f}(-\alpha j - \beta k, j, k) D_p(\eta - j) D_p(\zeta - k), \quad \eta, \zeta \in \mathbb{R};$$

$$(25) \quad \widehat{f}_{(\alpha,1,\beta)}(\xi, \zeta) = \sum_{j,k \in \mathbb{Z}_p} \widehat{f}(\xi, -\alpha j - \beta k, \zeta) D_p(\xi - j) D_p(\zeta - k), \quad \xi, \zeta \in \mathbb{R};$$

$$(26) \quad \widehat{f}_{(\alpha,\beta,1)}(\xi, \eta) = \sum_{j,k \in \mathbb{Z}_p} \widehat{f}(j, k, -\alpha j - \beta k) D_p(\xi - j) D_p(\eta - k), \quad \eta, \xi \in \mathbb{R},$$

in the form of interpolation by the grids in the respective Fourier slices. From (15) it follows that the right hand side of (24)-(26) are Laurent polynomials of 2 trigonometric variables (e.g.  $e^{i2\pi\eta/p}, e^{i2\pi\zeta/p}$  for (24)), and that (24)-(26) reduce to (21)-(23) when the trigonometric variables are integer powers of  $e^{i2\pi/p}$ .

Recalling the view of discretization espoused at the beginning of this section and returning to the original scale in the continuous setting, we note that

$$(27) \quad \lim_{p \rightarrow \infty} p D_p(pt) = \delta(t), \quad t \in \mathbb{R},$$

the Dirac delta function. By (27) and rescaling the standard, continuous version of Fourier slice theorem is recovered from (24)-(26).

For ease of notation, we denote by  $\mathbf{t}$  the direction of projection,  $(1, \alpha, \beta)$ ,  $(\alpha, 1, \beta)$  or  $(\alpha, \beta, 1)$  in the reference frame attached to the object. Let  $P_{\mathbf{t}}$  denote the origin-containing (continuous) plane orthogonal to  $\mathbf{t}$  in the Fourier space. The standard common line is defined by  $L_{\mathbf{t}, \mathbf{t}'} := P_{\mathbf{t}} \cap P_{\mathbf{t}'}$  for  $\mathbf{t}, \mathbf{t}'$  not parallel to each other.

By a slight abuse of notation, we can formulate Proposition 4.1 succinctly as

$$(28) \quad \widehat{f}_{\mathbf{t}}(\mathbf{k}) = \widehat{f}_{\mathbf{t}'}(\mathbf{k}'), \quad \mathbf{k}, \mathbf{k}' \in P_{\mathbf{t}} \cap P_{\mathbf{t}'} \cap \mathbb{Z}^2,$$

where  $\mathbf{k}, \mathbf{k}'$  are the corresponding integer points on  $P_{\mathbf{t}}$  and  $P_{\mathbf{t}'}$ , respectively.

For example, let  $\mathbf{t} \sim (\alpha, \beta, 1)$  and  $\mathbf{t}' \sim (\alpha', \beta', 1)$ . The Fourier slices are given by

$$(29) \quad \alpha\xi + \beta\eta + \zeta = 0, \quad \alpha'\xi + \beta'\eta + \zeta = 0,$$



with the correspondence  $\mathbf{k} = \mathbf{k}' = (\xi, \eta) \in \mathbb{Z}^2$ .

For a different configuration, let  $\mathbf{t} \sim (\alpha, \beta, 1)$  and  $\mathbf{t}' \sim (1, \beta', \gamma')$ . The Fourier planes are given by

$$(30) \quad \alpha\xi + \beta\eta + \zeta = 0, \quad \xi + \beta'\eta + \gamma'\zeta = 0,$$

with the correspondence  $\mathbf{k} = (\xi, \eta) \in \mathbb{Z}^2$  and  $\mathbf{k}' = (\eta, \zeta) \in \mathbb{Z}^2$ .

For non-integral points, however, the common lines are perturbed by interpolation (24)-(26). For (29) and (30), the ‘‘common lines’’ can be generalized respectively as the traces of the two-dimensional surfaces defined by

$$(31) \quad L_{\mathbf{t}, \mathbf{t}'}(f) := \left\{ \widehat{f}_{(\alpha, \beta, 1)}(\xi, \eta) = \widehat{f}_{(\alpha', \beta', 1)}(\xi', \eta') \right\} \subseteq \mathbb{R}^2 \times \mathbb{R}^2$$

$$(32) \quad L_{\mathbf{t}, \mathbf{t}'}(f) := \left\{ \widehat{f}_{(\alpha, \beta, 1)}(\xi, \eta) = \widehat{f}_{(1, \beta', \gamma')}(\eta', \zeta') \right\} \subseteq \mathbb{R}^2 \times \mathbb{R}^2.$$

By (28),  $0 \in L_{\mathbf{t}, \mathbf{t}'}(f)$ . In view of (27), the projection of  $L_{\mathbf{t}, \mathbf{t}'}$  on either Fourier slice is near  $P_{\mathbf{t}} \cap P_{\mathbf{t}'}$  for sufficiently large  $n$ .

We shall refer to  $L_{\mathbf{t}, \mathbf{t}'}(f)$  as the *common set* for the Fourier slices of  $f$  orthogonal to  $\mathbf{t}, \mathbf{t}'$ . The notion of common sets will be used to formulate a technical condition for Theorem 6.2.

**4.2. Diffraction pattern.** Let  $\mathcal{T}$  denote the set of directions  $\mathbf{t}$  employed in the 3D diffraction measurement, which can be coded (as in Figure 2) or uncoded (as in Figure 1). To fix the idea, let  $p = 2n - 1$  in (15).

Let the Fourier transform  $\mathcal{F}$  of the projection  $e^{i\kappa f_{\mathbf{t}}(\mathbf{n})}$  be written as

$$(33) \quad F_{\mathbf{t}}(e^{-i2\pi\mathbf{w}}) = \sum_{\mathbf{n} \in \mathbb{Z}_p^2} e^{-i2\pi\mathbf{n} \cdot \mathbf{w}} e^{i\kappa f_{\mathbf{t}}(\mathbf{n})}, \quad \mathbf{w} \in \left[ -\frac{1}{2}, \frac{1}{2} \right]^2.$$

In the absence of a random mask ( $\mu \equiv 1$ ), the intensities of the Fourier transform can be written as

$$(34) \quad |F_{\mathbf{t}}(e^{-i2\pi\mathbf{w}})|^2 = \sum_{\mathbf{n} \in \mathbb{Z}_{2p-1}^2} \left\{ \sum_{\mathbf{n}' \in \mathbb{Z}_p^2} e^{i\kappa f_{\mathbf{t}}(\mathbf{n}' + \mathbf{n})} e^{-i\kappa \overline{f_{\mathbf{t}}(\mathbf{n}')}} \right\} e^{-i2\pi\mathbf{n} \cdot \mathbf{w}}, \quad \mathbf{w} \in \left[ -\frac{1}{2}, \frac{1}{2} \right]^2,$$

which is called the uncoded diffraction pattern in the direction  $\mathbf{t}$ . Here and below the over-line notation means complex conjugacy. The expression in the brackets in (34) is the autocorrelation function of  $e^{i\kappa f_{\mathbf{t}}}$ .

The diffraction patterns are then uniquely determined by sampling on the grid

$$(35) \quad \mathbf{w} \in \frac{1}{2p-1} \mathbb{Z}_{2p-1}^2$$

or by Kadec’s 1/4-theorem on any following irregular grid [90]

$$(36) \quad \{\mathbf{w}_{jk}, j, k \in \mathbb{Z}_{2p-1} : |(2p-1)\mathbf{w}_{jk} - (j, k)| < 1/4\}.$$

With the regular (35) or irregular (36) sampling, the diffraction pattern contains the same information as does the autocorrelation function of  $f_{\mathbf{t}}$ .

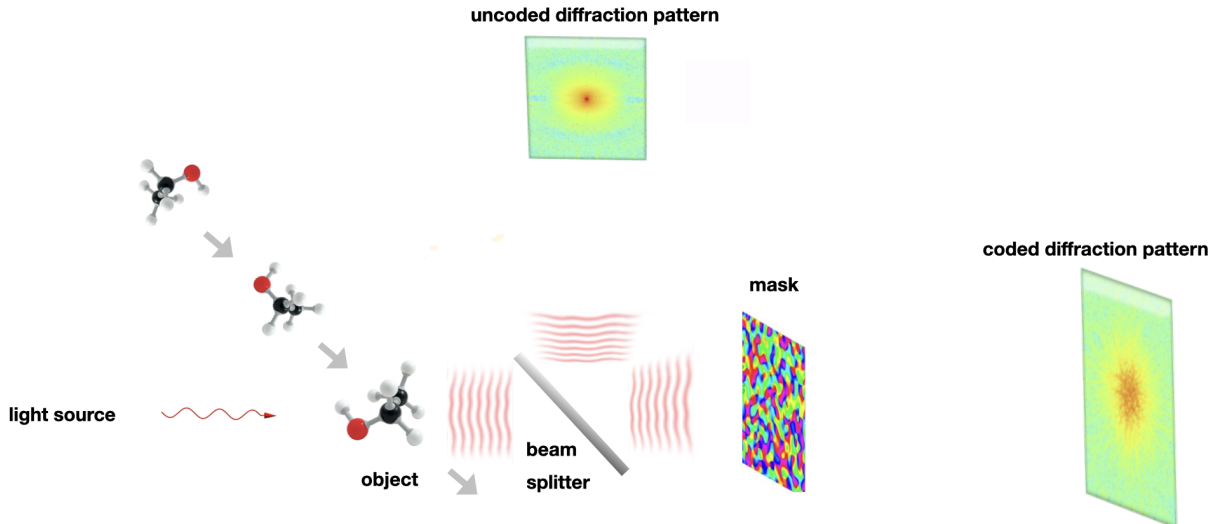


FIGURE 3. Simultaneous measurement of two diffraction patterns, one coded and one uncoded, with a beam splitter.

## 5. PAIRWISE MEASUREMENT SCHEMES

In this section, we introduce pairwise measurement schemes to facilitate conversion of diffraction patterns into (phase) projection in each direction.

**5.1. Beam splitting.** Consider the measurement scheme stylized in Figure 3 where a beam splitter is inserted behind the object and the mask placed in only one of two light paths behind the splitter. Ideally, the beam splitter produces two identical beams to facilitate two snapshots of the same exit wave. The reader is referred to [55, 57, 68, 73] for recent advances in X-ray splitters.

**5.2. Dual illuminations.** Alternatively, consider simultaneous illuminations by two beams of directions  $\mathbf{t} \neq \mathbf{t}'$  with both exit waves masked by the coded aperture as depicted in Figure 4. Both beams' intensities are then measured by detectors in far field. Note that the two beams need not be coherent with each other for the scheme to work since no interference is needed.

**5.3. Random conical tilt and orthogonal tilt.** The main idea in Figure 4 can be realized in a different way with a fixed-target sample delivery by the scheme *random conical tilt* (RCT) or *orthogonal tilt* (OT) in cryo-EM [33, 56].

As shown in Figure 5 (b), many identical particles are randomly located and oriented on a grid which can be precisely tilted about a tilt axis by a goniometer. With dose-fractionated beams, the diffraction patterns of the identical particles in the two orientations are measured with the *coded* aperture in correspondence with Figure 4.

In Section 6 and 7, we prove that

$$(37) \quad e^{i\kappa g \mathbf{t}} = e^{i\kappa f \mathbf{t}} \quad \text{in the case of strong phase objects}$$

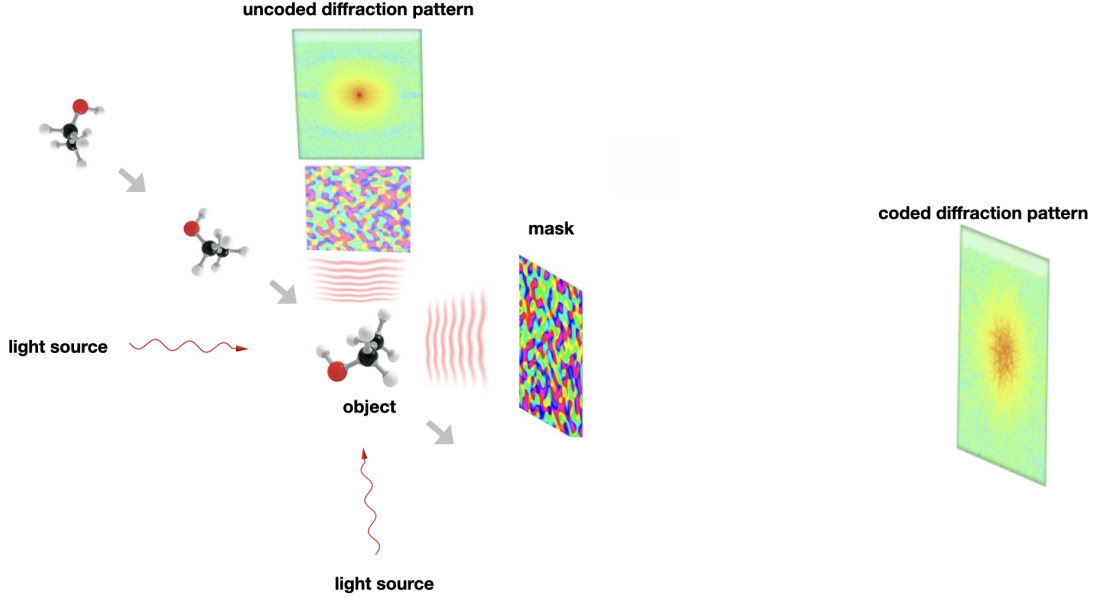


FIGURE 4. Simultaneous illumination of the object with two coded diffraction patterns measured in a known relative orientation.

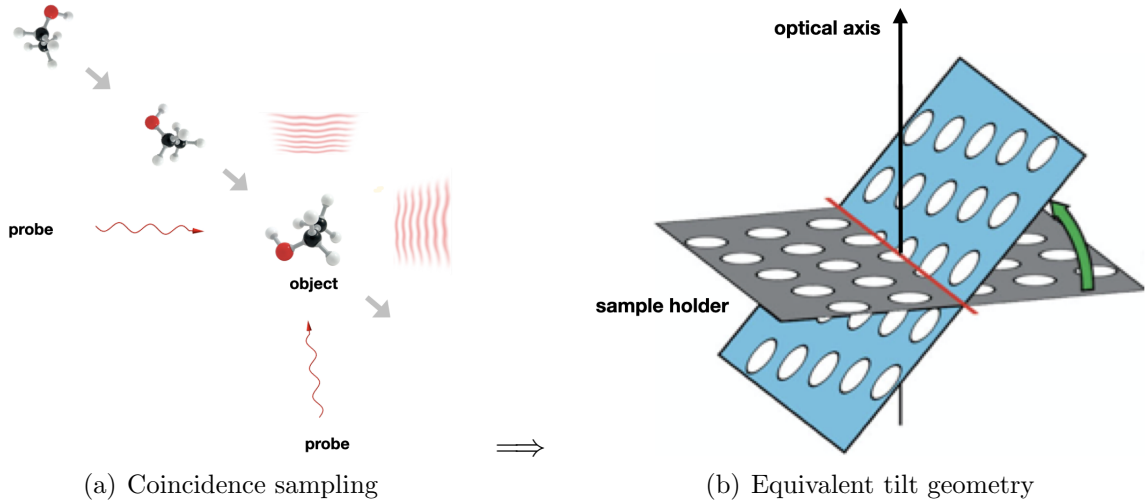


FIGURE 5. (a) *Serial* data collection implemented by (b) the random conical tilt and orthogonal tilt in cryo-EM both of which collect **pairs** of measurement data in a fixed relative orientation corresponding to the angle about 50 deg and 90 deg, respectively, between the two beams [33, 56].

and, for a constant  $\theta_0 \in \mathbb{R}$ ,

$$(38) \quad g_{\mathbf{t}} = e^{i\theta_0} f_{\mathbf{t}} \quad \text{in the case of weak phase objects}$$

if  $f, g \in O_n$  produce the same diffraction patterns for  $\mathbf{t} \in \mathcal{T}$  in the set-up of Figure 3, 4 and 5(b). For this uniqueness theory we assume the following on the coded aperture

**Mask Assumption:** The mask function is given by  $\mu(\mathbf{n}) = \exp[i\phi(\mathbf{n})]$  with independent, continuous random variables  $\phi(\mathbf{n}) \in \mathbb{R}$ .

In Section 8 we find conditions on  $\mathcal{T}$  that ensure  $g = f$  if (37) holds. This is a uniqueness theory for phase unwrapping.

In Section 10, we find conditions on  $\mathcal{T}$  that ensure  $g = e^{i\theta_0} f$  for some constant  $\theta_0 \in \mathbb{R}$  independent of  $\mathbf{t}$  if (38) holds. This is a unique theory for projection tomography.

In Section 11, we give numerical evidence for noise robustness of the set-up in Figure 3.

## 6. REDUCTION WITH STRONG PHASE OBJECTS

Let  $f_{\mathbf{t}}^*$  denote the projection  $f_{\mathbf{t}}$  translated by some  $\mathbf{l}_{\mathbf{t}} \in \mathbb{Z}^2$ , i.e.

$$(39) \quad f_{\mathbf{t}}^*(\mathbf{n}) := f_{\mathbf{t}}(\mathbf{n} + \mathbf{l}_{\mathbf{t}}), \quad \text{subject to } \text{supp}(f_{\mathbf{t}}^*) \subseteq \mathbb{Z}_n^2.$$

We assume that each snapshot is taken for  $f_{\mathbf{t}}^*$  (not  $f_{\mathbf{t}}$ ) with a shift  $\mathbf{l}_{\mathbf{t}}$  due to variability in sample delivery.

Theorem 6.1 says that the two diffraction patterns collected in the scheme of Figure 3 uniquely determine the underlying phase projection.

**Theorem 6.1.** *Let  $f, g \in O_n$  and the Mask Assumption hold true. Suppose that for any  $\mathbf{t}$*

$$(40) \quad |\mathcal{F}(e^{i\kappa g_{\mathbf{t}}^*})|^2 = |\mathcal{F}(e^{i\kappa f_{\mathbf{t}}^*})|^2$$

$$(41) \quad |\mathcal{F}(\mu \odot e^{i\kappa g_{\mathbf{t}}^*})|^2 = |\mathcal{F}(\mu \odot e^{i\kappa f_{\mathbf{t}}^*})|^2$$

*Then  $e^{i\kappa g_{\mathbf{t}}} = e^{i\kappa f_{\mathbf{t}}}$  almost surely.*

The proof of Theorem 6.1 is given in Appendix A.

Theorem 6.2 says that the two diffraction patterns collected in the scheme of Figure 4 uniquely determine the two phase projections.

**Theorem 6.2.** *Let  $f, g \in O_n$  such that  $C_{\mathbf{t}, \mathbf{t}'} := L_{\mathbf{t}, \mathbf{t}'}(f) \cap L_{\mathbf{t}, \mathbf{t}'}(g)$  contains some  $(\mathbf{k}, \mathbf{k}') \neq 0$  such that the slope of either  $\mathbf{k}$  or  $\mathbf{k}'$  is not a fraction over  $\mathbb{Z}_p$ . Let the Mask Assumption hold true. Suppose that*

$$(42) \quad |\mathcal{F}(\mu \odot e^{i\kappa g_{\mathbf{t}'}^*})|^2 = |\mathcal{F}(\mu \odot e^{i\kappa f_{\mathbf{t}'}^*})|^2$$

$$(43) \quad |\mathcal{F}(\mu \odot e^{i\kappa g_{\mathbf{t}}^*})|^2 = |\mathcal{F}(\mu \odot e^{i\kappa f_{\mathbf{t}}^*})|^2.$$

*Then  $e^{i\kappa g_{\mathbf{t}}} = e^{i\kappa f_{\mathbf{t}}}$  and  $e^{i\kappa g_{\mathbf{t}'}} = e^{i\kappa f_{\mathbf{t}'}}$  almost surely.*

The proof of Theorem 6.2 is given in Appendix B.

**Corollary 6.3.** *If for each  $\mathbf{t} \in \mathcal{T}$  there is a  $\mathbf{t}' \in \mathcal{T}$  to satisfy Theorem 6.2, then  $e^{i\kappa g_{\mathbf{t}}} = e^{i\kappa f_{\mathbf{t}}}$  for all  $\mathbf{t} \in \mathcal{T}$ .*

Note that Theorem 6.1, 6.2 and Corollary 6.3 do not hold for a uniform mask ( $\mu = \text{cost}$ .) because the chiral ambiguity and the shift ambiguity are present, i.e. both  $g(\cdot) = f(-\cdot)$  and  $g(\cdot) = f(\cdot + \mathbf{l}), \mathbf{l} \in \mathbb{R}^3$ , satisfy all the assumptions therein but  $e^{i\kappa g_{\mathbf{t}}} \neq e^{i\kappa f_{\mathbf{t}}}$  in general.

## 7. REDUCTION WITH WEAK PHASE OBJECTS

Under the weak-phase-object assumption (5) the exit wave is given by

$$(44) \quad v_B(x, y) = 1 - \frac{i}{2\kappa} \int dz' f(x, y, z').$$

The coded diffraction pattern is given by

$$(45) \quad |\mathcal{F}(\mu \odot v_B)|^2 = |\mathcal{F}\mu|^2 + \frac{1}{\kappa} \Im\{\overline{\mathcal{F}\mu} \cdot \mathcal{F}(\mu \int f dz')\} + \frac{1}{4\kappa^2} |\mathcal{F}(\mu \int f dz')|^2$$

where  $\Im$  denotes the imaginary part.

As (45) represents the interference pattern between the reference wave  $\mathcal{F}(\mu)$  and the masked object wave  $-\mathcal{F}(\mu \int f dz')/(2\kappa)$ , reconstruction based on the second term on the right hand side of (45) can be performed by conventional holographic techniques [59, 88, 89].

We take the diffraction pattern of the scattered waves

$$(46) \quad |\mathcal{F}(\mu \odot f_{\mathbf{t}})|^2,$$

as measurement data, which is reminiscent of dark-field imaging in light and electron microscopies where the unscattered wave (i.e.  $\mathcal{F}\mu$ ) is removed from view [2, 33].

The following results are analogous to Theorem 6.1 and 6.2

Theorem 7.1 says that the two diffraction patterns collected in the scheme of Figure 3 uniquely determine the projection.

**Theorem 7.1.** *Let  $f, g \in O_n$  and the Mask Assumption hold true. Suppose that  $\text{supp}(f_{\mathbf{t}})$  is not a subset of a line and that*

$$(47) \quad |\mathcal{F}(g_{\mathbf{t}}^*)|^2 = |\mathcal{F}(f_{\mathbf{t}}^*)|^2$$

$$(48) \quad |\mathcal{F}(\mu \odot g_{\mathbf{t}}^*)|^2 = |\mathcal{F}(\mu \odot f_{\mathbf{t}}^*)|^2$$

*Then almost surely  $g_{\mathbf{t}} = e^{i\theta_{\mathbf{t}}} f_{\mathbf{t}}$  for some constant  $\theta_{\mathbf{t}} \in \mathbb{R}$ .*

The proof of Theorem 7.1 is given in Appendix C.

Theorem 7.2 says that the two diffraction patterns collected in the scheme of Figure 4 uniquely determine the two projections, modulo the isotropy ambiguity.

**Theorem 7.2.** *Let  $f, g \in O_n$  and suppose that  $\widehat{f}(0) \neq 0$ . Let the Mask Assumption hold true. Suppose that neither  $\text{supp}(f_{\mathbf{t}})$  nor  $\text{supp}(f_{\mathbf{t}'})$  is a subset of a line and that*

$$(49) \quad |\mathcal{F}(\mu \odot g_{\mathbf{t}'}^*)|^2 = |\mathcal{F}(\mu \odot f_{\mathbf{t}'}^*)|^2$$

$$(50) \quad |\mathcal{F}(\mu \odot g_{\mathbf{t}}^*)|^2 = |\mathcal{F}(\mu \odot f_{\mathbf{t}}^*)|^2$$

*where  $\mathbf{t}$  and  $\mathbf{t}'$  are not parallel to each other. Then almost surely*

$$(51) \quad \text{either } (g_{\mathbf{t}} = e^{i\theta_0} f_{\mathbf{t}} \ \& \ g_{\mathbf{t}'} = e^{i\theta_0} f_{\mathbf{t}'}) \ \text{or } f_{\mathbf{t}}^* = f_{\mathbf{t}'}^*,$$

*for some constant  $\theta_0 \in \mathbb{R}$  (the two in (51) may both be true).*

The condition  $\widehat{f}(0) \neq 0$  is missing in the statement of the theorem in [26]. The proof is corrected and further elaborated in Appendix D.

**Corollary 7.3.** *Let the assumptions of Theorem 7.2 hold for any two non-parallel  $\mathbf{t}, \mathbf{t}' \in \mathcal{T}$ . Then*

$$(52) \quad \text{either } (g_{\mathbf{t}} = e^{i\theta_0} f_{\mathbf{t}}, \quad \forall \mathbf{t} \in \mathcal{T}) \quad \text{or} \quad (f_{\mathbf{t}}^* = f_{\mathbf{t}'}^*, \quad \forall \mathbf{t}, \mathbf{t}' \in \mathcal{T})$$

where  $\theta_0$  is independent of  $\mathbf{t} \in \mathcal{T}$ .

*Proof.* First, let us make the following observation. Suppose  $g_{\mathbf{t}} = e^{i\theta_{\mathbf{t}}} f_{\mathbf{t}}$  and  $g_{\mathbf{t}'} = e^{i\theta_{\mathbf{t}'}} f_{\mathbf{t}'}$  for  $\mathbf{t} \neq \mathbf{t}'$ . By Proposition 4.1  $\widehat{f}_{\mathbf{t}}(0) = \widehat{f}_{\mathbf{t}'}(0) = \widehat{f}(0) \neq 0$ , it follows from  $\widehat{g}_{\mathbf{t}}(0) = \widehat{g}_{\mathbf{t}'}(0)$  that  $\theta_{\mathbf{t}} = \theta_{\mathbf{t}'}$ .

Consequently, let  $\mathcal{T}_1 \subseteq \mathcal{T}$  be the *maximum* set of all  $\mathbf{t} \in \mathcal{T}$  for which  $g_{\mathbf{t}} = e^{i\theta_0} f_{\mathbf{t}}$  for  $\theta_0 \in \mathbb{R}$  independent of  $\mathbf{t} \in \mathcal{T}$ . Note that the value of  $\theta_0$  is arbitrary. Since  $\mathcal{T}_1$  is maximal, it follows that  $g_{\mathbf{t}'} \neq e^{i\theta_0} f_{\mathbf{t}'}$  for any  $\mathbf{t}' \notin \mathcal{T}_1$ .

Suppose the first alternative in (52) is not true, i.e.  $\mathcal{T}_1 \neq \mathcal{T}$ . Consider any  $\mathbf{t}' \notin \mathcal{T}_1$  and  $\mathbf{t} \in \mathcal{T}_1$ . By Theorem 7.2,  $f_{\mathbf{t}}^* = f_{\mathbf{t}'}^*$ , implying the second alternative in (52). □

**7.1. Sector constraint.** The X-ray spectrum generally lies to the high-frequency side of various resonances associated with the binding of electrons so the complex refractive index can be written as

$$(53) \quad n = 1 - \delta + i\beta, \quad 0 < \delta, \beta \ll 1,$$

where  $\delta$  and  $\beta$ , respectively, describe the dispersive and absorptive aspects of the wave-matter interaction. The component  $\beta$  is usually much smaller than  $\delta$  which is often of the order of  $10^{-5}$  for X-rays [53, 70].

By (4) and (53),

$$(54) \quad f = \frac{1}{2}(n^2 - 1) \approx -\delta + i\beta$$

and hence  $f$  satisfies the so called sector condition introduced in [25], i.e. the phase angle  $\angle f(\mathbf{n})$  of  $f_{\mathbf{t}}(\mathbf{n})$  for each  $\mathbf{n}$  satisfies

$$(55) \quad \angle f(\mathbf{n}) \in [a, b], \quad |a - b| < 2\pi,$$

where  $a$  and  $b$  are two constants independent of  $\mathbf{n}$ . For example, for  $\beta \geq 0$ ,  $a = 0$  and  $b = \pi$ . In particular, if  $\beta \ll \delta > 0$ , then  $a \approx \pi$  and  $b = \pi$ . The sector condition is a generalization of the constraint of positivity (of electron density) which is the cornerstone of the “direct methods” in X-ray crystallography [42].

In view of (27), the continuous interpolation  $\widetilde{f}$  in (14) satisfies the sector condition

$$(56) \quad \angle \widetilde{f}(\mathbf{n}) \in [\widetilde{a}, \widetilde{b}] \quad (\widetilde{a} \approx a, \quad \widetilde{b} \approx b, \quad p \gg 1).$$

If  $|\widetilde{b} - \widetilde{a}| \leq \pi$ , the sector (56) is a convex set and hence the discrete projections (16)-(18) also satisfy the section condition (56).

The sector condition (55) enables reduction from a single coded diffraction pattern.

**Theorem 7.4.** [25] *Let  $f \in O_n$  with the singleton  $\mathcal{T} = \{\mathbf{t}\}$  for any  $\mathbf{t}$  such that the sector condition (56) is convex (i.e.  $|\tilde{b} - \tilde{a}| \leq \pi$ ). Consider a random phase mask  $\mu(\mathbf{n}) = \exp[i\phi(\mathbf{n})]$  with independent uniform random variables  $\phi(\mathbf{n})$  over  $[0, 2\pi]$ . Suppose that  $\text{supp}(f_{\mathbf{t}})$  is not a subset of a line and that for  $g \in O_n$ ,  $g_{\mathbf{t}}^*$  produces the same coded diffraction pattern as  $f_{\mathbf{t}}^*$ . Then with probability at least*

$$(57) \quad 1 - n^2 \left| \frac{\tilde{b} - \tilde{a}}{2\pi} \right|^{\lfloor S_{\mathbf{t}}/2 \rfloor} \geq 1 - n^2 2^{-\lfloor S_{\mathbf{t}}/2 \rfloor},$$

where  $S_{\mathbf{t}}$  is the number of nonzero pixels of  $f_{\mathbf{t}}$ , we have  $g_{\mathbf{t}} = e^{i\theta_{\mathbf{t}}} f_{\mathbf{t}}$  for some constant  $\theta_{\mathbf{t}} \in \mathbb{R}$ .

If  $|\mathcal{T}| > 1$  and if the mask functions for different  $\mathbf{t} \in \mathcal{T}$  are independently distributed, then the probability for Theorem 7.4 to hold for all  $\mathbf{t} \in \mathcal{T}$  is at least

$$\prod_{\mathbf{t} \in \mathcal{T}} \left( 1 - n^2 \left| \frac{\tilde{b} - \tilde{a}}{2\pi} \right|^{\lfloor S_{\mathbf{t}}/2 \rfloor} \right).$$

For the sake of simplicity in measurement, however, let  $\mu$  be the same mask for all  $\mathbf{t} \in \mathcal{T}$ . The probability for Theorem 7.4 to hold for all  $\mathbf{t} \in \mathcal{T}$  can be roughly estimated as follows.

First note that for any two events  $A$  and  $B$ ,

$$(58) \quad P(A \cap B) = P(A) + P(B) - P(A \cup B) \geq P(A) + P(B) - 1,$$

where  $P(\cdot)$  is the probability of the respective event. Let  $\mathcal{T} = \{\mathbf{t}_j : j = 1, \dots, m\}$ ,  $E_j$  be the event that Theorem 7.4 to hold for  $\mathbf{t}_j$  and  $p_j = P(E_j)$ . By Theorem 7.4,  $p_j \geq 1 - c_j$  where

$$c_j = n^2 \left| \frac{\tilde{b} - \tilde{a}}{2\pi} \right|^{\lfloor S_{\mathbf{t}_j}/2 \rfloor},$$

and, hence by (58),

$$(59) \quad P(E_1 \cap E_2) \geq p_1 + p_2 - 1 \geq 1 - 2c, \quad c = \max_j c_j.$$

Iterating the bound (58) inductively with  $E_j, j = 1, \dots, m$ , we obtain

$$P(\cap_{i=1}^m E_i) = P(\cap_{i=1}^{m-1} E_i \cap E_m) \geq 1 - (m-1)c - c = 1 - mc.$$

**Corollary 7.5.** *Suppose  $\hat{f}(0) \neq 0$ . Theorem 7.4 holds true for  $\mathbf{t}$  with the same constant  $\theta_{\mathbf{t}} = \theta_0 \in \mathbb{R}$  independent of  $\mathbf{t}$  in any  $\mathcal{T}$  with probability at least*

$$(60) \quad 1 - |\mathcal{T}| n^2 \left| \frac{\tilde{b} - \tilde{a}}{2\pi} \right|^{s/2}, \quad s := \min_j S_{\mathbf{t}_j},$$

where  $s$  is the minimum sparsity (the least number of nonzero pixels) in all directions in  $\mathcal{T}$ .

*Proof.* By Proposition 4.1  $\widehat{f}_{\mathbf{t}}(0) = \widehat{f}_{\mathbf{t}'}(0) = \widehat{f}(0) \neq 0$ , it follows from  $\widehat{g}_{\mathbf{t}}(0) = \widehat{g}_{\mathbf{t}'}(0)$  that  $\theta_{\mathbf{t}} = \theta_{\mathbf{t}'}$ . Namely,  $g_{\mathbf{t}} = e^{i\theta_0} f_{\mathbf{t}}$  for some constant  $\theta_0$  independent of  $\mathbf{t} \in \mathcal{T}$ .

The proof is complete.  $\square$

The bound (60) is meaningful only if

$$(61) \quad |\mathcal{T}| < n^{-2} \left| \frac{\tilde{b} - \tilde{a}}{2\pi} \right|^{-s/2}.$$

Usually  $s$  is at least a multiple of  $n$  (often  $\mathcal{O}(n^2)$ ), (61) allows nearly exponentially large number of projections. As we will see in Corollary 10.3 (ii), a far smaller number  $m = n$  of projections suffices for unique determination of a weak phase object.

Note that Theorem 7.1, 7.2, 7.4, Corollary 6.3 and 7.5 do not hold for a uniform mask ( $\mu = \text{cost.}$ ) because the chiral ambiguity and the shift ambiguity are present, i.e. both  $g(\cdot) = f(-\cdot)$  and  $g(\cdot) = f(\cdot + \mathbf{I}), \mathbf{I} \in \mathbb{Z}^3$ , satisfy all the assumptions therein but  $g_{\mathbf{t}} \neq e^{i\theta_{\mathbf{t}}} f_{\mathbf{t}}$  in general.

## 8. PHASE UNWRAPPING

For a strong phase object, (37) naturally leads to the problem of phase unwrapping:

$$(62) \quad g_{\mathbf{t}}(\mathbf{n}) = f_{\mathbf{t}}(\mathbf{n}) \quad \text{mod } 2\pi/\kappa, \quad \mathbf{n} \in \mathbb{Z}_p^2,$$

which may have infinitely many solutions. We seek conditions on  $\mathcal{T}$  that can uniquely determine the 3D object in the sense that  $g \equiv f$ .

A basic approach appeals to the continuity of the projection's dependence on the direction  $\mathbf{t}$ , which, in turn, is the consequence of continuous interpolation (14).

Let  $\mathcal{T}_\epsilon$  denote the graph with the nodes given by  $\mathbf{t} \in \mathcal{T}$  and the edges defined between any two nodes  $\mathbf{t}_1, \mathbf{t}_2 \in \mathcal{T}$  with  $|\angle \mathbf{t}_1 \mathbf{t}_2| \leq \epsilon$  (such edges are called  $\epsilon$ -edges) where  $\angle \mathbf{t}_1 \mathbf{t}_2$  is the angle between  $\mathbf{t}_1$  and  $\mathbf{t}_2$ . We call  $\mathcal{T}$  is  $\epsilon$ -connected if  $\mathcal{T}_\epsilon$  is a connected graph. We say that two nodes  $\mathbf{t}_1, \mathbf{t}_2$  are  $\epsilon$ -connected if there is an  $\epsilon$ -edge between them.

Suppose that  $\mathcal{T}$  is  $\epsilon$ -connected for certain  $\epsilon$  (to be determined later). The continuous dependence of  $g_{\mathbf{t}}, f_{\mathbf{t}}$  on  $\mathbf{t}$  implies that  $|g_{\mathbf{t}_1} - g_{\mathbf{t}_2}|$  and  $|f_{\mathbf{t}_1} - f_{\mathbf{t}_2}|$  are arbitrarily small if  $\angle \mathbf{t}_1 \mathbf{t}_2$  is sufficiently small. On the other hand,  $h_{\mathbf{t}_1} - h_{\mathbf{t}_2}$  is an integer multiple of  $2\pi/\kappa$  where  $h_{\mathbf{t}} := g_{\mathbf{t}} - f_{\mathbf{t}}$ . Then for sufficiently small  $\epsilon$ ,  $h_{\mathbf{t}}(\mathbf{n})$  is a constant for each  $\mathbf{n}$  and hence  $g_{\mathbf{t}} - f_{\mathbf{t}}$  is independent of  $\mathbf{t}$ .

We can give a rough estimate for the required closeness  $\epsilon$  of two adjacent projections as follows. In general, the gradient of the continuous extension  $\tilde{f}$  is  $\mathcal{O}(1)$  and hence the gradient of  $f_{\mathbf{t}}$  (being a sum of  $n$  values of  $f$ ) with respect to  $\mathbf{t}$  is  $\mathcal{O}(n)$ . Consequently,  $|f_{\mathbf{t}_1} - f_{\mathbf{t}_2}|$  can be made sufficiently small with  $\epsilon = \mathcal{O}(1/n)$  (with a sufficiently small constant).

As pointed out at the beginning of Section 4, if we make use of the property that the fractional variation of  $f$  between adjacent grids is negligible, then the gradient of the continuous extension  $\tilde{f}$  is  $o(1)$  and  $|f_{\mathbf{t}_1} - f_{\mathbf{t}_2}|$  can be made sufficiently small with  $\epsilon$  that may be much larger than  $1/n$ .



The following is the main result of this section.

**Theorem 8.1.** *Let  $\mathcal{T}$  be an  $\epsilon$ -connected set of directions containing any of the following three sets:*

$$(63) \quad \{(1, \alpha_l, \beta_l) : l = 1, \dots, n\} \cup \{(0, \alpha_0, \beta_0), (0, 0, 1)\}$$

$$(64) \quad \{(\beta_l, 1, \alpha_l) : l = 1, \dots, n\} \cup \{(\beta_0, 0, \alpha_0), (1, 0, 0)\}$$

$$(65) \quad \{(\alpha_l, \beta_l, 1) : l = 1, \dots, n\} \cup \{(\alpha_0, \beta_0, 0), (0, 1, 0)\}$$

with the property that  $\alpha_0 \neq 0, |\beta_0| < 1$  and

$$(66) \quad \{\alpha_l \xi + \beta_l \eta : |\alpha_l|, |\beta_l| < 1, l = 1, \dots, n\} \text{ has } n \text{ distinct elements for each } (\xi, \eta) \neq (0, 0).$$

Suppose that the maximum variation of the object  $f$  between two adjacent grid points is less than  $\pi/\kappa$  (The 3D Itoh condition) and (37) holds for a sufficiently small  $\epsilon = \mathcal{O}(1/n)$ . Then  $g = f$ .

**Remark 8.2.** *As per the discussion in Section 4, with  $\lambda/2$  as the unit of length,  $\pi/\kappa = 1$ .*

*The projection  $f_{\mathbf{t}}$  in a direction  $\mathbf{t}$ , however, usually violates the 2D Itoh condition. Hence 2D phase unwrapping for  $f_{\mathbf{t}}$  may not have a unique solution [37, 52].*

**Remark 8.3.** *As shown in the following proof, the  $x, y$  and  $z$  axes in (63), (64) and (65), respectively, show up in the analysis because they are “privileged” w.r.t.  $\mathbb{Z}_n^3$  which is not isotropic. On the other hand, due to arbitrariness in choosing the orientation of the object frame, we can always designate one of the projection directions in  $\mathcal{T}$  as exactly one of the coordinate axes, say,  $(0, 0, 1)$ , and discretize the object domain into  $\mathbb{Z}_n^3$  accordingly.*

*Proof.* It suffices to consider the case that  $\mathcal{T}$  contains the set (63).

Let (62) hold true. Then the  $\epsilon$ -connected schemes with sufficiently small  $\epsilon$  ensure

$$h_{\mathbf{t}}(\mathbf{n}) := g_{\mathbf{t}}(\mathbf{n}) - f_{\mathbf{t}}(\mathbf{n}) \quad \text{is independent of } \mathbf{t} \in \mathcal{T}.$$

Intuitively, with sufficiently diverse views in  $\mathcal{T}$ ,  $h := g - f$  must be a multiple of Kronecker’s delta function as shown in the following analysis.

Let  $c(\cdot, \cdot)$  be independent of  $\alpha_l, \beta_l$ , such that

$$(67) \quad \widehat{h}_{(1, \alpha_l, \beta_l)}(\eta, \zeta) = c(\eta, \zeta)$$

and hence by Fourier Slice Theorem

$$(68) \quad \widehat{h}(-\alpha_l \eta - \beta_l \zeta, \eta, \zeta) = c(\eta, \zeta)$$

for all  $\eta, \zeta \in \mathbb{Z}$ . We want to show  $c \equiv 0$ .

Let

$$(69) \quad \widehat{h}(\xi, \eta, \zeta) = \sum_m \widehat{h}_{\eta\zeta}(m) e^{-2\pi i m \xi / p}$$

with

$$(70) \quad \widehat{h}_{\eta\zeta}(m) = \sum_l \widehat{h}_{\eta}(m, l) e^{-2\pi i l \zeta / p}$$

and

$$(71) \quad \widehat{h}_\eta(m, l) = \sum_k h(m, k, l) e^{-2\pi i k \eta / p}.$$

By the support constraint  $\text{supp}(h) \subseteq \mathbb{Z}_n^3$ , (68)-(69) becomes the  $n \times n$  Vandermonde system

$$(72) \quad V \widehat{h}_{\eta\zeta} = c(\eta, \zeta) \mathbb{1}$$

with the all-one vector  $\mathbb{1}$  and

$$(73) \quad V = [V_{ij}], \quad V_{ij} = e^{-2\pi i \xi_i j / p}, \quad \xi_i = -\alpha_i \eta - \beta_i \zeta$$

for  $\{\alpha_i, \beta_i : i = 1, \dots, n\}$ . The Vandermonde system is nonsingular if and only if  $\{\xi_i : i = 1, \dots, n\}$  has  $n$  distinct members.

Since the system (72) has a unique solution, we identify  $\widehat{h}_{\eta\zeta}(\cdot)$  as

$$\widehat{h}_{\eta\zeta}(\cdot) = c(\eta, \zeta) \delta(\cdot).$$

For  $m \neq 0$ ,  $\widehat{h}_{\eta\zeta}(m) = 0$  for all  $\eta, \zeta \in \mathbb{Z}$  and hence  $\widehat{h}_\eta(m, l) = 0$  for all  $l$  and  $m \neq 0$ . Likewise for (71), we select  $n$  distinct values of  $\eta$  to perform inversion of the Vandermonde system and obtain

$$(74) \quad h(m, k, l) = 0, \quad m \neq 0.$$

In other words,  $h$  is supported on the  $(y, z)$  plane. Consequently the projection of  $h$  in the direction of  $(0, \alpha_0, \beta_0)$ , with  $\alpha_0 \neq 0$ , would be part of a line segment and, hence by the assumption of  $h_{\mathbf{t}}$ 's independence of  $\mathbf{t} \in \mathcal{T}$ ,  $h_{\mathbf{t}}$  is also a line object for all  $\mathbf{t} \in \mathcal{T}$ .

That is to say,  $h$  is supported on the  $z$ -axis. Now that  $(0, 0, 1) \in \mathcal{T}$ , the projection of  $h$  in  $(0, 0, 1)$  is Kronecker's delta function  $\delta$  at the origin,  $h_{\mathbf{t}}$ 's independence of  $\mathbf{t}$  implies that for some  $q \in \mathbb{Z}$ ,

$$(75) \quad g(\mathbf{n}) - f(\mathbf{n}) = \frac{2\pi}{\kappa} q \delta(\mathbf{n})$$

where  $\delta$  is Kronecker's delta function on  $\mathbb{Z}^3$ .

The ambiguity on the right hand side of (75) can be further eliminated by limiting the maximum variation of the object between two adjacent grid points to less than  $\pi/\kappa$ , the so called Itoh condition [52]. This can be seen as follows: If both  $g$  and  $f$  satisfy Itoh's condition as well as  $g(\mathbf{n}) - f(\mathbf{n}) = 0$  for  $\mathbf{n} \neq 0$ , then  $|g - f| < 2\pi/\kappa$  at the origin, implying  $q = 0$  in (75). The proof is complete. □

In view of Theorem 6.1, 6.2 and 8.1, we have the following uniqueness results for 3D phase retrieval with a strong phase object.

**Corollary 8.4.** *Let  $\mathcal{T}$  be a  $\epsilon$ -connected set of directions in Theorem 8.1 for a sufficiently small  $\epsilon = \mathcal{O}(1/n)$  satisfying (66). Consider the class of objects in  $O_n$  with the maximum variation between two adjacent grid points less than  $\pi/\kappa$ .*

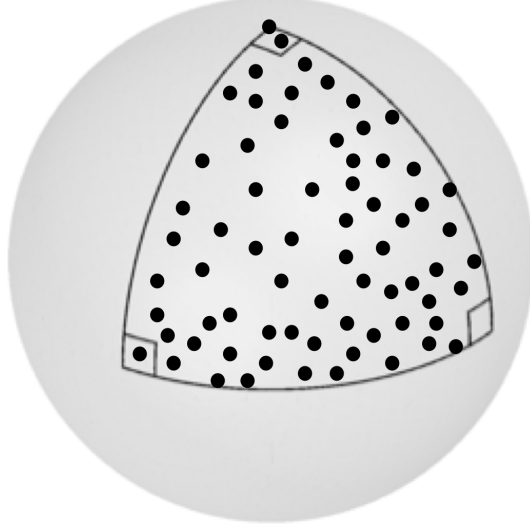


FIGURE 6. Unit sphere representing all directions in the object frame. A sufficiently large set of randomly selected points from the spherical triangle (or a larger one) contain the scheme (63) and satisfy the conditions in Theorem 8.1. Since  $\epsilon = \mathcal{O}(1/n)$  with a small constant,  $|\mathcal{T}|$  is at least a large multiple of  $n$ .

(i) Under the setting of Theorem 6.1, the pairs of coded and uncoded diffraction patterns corresponding to  $\mathbf{t} \in \mathcal{T}$  uniquely determine the strong phase object almost surely .

(ii) Under the setting of Corollary 6.3, the coded diffraction patterns corresponding to  $\mathcal{T}$  uniquely determine the strong phase object almost surely.

## 9. TILT SCHEMES FOR PHASE UNWRAPPING

In this section, we consider a few examples as applications of Theorem 8.1 and Corollary 8.4.

9.1. **Random tilt.** We can satisfy condition (66) with overwhelming probability by randomly and independently selecting  $n$  pairs of  $(\alpha_l, \beta_l)$  that are distributed with probability density function bounded away from 0 and  $\infty$  over any square contained in  $[0, 1]^2$  (see [6]).

In the case of (63) with  $\alpha_l, \beta_l \in [0, 1)$ , for instance, this random tilt series is distributed over the spherical rectangle of azimuth range  $[0, \pi/4)$  and polar angle range  $(\pi/4, \pi/2]$ . We can enlarge the random sampling area from this spherical rectangle to the spherical triangle shown in Figure 6. If the sampling is sufficiently dense, then the whole scheme would include the direction  $(0, 1, \beta_0)$ , for some  $\beta_0 \in (0, 1)$ , and  $\epsilon$ -connect to  $(0, 0, 1)$  (which is included by assumption),

More generally, the conditions of Theorem 8.1 are satisfied by any tilt series of sufficiently dense sampling from a spherical triangle with vertexes in three orthogonal directions (cf. Remark 8.3).

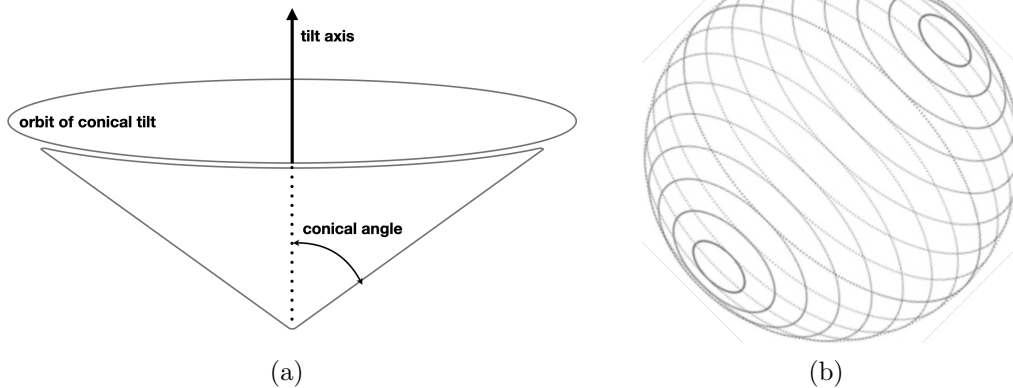


FIGURE 7. (a) Conical tilt geometry; (b) Conical tilt orbits of various conical angles about an axis of obliquity. A single-axis tilt orbit is a great circle, corresponding to a conical angle  $\pi/2$ , which can not uniquely unwrap phase.

Random schemes arise naturally in single-particle imaging. On the other hand, deterministic tilt schemes are often employed in tomography.

**9.2. Deterministic tilt.** First, the single-axis tilting (with the conical angle  $\pi/2$ ) is not covered by Theorem 8.1 and contains certain blindspot as exhibited in the proof, i.e. it can not completely resolve the ambiguities in phase unwrapping.

Second, certain combinations of (63), (64), (65), can be made  $\epsilon$ -connected (for sufficiently small  $\epsilon$ ) in the following scheme:

$$(76) \quad \mathcal{T} = \left\{ \left(1, \frac{l}{q}, \alpha\right) : l = 0, \dots, q \right\} \cup \left\{ \left(\frac{l}{q}, 1, \alpha\right) : l = 0, \dots, q \right\} \\ \cup \left\{ \left(0, 1, \frac{l}{q}\right) : l = 0, \dots, q \right\} \cup \left\{ \left(0, \frac{l}{q}, 1\right) : l = 0, \dots, q \right\}, \quad q \in \mathbb{N}$$

with a fixed  $\alpha \in [0, 1)$ , where the first subset is from (63), the second and third from (64) and the fourth from (65). In the limit of  $q \rightarrow \infty$ , the scheme (76) has a continuous limit which can be illustrated more concretely in terms of the spherical polar coordinates as in the following example.

**Example 9.1.** The continuous limit of (76) consists of two circular arcs. The first arc, the limit of the first and second subsets in (76), going from  $(1, 0, \alpha)$  to  $(1, 1, \alpha)$  and to  $(0, 1, \alpha)$ , is parametrized by the azimuthal angle  $\phi_z \in [0, \pi/2]$ , at the polar angle  $\theta_z = \arccot(\alpha) > \pi/4$  (since  $\alpha \in [0, 1)$ ) w.r.t. the polar axis  $z$ . The second arc, the limit of the third and fourth subsets in (76), going from  $(0, 1, \alpha)$  to  $(0, 1, 1)$  and to  $(0, 0, 1)$ , is parametrized by the azimuthal angle  $\phi_x \in [\arctan(\alpha), \pi/2]$ , at the polar angle  $\theta_x = \pi/2$  w.r.t. the polar axis  $x$ .

In other words, the continuous limit of (76) is an union of a conical tilting (the first arc) of range  $\pi/2$  at the conical angle  $\arccot(\alpha)$  and an orthogonal single-axis tilting (the second arc) of range  $\arccot(\alpha)$ .

For  $\alpha = 0$ , the scheme is an orthogonal dual-axis tilting of a tilt range  $\pi/2$  for each axis [72]. The total length of the orbit is  $\pi$ .  $\square$

Note that the total radiation dose is proportional to the number of projections, which is  $\mathcal{O}(n)$  with a large constant (since  $\epsilon = \mathcal{O}(1/n)$  with a small constant), and, as  $n \rightarrow \infty$ , proportional to the orbit's total length on the unit sphere.

More conveniently, instead of being split into a conical tilting and a single-axis tilting as in (76), the schemes in Theorem 8.1 can be implemented as a single conical tilting (Figure 7) which has a smooth circular orbit, instead of a broken one.

**Example 9.2.** Let  $(1, 0, 0)$  and  $(0, 0, 1)$ , respectively, be the start and the end of the orbit, with the midpoint  $(0, 1, 0)$ . Any three directions of the conical tilt uniquely determine the direction of the tilt axis,  $(1, 1, 1)$ , with the conical angle,  $\arccos(1/\sqrt{3}) \approx 54.7^\circ$ , and the tilt range,  $4\pi/3$ . The total length of the orbit is  $\frac{4\pi}{9}\sqrt{10 - 2\sqrt{3}} \approx 3.57$  which is slightly larger than the length  $\pi$  in Example 9.1 for  $\alpha = 0$ .

The conical tilt going through  $(1, 0, \alpha)$ ,  $(0, 1, \alpha)$  and  $(0, 0, 1)$  can be similarly constructed. We leave the details to the interested reader.  $\square$

## 10. UNIQUENESS WITH WEAK PHASE OBJECTS

In this section we show that for weak phase objects, much less restrictive schemes than those of Theorem 8.1 guarantee uniqueness of solution to 3D phase retrieval.

The following is the uniqueness result for discrete projection tomography.

**Theorem 10.1.** *Let  $\mathcal{T}$  be any one of the following sets:*

$$(77) \quad \{(1, \alpha_l, \beta_l) : l = 1, \dots, n\}$$

$$(78) \quad \{(\alpha_l, 1, \beta_l) : l = 1, \dots, n\}$$

$$(79) \quad \{(\alpha_l, \beta_l, 1) : l = 1, \dots, n\}$$

*under the condition (66). Suppose that  $g_{\mathbf{t}} = e^{i\theta_0} f_{\mathbf{t}}$ , for some constant  $\theta_0 \in \mathbb{R}$ , independent of  $\mathbf{t} \in \mathcal{T}$ . Then  $g = e^{i\theta_0} f$ .*

**Remark 10.2.** *Theorem 10.1 is the finite, discrete counterpart of the classical result that a compactly supported function is uniquely determined by the projections in any infinite set of directions ([43], proposition 7.8).*

*Proof.* To fix the idea, consider the case (79) for  $\mathcal{T}$ . By the discrete Fourier slice theorem, we have

$$(80) \quad \widehat{g}(\xi, \eta, -\alpha_l \xi - \beta_l \eta) = e^{i\theta_0} \widehat{f}(\xi, \eta, -\alpha_l \xi - \beta_l \eta), \quad l = 1, \dots, n, \quad \xi, \eta \in \mathbb{Z}.$$

In other words, for each  $\xi, \eta \in \mathbb{Z}$ , the corresponding partial Fourier transforms defined in (69) satisfy

$$(81) \quad \sum_{m \in \mathbb{Z}_n} (\widehat{g}_{\xi\eta}(m) - e^{i\theta_0} \widehat{f}_{\xi\eta}(m)) e^{-i2\pi m(-\alpha_l \xi - \beta_l \eta)/p} = 0, \quad l = 1, \dots, n$$

in terms of the notation for partial Fourier transforms in the proof of Theorem 8.1. For each  $\xi, \eta$ , (81) is a Vandermonde system which is nonsingular if and only if (66) holds. This implies that

$$\widehat{g}_{\xi\eta}(m) = e^{i\theta_0} \widehat{f}_{\xi\eta}(m), \quad m \in \mathbb{Z}_p, \quad \forall \xi, \eta \in \mathbb{Z}.$$

Therefore,  $g = e^{i\theta_0} f$  as asserted.  $\square$

It may be interesting to compare Theorem 10.1 with Crowther's rough estimate

$$(82) \quad N = \frac{\pi}{2} n$$

for the number  $N$  of projections needed for projection tomography with a single-axis tilting of tilt range  $\pi$  ([53], eq. (8.3)).

We have the following uniqueness results for 3D phase retrieval with a weak phase object.

**Corollary 10.3.** *Let  $\mathcal{T}$  be any one of the direction sets in Theorem 10.1.*

- (i) *Under the setting of Theorem 7.1, the  $n$  pairs of coded and uncoded diffraction patterns corresponding to  $\mathcal{T}$  uniquely determine the weak phase object almost surely.*
- (ii) *Under the setting of Corollary 7.5, the  $n$  coded diffraction patterns corresponding to  $\mathcal{T}$  uniquely determine the weak phase object with high probability (for  $n \gg 1$ ).*

In contrast to Corollary 10.3 (ii), the setting of Corollary 7.3 requires an extra coded diffraction pattern to remove the isotropy ambiguity.

**Theorem 10.4.** [26] *Let  $\mathcal{T}$  be any one of the following direction sets*

$$(83) \quad \{(1, \alpha_l, \beta_l) : l = 1, \dots, n\} \cup \{(0, \alpha_0, \beta_0)\}$$

$$(84) \quad \{(\alpha_l, 1, \beta_l) : l = 1, \dots, n\} \cup \{(\alpha_0, 0, \beta_0)\}$$

$$(85) \quad \{(\alpha_l, \beta_l, 1) : l = 1, \dots, n\} \cup \{(\alpha_0, \beta_0, 0)\}$$

*under the condition (66) and  $(\alpha_0, \beta_0) \neq (0, 0)$ . Then in the setting of Corollary 7.3,  $g = e^{i\theta_0} f$  for some constant  $\theta_0 \in \mathbb{R}$  almost surely.*

*Proof.* To rule out the second alternative in Corollary 7.3 that  $f_{\mathbf{t}}^* = f_{\mathbf{t}'}^*, \forall \mathbf{t}, \mathbf{t}' \in \mathcal{T}$ , define  $h_{\mathbf{t}} := f_{\mathbf{t}}^*$  which is independent of  $\mathbf{t} \in \mathcal{T}$ . Now applying the analysis in the proof of Theorem 8.1 to this  $h_{\mathbf{t}}$  for the scheme, e.g. (83). The argument up to (74) leads to the conclusion that the projection of  $h$  in the direction of  $(0, \alpha_0, \beta_0)$ , with  $\alpha_0 \neq 0$ , is part of a line segment and hence  $h_{\mathbf{t}}$  is a line object for all  $\mathbf{t} \in \mathcal{T}$ . This violates the assumption in Corollary 7.3 that no projection is part of a line. This implies that the first alternative of Corollary 7.3 holds, i.e.  $g_{\mathbf{t}} = e^{i\theta_0} f_{\mathbf{t}}, \quad \forall \mathbf{t} \in \mathcal{T}$ .  $\square$

## 11. NOISE ROBUSTNESS

Let us turn to the shot noise issue not addressed by the preceding uniqueness results. At present, there are few theoretical results on noise robustness in phase retrieval except for simplified models [24].

In practice, noise stability has as much to do with the reconstruction method as the information content of the given dataset. However, assessing and optimizing algorithms for 3D reconstruction from a large number of snapshots is by itself a challenging ongoing task [71]. Herein, we limit ourselves to the question of noise stability in reconstructing the *single* projection data from one (Theorem 7.4) or two (Theorem 7.2) diffraction patterns, for which the corresponding 2D phase retrieval algorithms have been well analyzed (cf. [29] and references therein).

Many of these algorithms are based on the real-space projection  $\mathcal{P}_1$  and the data-constrained projection  $\mathcal{P}_2$ .

With two diffraction patterns,  $\mathcal{P}_1 = AA^\dagger$  where  $A^\dagger$  is the pseudo-inverse of the measurement matrix

$$(86) \quad A = \begin{bmatrix} \Phi \operatorname{diag}\{\mu\} \\ \Phi \end{bmatrix}, \quad \Phi = (2p-1)^2 \times n^2 \text{ oversampled Fourier matrix (33).}$$

and

$$(87) \quad \mathcal{P}_2 z = \sqrt{d} \odot \operatorname{sgn}(z),$$

for all  $z \in \mathbb{C}^{2(2p-1)^2}$ , where  $\operatorname{sgn}(z)$  is the phase factor vector of  $z$  and  $d$  the concatenated coded and uncoded diffraction patterns.

With a single coded diffraction pattern,  $\mathcal{P}_2$  is the same as (87) with the vectorized coded diffraction pattern  $d$  but  $\mathcal{P}_1$  is changed to

$$(88) \quad \mathcal{P}_1 = AA^\dagger \mathcal{P}_0, \quad A = \Phi \operatorname{diag}\{\mu\}, \quad \mathcal{P}_0 = \text{projection onto the constraint (55) [27].}$$

The simplest among these is Alternating Projection (AP) (also known as Error-Reduction [32] or Gerchberg-Saxton [36] algorithm) which iterates  $\mathcal{P}_1$  and  $\mathcal{P}_2$  alternately.

AP with (86)-(87) is referred to as the Parallel AP (PAP) to emphasize the parallel treatment of the two diffraction patterns. Alternatively, the two diffraction patterns can be utilized in serially, resulting in the Serial AP (SAP) [15]. SAP usually has a faster convergence rate but lower robustness to noise than PAP (Figure 8(b)).

From the optimization perspective, AP is the gradient descent with unit step size for

$$(89) \quad \hat{f} := \arg \min_{g \in \mathcal{O}_n} \|\sqrt{d} - |Ag|\|$$

for weak phase objects. For comparison, the *Wirtinger Flow* (WF) is the gradient descent method with an adjustable step size for

$$(90) \quad \hat{f} := \arg \min_{g \in \mathcal{O}_n} \|d - |Ag|^2\|$$

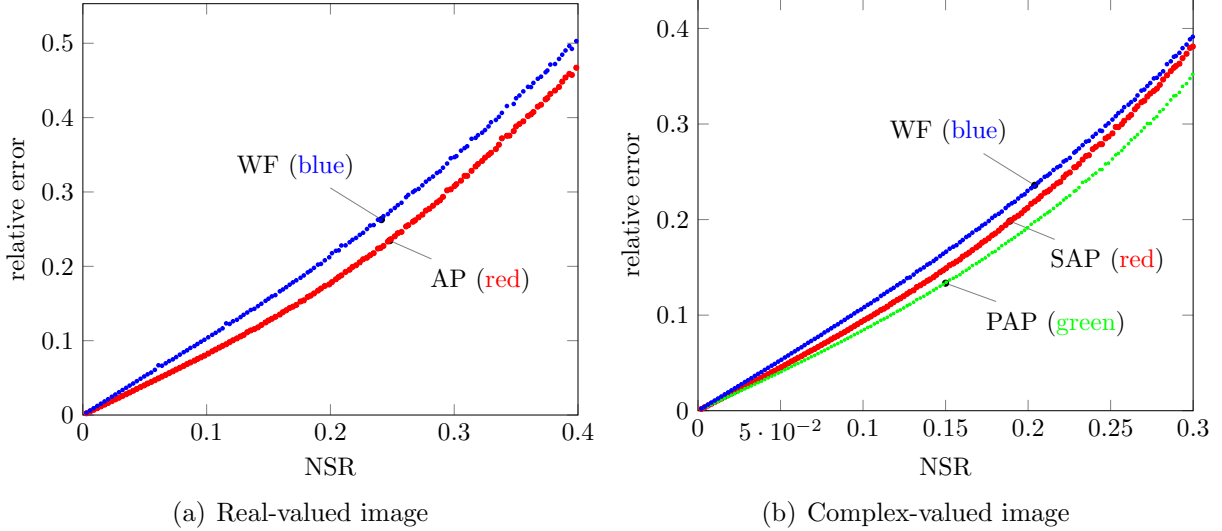


FIGURE 8. Relative reconstruction error of (a) the Cameraman from a single diffraction pattern and (b) RSCB from two diffraction patterns with Poisson noise at various NSR.

which is analytically smoother than (89) [11]. Weak phase objects are usually less favorable than strong phase objects for reconstruction because of the possibilities of vanishing pixels and loose supports.

The following noisy reconstruction shows that the relative reconstruction error  $\|\hat{f} - f\|/\|f\|$  is proportional to the noise level in the data with a noise amplification factor slightly above 1 which is not far from optimal (in the absence of additional prior information), even with simple algorithms such as AP and WF. The convergence rate, however, can be much improved by using more sophisticated algorithms (see [30], [29] and references therein).

For a single diffraction pattern simulation, we use the  $256 \times 256$  real-valued Cameraman image  $C$  as the projected object which satisfies the sector constraint with  $a = b$ . For a complex-valued object violating the sector condition (55), let  $B$  denote the  $256 \times 256$  real-valued Barbara image and define the Randomly Signed Cameraman-Barbara (RSCB) by

$$(91) \quad \beta_R(\mathbf{n}) \odot C(\mathbf{n}) + i\beta_I(\mathbf{n}) \odot B(\mathbf{n})$$

where  $\beta_R(\mathbf{n})$  and  $\beta_I(\mathbf{n})$  are i.i.d. Bernoulli random variables  $\pm 1$ .

We add the independent Poisson noise to the coded and uncoded diffraction patterns at various noise to signal ratios (NSR). Without assuming any additional information, each reconstruction is seeded with the 1-bit initialization method that can effectively prevent numerical stagnation [14, 15].

Figure 8 shows that the relative reconstruction error to NSR ratio is slightly above 1. We did not pursue larger NSR than shown because the relative error as figure of merit becomes less relevant as at higher NSR as reconstruction of large relative error can still have informative features that are useful for tomography. When applicable, various sparsity priors can enhance numerical reconstruction's robustness to noise [8, 49, 64, 77, 78]. Finally, the coded aperture



itself needs not be known in advance and can be simultaneously calibrated by effective algorithms [28].

## 12. CONCLUSIONS AND DISCUSSION

Since it is easier to mitigate measurement uncertainties with projection data than diffraction data, the proposed schemes are designed to reconstruct the projection dataset without the prior knowledge of relative orientations and locations of different snapshots (see [13, 17, 62, 63, 69] for other uncertainties in X-ray and electron experiments with small-sized objects such as nano-crystals and macromolecules).

While the schemes in Theorem 6.1, 7.1 and 7.4 are numerically effective and stable (Section 11), the schemes in Theorem 6.2 and 7.2 are expected to be less so in view of the fact that the information overlap between projections in two directions is just a line in the Fourier domain (the common line). The remedy would be to include more than two directions in the reconstruction of (phase) projections. How many directions are necessary? Theorem 10.4 suggests that the answer is  $n + 1$  directions.

With the schemes in Theorem 7.1 and 7.4 for a weak phase object, classification and alignment can then be carried out with single-particle cryo-EM methods such as the common-line methods [21, 82, 84], the maximum-likelihood methods [61, 81] and the Bayesian methods [74–76] based on projection data instead of diffraction patterns [34, 38, 48, 60, 79].

A similar approach called *ptychographic tomography* has been proposed and studied numerically [23, 40, 41, 46, 58]. The difference is that in ptychography, instead of simultaneous pairwise measurements of the whole object, multiple significantly overlapped diffraction patterns are measured in each direction by sequentially shifting the aperture over different parts of the object. As a consequence, ptychographic tomography is limited to sizable objects capable of sustaining multiple intense illuminations and hence not suitable for, e.g. single particle imaging.

With the scheme in Theorem 6.1 for a strong phase object, however, there remain several hurdles to be overcome. The foremost is developing effective numerical algorithms for 3D phase unwrapping which is not as well studied as 2D phase unwrapping [37].

After the alignment of the phase projections, it is tempting to apply the 2D phase unwrapping methods and try to recover the projection from the phase projection in each direction. The projection in each direction, however, usually violate the 2D Itoh condition even when the 3D Itoh condition holds. If the 2D Itoh condition fails to hold at a large number of pixels, then 2D phase unwrapping becomes more complicated, requiring additional prior information. Moreover, the unwrapped phases for different directions must be consistent with one another. Hence the 3D phase unwrapping problem should be approached with all phase projections together instead of one direction at a time. This is our on-going work.

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## APPENDIX A. PROOF OF THEOREM 6.1

The following result is our basic tool.

**Lemma A.1.** [25] *Let  $\mu$  be the phase mask (i.e.  $\mu(\mathbf{n}) = \exp[i\phi(\mathbf{n})]$ ,  $\phi(\mathbf{n}) \in \mathbb{R}, \forall \mathbf{n}$ ) with independent, continuous random variables  $\phi(\mathbf{n}) \in \mathbb{R}$ . If  $e^{i\kappa g_{\mathbf{t}}} \odot \nu$  produces the same diffraction pattern as  $e^{i\kappa f_{\mathbf{t}}} \odot \mu$ , then for some  $\mathbf{m}_{\mathbf{t}} \in \mathbb{Z}^2, \theta_{\mathbf{t}} \in \mathbb{R}$*

$$(92) \quad e^{i\kappa g_{\mathbf{t}}(\mathbf{n})} \nu(\mathbf{n}) = \text{either } e^{i\theta_{\mathbf{t}}} e^{i\kappa f_{\mathbf{t}}(\mathbf{n} + \mathbf{m}_{\mathbf{t}})} \mu(\mathbf{n} + \mathbf{m}_{\mathbf{t}}) \\ \text{or } e^{i\theta_{\mathbf{t}}} e^{-i\kappa f_{\mathbf{t}}(-\mathbf{n} + \mathbf{m}_{\mathbf{t}})} \overline{\mu(-\mathbf{n} + \mathbf{m}_{\mathbf{t}})}$$

for all  $\mathbf{n}$ .

Lemma A.1 is a special case of the more general result in [25] which is not limited to phase masks. Note that the statement holds for *any* real-valued continuous random variable  $\phi(\mathbf{n})$ . By more advanced techniques from algebraic geometry and probability, one can relax the conditions of continuity and independence on  $\phi(\mathbf{n})$ .

After taking logarithm, (92) becomes

$$(93) \quad \kappa g_{\mathbf{t}}(\mathbf{n}) - i \ln \nu(\mathbf{n}) = \text{either } \theta_{\mathbf{t}} + \kappa f_{\mathbf{t}}(\mathbf{n} + \mathbf{m}_{\mathbf{t}}) - i \ln \mu(\mathbf{n} + \mathbf{m}_{\mathbf{t}}) \\ \text{or } \theta_{\mathbf{t}} - \kappa f_{\mathbf{t}}(-\mathbf{n} + \mathbf{m}_{\mathbf{t}}) - i \ln \overline{\mu(-\mathbf{n} + \mathbf{m}_{\mathbf{t}})}$$

modulo  $2\pi$ .

If  $\mu$  is completely known, i.e.  $\nu = \mu$ , then (93) becomes

$$(94) \quad \begin{aligned} \kappa g_{\mathbf{t}}(\mathbf{n}) - i \ln \mu(\mathbf{n}) &= \text{either } \theta_{\mathbf{t}} + \kappa f_{\mathbf{t}}(\mathbf{n} + \mathbf{m}_{\mathbf{t}}) - i \ln \mu(\mathbf{n} + \mathbf{m}_{\mathbf{t}}) \\ &\text{or } \theta_{\mathbf{t}} - \kappa \overline{f_{\mathbf{t}}(-\mathbf{n} + \mathbf{m}_{\mathbf{t}})} - i \ln \overline{\mu(-\mathbf{n} + \mathbf{m}_{\mathbf{t}})} \end{aligned}$$

modulo  $2\pi$ .

Since both diffraction patterns are from the same snapshot, we can reset the object frame so that  $\mathbf{l}_{\mathbf{t}} = 0$ .

Suppose the first alternative in (94) holds with  $\mathbf{m}_{\mathbf{t}} \neq 0$ . By (40),  $e^{i\kappa f_{\mathbf{t}}}$  and  $e^{i\kappa g_{\mathbf{t}}}$  have the same autocorrelation function and hence

$$\sum_{\mathbf{n}} e^{i\kappa(f_{\mathbf{t}}(\mathbf{n}+\mathbf{k})-\overline{f_{\mathbf{t}}(\mathbf{n})})} = \sum_{\mathbf{n}} e^{i\kappa(f_{\mathbf{t}}(\mathbf{n}+\mathbf{m}_{\mathbf{t}}+\mathbf{k})-\overline{f_{\mathbf{t}}(\mathbf{n}+\mathbf{m}_{\mathbf{t}})})} e^{i(\phi(\mathbf{n}+\mathbf{m}_{\mathbf{t}}+\mathbf{k})-\phi(\mathbf{n}+\mathbf{k}))} e^{-i(\phi(\mathbf{n}+\mathbf{m}_{\mathbf{t}})-\phi(\mathbf{n}))}$$

for all  $\mathbf{k}$ , or equivalently

$$(95) \quad \begin{aligned} \sum_{\mathbf{n}} e^{i\kappa(f_{\mathbf{t}}(\mathbf{n}+\mathbf{m}_{\mathbf{t}}+\mathbf{k})-\overline{f_{\mathbf{t}}(\mathbf{n}+\mathbf{m}_{\mathbf{t}})})} \\ = \sum_{\mathbf{n}} e^{i\kappa(f_{\mathbf{t}}(\mathbf{n}+\mathbf{m}_{\mathbf{t}}+\mathbf{k})-\overline{f_{\mathbf{t}}(\mathbf{n}+\mathbf{m}_{\mathbf{t}})})} e^{i(\phi(\mathbf{n}+\mathbf{m}_{\mathbf{t}}+\mathbf{k})-\phi(\mathbf{n}+\mathbf{m}_{\mathbf{t}})-\phi(\mathbf{n}+\mathbf{k})+\phi(\mathbf{n}))} \end{aligned}$$

by change of index,  $\mathbf{n} \rightarrow \mathbf{n} + \mathbf{m}_{\mathbf{t}}$ , on the left hand side of equation. Define

$$\Delta_{\mathbf{k}} f_{\mathbf{t}}(\mathbf{n} + \mathbf{m}_{\mathbf{t}}) := f_{\mathbf{t}}(\mathbf{n} + \mathbf{m}_{\mathbf{t}} + \mathbf{k}) - \overline{f_{\mathbf{t}}(\mathbf{n} + \mathbf{m}_{\mathbf{t}})}$$

and rewrite (95) as

$$(96) \quad 0 = \sum_{\mathbf{n}} [e^{i(\phi(\mathbf{n}+\mathbf{m}_{\mathbf{t}}+\mathbf{k})-\phi(\mathbf{n}+\mathbf{m}_{\mathbf{t}})-\phi(\mathbf{n}+\mathbf{k})+\phi(\mathbf{n}))} - 1] e^{i\kappa \Delta_{\mathbf{k}} f_{\mathbf{t}}(\mathbf{n}+\mathbf{m}_{\mathbf{t}})},$$

for all  $\mathbf{k}$ . We want to show that the probability of the event (96) is zero.

Let us consider those summands in (96), for any fixed  $\mathbf{k}$ , that share a common  $\phi(\mathbf{l})$ , for any fixed  $\mathbf{l}$ , in the expression. Clearly, there are at most four such terms:

$$(97) \quad \begin{aligned} & [e^{i(\phi(\mathbf{l})-\phi(\mathbf{l}-\mathbf{k})-\phi(\mathbf{l}-\mathbf{m}_{\mathbf{t}})+\phi(\mathbf{l}-\mathbf{k}-\mathbf{m}_{\mathbf{t}}))} - 1] e^{i\kappa \Delta_{\mathbf{k}} f_{\mathbf{t}}(\mathbf{l}-\mathbf{k})} \\ & + [e^{i(\phi(\mathbf{l}+\mathbf{k})-\phi(\mathbf{l})-\phi(\mathbf{l}+\mathbf{k}-\mathbf{m}_{\mathbf{t}})+\phi(\mathbf{l}-\mathbf{m}_{\mathbf{t}}))} - 1] e^{i\kappa \Delta_{\mathbf{k}} f_{\mathbf{t}}(\mathbf{l})} \\ & + [e^{i(\phi(\mathbf{l}+\mathbf{m}_{\mathbf{t}})-\phi(\mathbf{l}-\mathbf{k}+\mathbf{m}_{\mathbf{t}})-\phi(\mathbf{l})+\phi(\mathbf{l}-\mathbf{k}))} - 1] e^{i\kappa \Delta_{\mathbf{k}} f_{\mathbf{t}}(\mathbf{l}-\mathbf{k}+\mathbf{m}_{\mathbf{t}})} \\ & + [e^{i(\phi(\mathbf{l}+\mathbf{k}+\mathbf{m}_{\mathbf{t}})-\phi(\mathbf{l}+\mathbf{m}_{\mathbf{t}})-\phi(\mathbf{l}+\mathbf{k})+\phi(\mathbf{l}))} - 1] e^{i\kappa \Delta_{\mathbf{k}} f_{\mathbf{t}}(\mathbf{l}+\mathbf{m}_{\mathbf{t}})}. \end{aligned}$$

Since the continuous random variable  $\phi(\mathbf{l})$  does not appear in other summands and hence is independent of them, (96) implies that (97) (and the rest of (96)) must vanish almost surely.

For  $\mathbf{k}$  that are linearly independent of  $\mathbf{m}_{\mathbf{t}}$ , the four independent random variables

$$(98) \quad \phi(\mathbf{l} - \mathbf{k} - \mathbf{m}_{\mathbf{t}}), \quad \phi(\mathbf{l} + \mathbf{k} - \mathbf{m}_{\mathbf{t}}), \quad \phi(\mathbf{l} - \mathbf{k} + \mathbf{m}_{\mathbf{t}}), \quad \phi(\mathbf{l} + \mathbf{k} + \mathbf{m}_{\mathbf{t}})$$

appear separately in exactly one summand in (97). Consequently, (97) (and hence (96)) almost surely does not vanishes for  $\mathbf{k}$  that are linearly independent of  $\mathbf{m}_{\mathbf{t}}$ .

On the other hand, if  $\mathbf{k}$  is parallel to  $\mathbf{m}_t \neq 0$ , then for any

$$\mathbf{k} \notin \{\pm \mathbf{m}_t, \pm \frac{1}{2} \mathbf{m}_t, \pm 2 \mathbf{m}_t\}$$

the four terms in (98) appear separately in exactly one summand in (97). Consequently, (97) almost surely does not vanishes.

Thus whenever the first alternative in (94) holds true, we have  $\mathbf{m}_t = 0$  and  $e^{i\kappa g_t} = e^{i\theta_t} e^{i\kappa f_t}$  for some constant  $\theta_t$  independent of the grid point.

Next, we show that the second alternative in (92) is false. By (40), we have

$$\begin{aligned} & \sum_{\mathbf{n}} e^{i\kappa(f_t(\mathbf{n}+\mathbf{k})-\overline{f_t(\mathbf{n})})} \\ &= \sum_{\mathbf{n}} e^{-i\kappa(\overline{f_t(-\mathbf{n}+\mathbf{m}_t+\mathbf{k})}-f_t(-\mathbf{n}+\mathbf{m}_t))} e^{-i(\phi(-\mathbf{n}+\mathbf{m}_t+\mathbf{k})+\phi(\mathbf{n}+\mathbf{k}))} e^{i(\phi(-\mathbf{n}+\mathbf{m}_t)+\phi(\mathbf{n}))} \end{aligned}$$

for all  $\mathbf{k}$ , or equivalently

$$(99) \quad \begin{aligned} & \sum_{\mathbf{n}} e^{i\kappa(f_t(\mathbf{n}+\mathbf{m}_t+\mathbf{k})-\overline{f_t(\mathbf{n}+\mathbf{m}_t)})} \\ &= \sum_{\mathbf{n}} e^{-i\kappa(\overline{f_t(-\mathbf{n}+\mathbf{m}_t+\mathbf{k})}-f_t(-\mathbf{n}+\mathbf{m}_t))} e^{-i(\phi(-\mathbf{n}+\mathbf{m}_t+\mathbf{k})+\phi(\mathbf{n}+\mathbf{k}))} e^{i(\phi(-\mathbf{n}+\mathbf{m}_t)+\phi(\mathbf{n}))} \end{aligned}$$

by change of index,  $\mathbf{n} \rightarrow -\mathbf{n} + \mathbf{m}_t$ , on the left hand side of equation. With

$$\Delta_{\mathbf{k}} \overline{f_t(-\mathbf{n} + \mathbf{m}_t)} := \overline{f_t(-\mathbf{n} + \mathbf{m}_t + \mathbf{k})} - f_t(-\mathbf{n} + \mathbf{m}_t)$$

we rewrite (99) as

$$(100) \quad 0 = \sum_{\mathbf{n}} [e^{i(-\phi(-\mathbf{n}+\mathbf{m}_t+\mathbf{k})+\phi(-\mathbf{n}+\mathbf{m}_t)-\phi(\mathbf{n}+\mathbf{k})+\phi(\mathbf{n}))} - 1] e^{-i\kappa \Delta_{\mathbf{k}} \overline{f_t(-\mathbf{n}+\mathbf{m}_t)}}$$

for all  $\mathbf{k}$ . We want to show that the right hand side of (100) almost surely does not vanish for any  $\mathbf{k}$ .

As before, consider those summands in (100), for any fixed  $\mathbf{k}$ , that share a common  $\phi(\mathbf{l})$ , for any fixed  $\mathbf{l}$ , in the expression. Clearly, there are at most four such terms:

$$(101) \quad \begin{aligned} & [e^{i(-\phi(\mathbf{l})+\phi(\mathbf{l}+\mathbf{k})-\phi(-\mathbf{l}+\mathbf{m}_t)+\phi(-\mathbf{l}-\mathbf{k}+\mathbf{m}_t))} - 1] e^{-i\kappa \Delta_{\mathbf{k}} \overline{f_t(\mathbf{l})}} \\ & + [e^{i(-\phi(\mathbf{l}-\mathbf{k})+\phi(\mathbf{l})-\phi(-\mathbf{l}+\mathbf{k}+\mathbf{m}_t)+\phi(-\mathbf{l}+\mathbf{m}_t))} - 1] e^{-i\kappa \Delta_{\mathbf{k}} \overline{f_t(\mathbf{l}-\mathbf{k})}} \\ & + [e^{i(-\phi(-\mathbf{l}+\mathbf{m}_t)+\phi(-\mathbf{l}+\mathbf{k}+\mathbf{m}_t)-\phi(\mathbf{l})+\phi(\mathbf{l}-\mathbf{k}))} - 1] e^{-i\kappa \Delta_{\mathbf{k}} \overline{f_t(-\mathbf{l}+\mathbf{m}_t)}} \\ & + [e^{i(-\phi(-\mathbf{l}-\mathbf{k}+\mathbf{m}_t)+\phi(-\mathbf{l}+\mathbf{m}_t)-\phi(\mathbf{l}+\mathbf{k})+\phi(\mathbf{l}))} - 1] e^{-i\kappa \Delta_{\mathbf{k}} \overline{f_t(-\mathbf{l}-\mathbf{k}+\mathbf{m}_t)}} \end{aligned}$$

With  $\phi(\mathbf{l})$  appearing in no other terms, (100) implies that (101) must vanish almost surely.

Some observations are in order. First, both  $\phi(\mathbf{l})$  and  $\phi(-\mathbf{l} + \mathbf{m}_t)$  appear exactly once in each summand in (129). Second, the following pairings of the other phases

$$\{\phi(\mathbf{l} + \mathbf{k}), \phi(-\mathbf{l} - \mathbf{k} + \mathbf{m}_t)\}, \quad \{\phi(\mathbf{l} - \mathbf{k}), \phi(-\mathbf{l} + \mathbf{k} + \mathbf{m}_t)\}$$

also appear exactly twice in (129). As long as  $\mathbf{k} \neq 0$  and  $2\mathbf{l} \neq \mathbf{m}_t$ , these two pairs are not identical and hence

$$(102) \quad \begin{aligned} 0 &= \left[ e^{i(-\phi(\mathbf{l})+\phi(\mathbf{l}+\mathbf{k})-\phi(-\mathbf{l}+\mathbf{m}_t)+\phi(-\mathbf{l}-\mathbf{k}+\mathbf{m}_t))} - 1 \right] e^{-i\kappa\Delta_{\mathbf{k}}\overline{f_t(\mathbf{l})}} \\ &\quad + \overline{\left[ e^{i(\phi(-\mathbf{l}-\mathbf{k}+\mathbf{m}_t)-\phi(-\mathbf{l}+\mathbf{m}_t)+\phi(\mathbf{l}+\mathbf{k})-\phi(\mathbf{l}))} - 1 \right]} e^{-i\kappa\Delta_{\mathbf{k}}\overline{f_t(-\mathbf{l}-\mathbf{k}+\mathbf{m}_t)}} \\ 0 &= \left[ e^{i(-\phi(\mathbf{l}-\mathbf{k})+\phi(\mathbf{l})-\phi(-\mathbf{l}+\mathbf{k}+\mathbf{m}_t)+\phi(-\mathbf{l}+\mathbf{m}_t))} - 1 \right] e^{-i\kappa\Delta_{\mathbf{k}}\overline{f_t(\mathbf{l}-\mathbf{k})}} \\ &\quad + \overline{\left[ e^{i(\phi(-\mathbf{l}+\mathbf{m}_t)-\phi(-\mathbf{l}+\mathbf{k}+\mathbf{m}_t)+\phi(\mathbf{l})-\phi(\mathbf{l}-\mathbf{k}))} - 1 \right]} e^{-i\kappa\Delta_{\mathbf{k}}\overline{f_t(-\mathbf{l}+\mathbf{m}_t)}} \end{aligned}$$

both of which are almost surely false because the two factors

$$\left[ e^{i(-\phi(\mathbf{l})+\phi(\mathbf{l}+\mathbf{k})-\phi(-\mathbf{l}+\mathbf{m}_t)+\phi(-\mathbf{l}-\mathbf{k}+\mathbf{m}_t))} - 1 \right], \quad \left[ e^{i(-\phi(\mathbf{l}-\mathbf{k})+\phi(\mathbf{l})-\phi(-\mathbf{l}+\mathbf{k}+\mathbf{m}_t)+\phi(-\mathbf{l}+\mathbf{m}_t))} - 1 \right]$$

differ with their complex conjugates in a random manner independently from  $f_t$ .

Therefore, the second alternative in (94) almost surely does not hold true.

In summary, the first alternative in (94) holds with  $\mathbf{m}_t = 0$ , namely

$$\kappa g_t(\mathbf{n}) = \theta_t + \kappa f_t(\mathbf{n}) \quad \text{mod } 2\pi$$

almost surely.

The actual support of the projections (16)-(18) for  $0 \leq \alpha, \beta \leq 1$  and odd integer  $n$ , for example, is contained in

$$(103) \quad \bigcup_{i \in \mathbb{Z}_n} (\mathbb{Z}_n - \lfloor \alpha i \rfloor) \times (\mathbb{Z}_n - \lfloor \beta i \rfloor)$$

where  $\lfloor \cdot \rfloor$  denotes the floor function. In turn, the set in (103) is a subset of

$$(104) \quad \left\{ \bigcup_{i \in \mathbb{Z}_n} (\mathbb{Z}_n - \lfloor \alpha i \rfloor) \right\} \times \left\{ \bigcup_{i \in \mathbb{Z}_n} (\mathbb{Z}_n - \lfloor \beta i \rfloor) \right\} = \mathbb{Z}_{\ell_\alpha} \times \mathbb{Z}_{\ell_\beta}$$

where

$$(105) \quad \ell_\alpha = 2 \cdot \lfloor \frac{1}{2}(1 + |\alpha|)(n - 1) \rfloor + 1, \quad \ell_\beta = 2 \cdot \lfloor \frac{1}{2}(1 + |\beta|)(n - 1) \rfloor + 1.$$

The same support constraint  $\mathbb{Z}_{\ell_\alpha} \times \mathbb{Z}_{\ell_\beta}$  with (105) applies to the case with  $|\alpha|, |\beta| \leq 1$  and odd integer  $n$ .

Now that  $g_t(\mathbf{n}) = f_t(\mathbf{n}) = 0$  for  $\mathbf{n} \in \mathbb{Z}_p^2 \setminus \mathbb{Z}_{\ell_\alpha} \times \mathbb{Z}_{\ell_\beta}$  for  $\mathbf{t} = (1, \alpha, \beta)$  due to the support constraint (104)-(105), so  $\theta_t$  must be an integer multiple of  $2\pi$ , i.e.  $e^{i\kappa g_t} = e^{i\kappa f_t}$  almost surely. The proof is complete.

## APPENDIX B. PROOF OF THEOREM 6.2

Let

$$\begin{aligned} f_{\mathbf{t}'}^*(\mathbf{n}) &= f_{\mathbf{t}'}(\mathbf{n} + \mathbf{l}_{\mathbf{t}'}), & f_{\mathbf{t}}^*(\mathbf{n}) &= f_{\mathbf{t}}(\mathbf{n} + \mathbf{l}_{\mathbf{t}}) \\ g_{\mathbf{t}'}^*(\mathbf{n}) &= g_{\mathbf{t}'}(\mathbf{n} + \mathbf{l}_{\mathbf{t}'}), & g_{\mathbf{t}}^*(\mathbf{n}) &= g_{\mathbf{t}}(\mathbf{n} + \mathbf{l}_{\mathbf{t}}) \end{aligned}$$

for some  $\mathbf{l}_{\mathbf{t}'}, \mathbf{l}_{\mathbf{t}}$ .



Suppose that the first alternative in (94) holds true for  $\mathbf{t}'$ , i.e.

$$(106) \quad \kappa g_{\mathbf{t}'}^*(\mathbf{n}) - i \ln \mu(\mathbf{n}) = \theta_{\mathbf{t}'} + \kappa f_{\mathbf{t}'}^*(\mathbf{n} + \mathbf{m}_{\mathbf{t}'}) - i \ln \mu(\mathbf{n} + \mathbf{m}_{\mathbf{t}'})$$

modulo  $2\pi$ , or equivalently

$$(107) \quad \kappa g_{\mathbf{t}'}^*(\mathbf{n}) + \phi(\mathbf{n}) = \theta_{\mathbf{t}'} + \kappa f_{\mathbf{t}'}^*(\mathbf{n} + \mathbf{m}_{\mathbf{t}'}) + \phi(\mathbf{n} + \mathbf{m}_{\mathbf{t}'}) + \kappa h_{\mathbf{t}'}(\mathbf{n}),$$

where  $h_{\mathbf{t}'}(\mathbf{n})$  is an integer multiple of  $2\pi/\kappa$  for every  $\mathbf{n}$ , implying

$$(108) \quad \kappa \widehat{g}_{\mathbf{t}'}^*(\mathbf{k}) + \widehat{\phi}(\mathbf{k}) = e^{i2\pi \mathbf{m}_{\mathbf{t}'} \cdot \mathbf{k}/p} (\kappa \widehat{f}_{\mathbf{t}'}^*(\mathbf{k}) + \widehat{\phi}(\mathbf{k})) + p^2 \theta_{\mathbf{t}'} D_p^2(\mathbf{k}) + \kappa \widehat{h}_{\mathbf{t}'}(\mathbf{k}).$$

First we show that the second alternative in (94) can not hold for  $\mathbf{t} \neq \mathbf{t}'$ . Suppose otherwise, i.e.

$$(109) \quad \kappa g_{\mathbf{t}}^*(\mathbf{n}) + \phi(\mathbf{n}) = \theta_{\mathbf{t}} + \overline{\kappa f_{\mathbf{t}}^*(-\mathbf{n} + \mathbf{m}_{\mathbf{t}})} - \phi(-\mathbf{n} + \mathbf{m}_{\mathbf{t}}) \pmod{2\pi}$$

implying

$$(110) \quad \kappa \widehat{g}_{\mathbf{t}}^*(\mathbf{k}) + \widehat{\phi}(\mathbf{k}) = e^{-i2\pi \mathbf{m}_{\mathbf{t}} \cdot \mathbf{k}/p} (\overline{\kappa \widehat{f}_{\mathbf{t}}^*(\mathbf{k})} - \widehat{\phi}(-\mathbf{k})) + p^2 \theta_{\mathbf{t}} D_p^2(\mathbf{k}) + \kappa \widehat{h}_{\mathbf{t}}(\mathbf{k})$$

where  $h_{\mathbf{t}}(\mathbf{n})$  is an integer multiple of  $2\pi$  for every  $\mathbf{n}$ .

Since

$$\widehat{g}_{\mathbf{t}'}(\mathbf{k}') = \widehat{g}_{\mathbf{t}}(\mathbf{k}), \quad \widehat{f}_{\mathbf{t}'}(\mathbf{k}') = \widehat{f}_{\mathbf{t}}(\mathbf{k}), \quad (\mathbf{k}, \mathbf{k}') \in C_{\mathbf{t}, \mathbf{t}'},$$

we have

$$(111) \quad \widehat{g}_{\mathbf{t}'}^*(\mathbf{k}') e^{-i2\pi \mathbf{k}' \cdot \mathbf{l}_{\mathbf{t}'}/p} = \widehat{g}_{\mathbf{t}}^*(\mathbf{k}) e^{-i2\pi \mathbf{k} \cdot \mathbf{l}_{\mathbf{t}}/p}$$

$$(112) \quad \widehat{f}_{\mathbf{t}'}^*(\mathbf{k}') e^{-i2\pi \mathbf{k}' \cdot \mathbf{l}_{\mathbf{t}'}/p} = \widehat{f}_{\mathbf{t}}^*(\mathbf{k}) e^{-i2\pi \mathbf{k} \cdot \mathbf{l}_{\mathbf{t}}/p}.$$

Eq. (111), together with (108) and (110), imply that for  $(\mathbf{k}, \mathbf{k}') \in C_{\mathbf{t}, \mathbf{t}'}$

$$\begin{aligned} & e^{-i2\pi \mathbf{k}' \cdot \mathbf{l}_{\mathbf{t}'}/p} \left[ e^{i2\pi \mathbf{m}_{\mathbf{t}'} \cdot \mathbf{k}'/p} (\kappa \widehat{f}_{\mathbf{t}'}^*(\mathbf{k}') + \widehat{\phi}(\mathbf{k}')) + p^2 \theta_{\mathbf{t}'} D_p^2(\mathbf{k}') + \kappa \widehat{h}_{\mathbf{t}'}(\mathbf{k}') - \widehat{\phi}(\mathbf{k}') \right] \\ &= e^{-i2\pi \mathbf{k} \cdot \mathbf{l}_{\mathbf{t}}/p} \left[ e^{-i2\pi \mathbf{m}_{\mathbf{t}} \cdot \mathbf{k}/p} (\overline{\kappa \widehat{f}_{\mathbf{t}}^*(\mathbf{k})} - \widehat{\phi}(-\mathbf{k})) + p^2 \theta_{\mathbf{t}} D_p^2(\mathbf{k}) + \kappa \widehat{h}_{\mathbf{t}}(\mathbf{k}) - \widehat{\phi}(\mathbf{k}) \right], \end{aligned}$$

and hence

$$(113) \quad \begin{aligned} & \left[ e^{i2\pi (\mathbf{m}_{\mathbf{t}'} - \mathbf{l}_{\mathbf{t}'}) \cdot \mathbf{k}'/p} - e^{-i2\pi \mathbf{k}' \cdot \mathbf{l}_{\mathbf{t}'}/p} \right] \widehat{\phi}(\mathbf{k}') + e^{-i2\pi (\mathbf{m}_{\mathbf{t}} + \mathbf{l}_{\mathbf{t}}) \cdot \mathbf{k}/p} \widehat{\phi}(-\mathbf{k}) + e^{-i2\pi \mathbf{l}_{\mathbf{t}} \cdot \mathbf{k}/p} \widehat{\phi}(\mathbf{k}) \\ &= -\kappa e^{i2\pi (\mathbf{m}_{\mathbf{t}'} - \mathbf{l}_{\mathbf{t}'}) \cdot \mathbf{k}'/p} \widehat{f}_{\mathbf{t}'}^*(\mathbf{k}') + \kappa e^{-i2\pi (\mathbf{m}_{\mathbf{t}} + \mathbf{l}_{\mathbf{t}}) \cdot \mathbf{k}/p} \overline{\widehat{f}_{\mathbf{t}}^*(\mathbf{k})} + \kappa e^{-i2\pi \mathbf{k} \cdot \mathbf{l}_{\mathbf{t}}/p} \widehat{h}_{\mathbf{t}}(\mathbf{k}) \\ & \quad - \kappa e^{-i2\pi \mathbf{k}' \cdot \mathbf{l}_{\mathbf{t}'}/p} \widehat{h}_{\mathbf{t}'}(\mathbf{k}') - p^2 e^{-i2\pi \mathbf{k}' \cdot \mathbf{l}_{\mathbf{t}'}/p} \theta_{\mathbf{t}'} D_p^2(\mathbf{k}') + p^2 e^{-i2\pi \mathbf{k} \cdot \mathbf{l}_{\mathbf{t}}/p} \theta_{\mathbf{t}} D_p^2(\mathbf{k}). \end{aligned}$$

The left hand side of (113) is a sum of independent, continuous random variables while the right hand side is a discrete random variable for a fixed  $f$ . Therefore, (113) is false almost surely.

This leaves the first alternative of (94) the only viable alternative for  $\mathbf{t}$ , i.e.

$$(114) \quad \kappa g_{\mathbf{t}}^*(\mathbf{n}) + \phi(\mathbf{n}) = \theta_{\mathbf{t}} + \kappa f_{\mathbf{t}}^*(\mathbf{n} + \mathbf{m}_{\mathbf{t}}) + \phi(\mathbf{n} + \mathbf{m}_{\mathbf{t}}) \pmod{2\pi},$$

for some  $\mathbf{m}_t$ , and hence

$$\begin{aligned} & e^{i2\pi(\mathbf{m}_t - \mathbf{1}_t) \cdot \mathbf{k}/p} (\kappa \widehat{f}_t^*(\mathbf{k}) + \widehat{\phi}(\mathbf{k})) - e^{-i2\pi \mathbf{1}_t \cdot \mathbf{k}/p} \widehat{\phi}(\mathbf{k}) + p^2 \theta_t e^{-i2\pi \mathbf{k} \cdot \mathbf{1}_t/p} D_p^2(\mathbf{k}) + \kappa e^{-i2\pi \mathbf{k} \cdot \mathbf{1}_t/p} \widehat{h}_t(\mathbf{k}) \\ = & e^{i2\pi(\mathbf{m}_{t'} - \mathbf{1}_{t'}) \cdot \mathbf{k}'/p} (\kappa \widehat{f}_{t'}^*(\mathbf{k}') + \widehat{\phi}(\mathbf{k}')) - e^{-i2\pi \mathbf{1}_{t'} \cdot \mathbf{k}'/p} \widehat{\phi}(\mathbf{k}') \\ & + p^2 \theta_{t'} e^{-i2\pi \mathbf{k}' \cdot \mathbf{1}_{t'}/p} D_p^2(\mathbf{k}') + \kappa e^{-i2\pi \mathbf{k}' \cdot \mathbf{1}_{t'}/p} \widehat{h}_{t'}(\mathbf{k}') \end{aligned}$$

for  $(\mathbf{k}, \mathbf{k}') \in C_{t,t'}$ . Reorganizing the above equation, we have

$$\begin{aligned} (115) \quad & (e^{i2\pi \mathbf{m}_t \cdot \mathbf{k}/p} - 1) e^{-i2\pi \mathbf{1}_t \cdot \mathbf{k}/p} \widehat{\phi}(\mathbf{k}) + (1 - e^{i2\pi \mathbf{m}_{t'} \cdot \mathbf{k}'/p}) e^{-i2\pi \mathbf{1}_{t'} \cdot \mathbf{k}'/p} \widehat{\phi}(\mathbf{k}') \\ = & e^{i2\pi(\mathbf{m}_{t'} - \mathbf{1}_{t'}) \cdot \mathbf{k}'/p} \kappa \widehat{f}_{t'}^*(\mathbf{k}') - e^{i2\pi(\mathbf{m}_t - \mathbf{1}_t) \cdot \mathbf{k}/p} \kappa \widehat{f}_t^*(\mathbf{k}) + p^2 \theta_{t'} e^{-i2\pi \mathbf{k}' \cdot \mathbf{1}_{t'}/p} D_p^2(\mathbf{k}') \\ & - p^2 \theta_t e^{-i2\pi \mathbf{k} \cdot \mathbf{1}_t/p} D_p^2(\mathbf{k}) + \kappa e^{-i2\pi \mathbf{k}' \cdot \mathbf{1}_{t'}/p} \widehat{h}_{t'}(\mathbf{k}') - \kappa e^{-i2\pi \mathbf{k} \cdot \mathbf{1}_t/p} \widehat{h}_t(\mathbf{k}) \end{aligned}$$

for  $(\mathbf{k}, \mathbf{k}') \in C_{t,t'}$ . If, for some  $(\mathbf{k}, \mathbf{k}') \in C_{t,t'}$ ,

$$(116) \quad (e^{i2\pi \mathbf{m}_t \cdot \mathbf{k}/p} - 1) e^{-i2\pi \mathbf{1}_t \cdot \mathbf{k}/p} \neq 0 \quad \text{or} \quad e^{-i2\pi \mathbf{1}_{t'} \cdot \mathbf{k}'/p} (1 - e^{i2\pi \mathbf{m}_{t'} \cdot \mathbf{k}'/p}) \neq 0,$$

then the left hand side of (115) is a continuous random variable while the right hand side takes value in a discrete set for a given  $f$ . This is a contradiction with probability one, implying for all  $(\mathbf{k}, \mathbf{k}') \in C_{t,t'}$

$$(e^{i2\pi \mathbf{m}_t \cdot \mathbf{k}/p} - 1) e^{-i2\pi \mathbf{1}_t \cdot \mathbf{k}/p} = e^{-i2\pi \mathbf{1}_{t'} \cdot \mathbf{k}'/p} (e^{i2\pi \mathbf{m}_{t'} \cdot \mathbf{k}'/p} - 1) = 0$$

and consequently,

$$(117) \quad \mathbf{m}_t \cdot \mathbf{k} = \mathbf{m}_{t'} \cdot \mathbf{k}' = 0 \quad \text{mod } p.$$

By assumption, some  $(\mathbf{k}, \mathbf{k}') \in C_{t,t'}$  have components whose ratio is not a fraction over  $\mathbb{Z}_p$ , (117) can not hold true for  $\mathbf{m}_t, \mathbf{m}_{t'} \in \mathbb{Z}_p^2$ .

By (114) and (107),

$$\begin{aligned} \kappa g_t^*(\mathbf{n}) &= \theta_t + \kappa f_t^*(\mathbf{n}) \quad \text{mod } 2\pi, \\ \kappa g_{t'}^*(\mathbf{n}) &= \theta_{t'} + \kappa f_{t'}^*(\mathbf{n}) \quad \text{mod } 2\pi, \end{aligned}$$

which imply, by the set-up of zero-padding,  $\theta_t = \theta_{t'} = 0$  and hence

$$\kappa g_t^*(\mathbf{n}) = \kappa f_t^*(\mathbf{n}), \quad \kappa g_{t'}^*(\mathbf{n}) = \kappa f_{t'}^*(\mathbf{n}),$$

for all  $\mathbf{n} \in \mathbb{Z}_p^2$ .

Let us rule out the remaining undesirable alternative: For all  $\mathbf{n} \in \mathbb{Z}_p^2$ ,

$$(118) \quad \kappa g_t^*(\mathbf{n}) + \phi(\mathbf{n}) = \theta_t + \overline{\kappa f_t^*(-\mathbf{n} + \mathbf{m}_t)} - \phi(-\mathbf{n} + \mathbf{m}_t) \quad \text{mod } 2\pi$$

$$(119) \quad \kappa g_{t'}^*(\mathbf{n}) + \phi(\mathbf{n}) = \theta_{t'} + \overline{\kappa f_{t'}^*(-\mathbf{n} + \mathbf{m}_{t'})} - \phi(-\mathbf{n} + \mathbf{m}_{t'}) \quad \text{mod } 2\pi.$$

For  $(\mathbf{k}, \mathbf{k}') \in C_{t,t'}$ , we have

$$\begin{aligned} & e^{-i2\pi \mathbf{k}' \cdot \mathbf{1}_{t'}/p} \left[ e^{-i2\pi \mathbf{m}_{t'} \cdot \mathbf{k}'/p} (\overline{\kappa \widehat{f}_{t'}^*(\mathbf{k}')}) - \widehat{\phi}(-\mathbf{k}') + p^2 \theta_{t'} D_p^2(\mathbf{k}') - \widehat{\phi}(\mathbf{k}') + \kappa \widehat{h}_{t'}(\mathbf{k}') \right] \\ = & e^{-i2\pi \mathbf{k} \cdot \mathbf{1}_t/p} \left[ e^{-i2\pi \mathbf{m}_t \cdot \mathbf{k}/p} (\overline{\kappa \widehat{f}_t^*(\mathbf{k})}) - \widehat{\phi}(-\mathbf{k}) + p^2 \theta_t D_p^2(\mathbf{k}) - \widehat{\phi}(\mathbf{k}) + \kappa \widehat{h}_t(\mathbf{k}) \right], \end{aligned}$$

and hence

$$\begin{aligned}
& e^{-i2\pi(\mathbf{m}_t + \mathbf{l}_t) \cdot \mathbf{k}/p} \widehat{\phi}(-\mathbf{k}) + e^{-i2\pi \mathbf{l}_t \cdot \mathbf{k}/p} \widehat{\phi}(\mathbf{k}) - e^{-i2\pi(\mathbf{m}_t + \mathbf{l}_t) \cdot \mathbf{k}'/p} \widehat{\phi}(-\mathbf{k}') - e^{-i2\pi \mathbf{l}_t \cdot \mathbf{k}'/p} \widehat{\phi}(\mathbf{k}') \\
= & -\kappa e^{-i2\pi(\mathbf{m}_t + \mathbf{l}_t) \cdot \mathbf{k}'/p} \overline{\widehat{f}_t^*(\mathbf{k}')} + \kappa e^{-i2\pi(\mathbf{m}_t + \mathbf{l}_t) \cdot \mathbf{k}/p} \overline{\widehat{f}_t^*(\mathbf{k})} + \kappa e^{-i2\pi \mathbf{k} \cdot \mathbf{l}_t/p} \widehat{h}_t(\mathbf{k}) \\
& -\kappa e^{-i2\pi \mathbf{k}' \cdot \mathbf{l}_t/p} \widehat{h}_t(\mathbf{k}') - p^2 e^{-i2\pi \mathbf{k}' \cdot \mathbf{l}_t/p} \theta_t D_p^2(\mathbf{k}') + p^2 e^{-i2\pi \mathbf{k} \cdot \mathbf{l}_t/p} \theta_t D_p^2(\mathbf{k}).
\end{aligned}$$

The left hand side is a continuous random variable while the right hand side is a discrete random variable for a fixed  $f$ . This is impossible and hence the undesirable alternative is ruled out. The proof is complete.

### APPENDIX C. PROOF OF THEOREM 7.1

The proof of Theorem 7.1 is analogous to that of Theorem 6.1, except with the additional complication of possible vanishing of the object function under the Born approximation.

Similar to Lemma A.1, for the diffraction pattern given by (46) we have the following characterization.

**Lemma C.1.** [25] *Let  $\mu = e^{i\phi(\mathbf{n})}$  with independent, continuous random variables  $\phi(\mathbf{n}) \in \mathbb{R}$ . Suppose that  $\text{supp}(f_t)$  is not a subset of a line and another masked object projection  $\nu \odot g_t$  produces the same diffraction pattern as  $\mu \odot f_t$ . Then for some  $\mathbf{p}$  and  $\theta_t$ ,*

$$\begin{aligned}
(120) \quad g_t(\mathbf{n})\nu(\mathbf{n}) &= \text{either } e^{i\theta_t} f_t(\mathbf{n} + \mathbf{m}_t)\mu(\mathbf{n} + \mathbf{m}_t) \\
&\text{or } e^{i\theta_t} \overline{f_t(-\mathbf{n} + \mathbf{m}_t)\mu(-\mathbf{n} + \mathbf{m}_t)}
\end{aligned}$$

for all  $\mathbf{n}$ .

If  $\mu$  is completely known, then  $\nu = \mu$  and (120) becomes

$$\begin{aligned}
(121) \quad g_t(\mathbf{n})\mu(\mathbf{n}) &= \text{either } e^{i\theta_t} f_t(\mathbf{n} + \mathbf{m}_t)\mu(\mathbf{n} + \mathbf{m}_t) \\
&\text{or } e^{i\theta_t} \overline{f_t(-\mathbf{n} + \mathbf{m}_t)\mu(-\mathbf{n} + \mathbf{m}_t)}.
\end{aligned}$$

First suppose that the first alternative in (121) and we want to show that  $\mathbf{m}_t = 0$ , which then implies that  $g_t(\cdot) = e^{i\theta_t} f_t(\cdot)$ .

Equality of the uncoded diffraction (41) implies that the autocorrelation of  $g_t$  equals that of  $f_t$  and hence by (121)

$$\sum_{\mathbf{n} \in \mathbb{Z}_p^2} f_t(\mathbf{n} + \mathbf{k}) \overline{f_t(\mathbf{n})} = \sum_{\mathbf{n} \in \mathbb{Z}_p^2} f_t(\mathbf{n} + \mathbf{k} + \mathbf{m}_t) \overline{f_t(\mathbf{n} + \mathbf{m}_t)} \mu(\mathbf{n} + \mathbf{k} + \mathbf{m}_t) \overline{\mu(\mathbf{n})} \overline{\mu(\mathbf{n} + \mathbf{k})} \mu(\mathbf{n} + \mathbf{m}_t)$$

which, after change of index  $\mathbf{n} \rightarrow \mathbf{n} + \mathbf{m}_t$  on the left hand side, becomes

$$(122) \quad 0 = \sum_{\mathbf{n} \in \mathbb{Z}_p^2} f_t(\mathbf{n} + \mathbf{k} + \mathbf{m}_t) \overline{f_t(\mathbf{n} + \mathbf{m}_t)} \left[ e^{i(\phi(\mathbf{n} + \mathbf{k} + \mathbf{m}_t) - \phi(\mathbf{n} + \mathbf{m}_t) + \phi(\mathbf{n}) - \phi(\mathbf{n} + \mathbf{k}))} - 1 \right]$$

for all  $\mathbf{k} \in \mathbb{Z}_{2p-1}^2$ . It is convenient to consider the autocorrelation function as  $(2p-1)$ -periodic function and endow  $\mathbb{Z}_{2p-1}^2$  with the periodic boundary condition.

Let us consider those summands on the right side of (122), for any fixed  $\mathbf{k}$ , that share a common  $\phi(\mathbf{l})$ , for any fixed  $\mathbf{l}$ . Clearly, there are at most four such terms:

$$(123) \quad \begin{aligned} & [e^{i(\phi(\mathbf{l})-\phi(\mathbf{l}-\mathbf{k})-\phi(\mathbf{l}-\mathbf{m}_t)+\phi(\mathbf{l}-\mathbf{k}-\mathbf{m}_t))} - 1] f_t(\mathbf{l})\overline{f_t(\mathbf{l}-\mathbf{k})} \\ & + [e^{i(\phi(\mathbf{l}+\mathbf{k})-\phi(\mathbf{l})-\phi(\mathbf{l}+\mathbf{k}-\mathbf{m}_t)+\phi(\mathbf{l}-\mathbf{m}_t))} - 1] f_t(\mathbf{l}+\mathbf{k})\overline{f_t(\mathbf{l})} \\ & + [e^{i(\phi(\mathbf{l}+\mathbf{m}_t)-\phi(\mathbf{l}-\mathbf{k}+\mathbf{m}_t)-\phi(\mathbf{l})+\phi(\mathbf{l}-\mathbf{k}))} - 1] f_t(\mathbf{l}+\mathbf{m}_t)\overline{f_t(\mathbf{l}-\mathbf{k}+\mathbf{m}_t)} \\ & + [e^{i(\phi(\mathbf{l}+\mathbf{k}+\mathbf{m}_t)-\phi(\mathbf{l}+\mathbf{m}_t)-\phi(\mathbf{l}+\mathbf{k})+\phi(\mathbf{l}))} - 1] f_t(\mathbf{l}+\mathbf{k}+\mathbf{m}_t)\overline{f_t(\mathbf{l}+\mathbf{m}_t)}. \end{aligned}$$

Since the continuous random variable  $\phi(\mathbf{l})$  does not appear in other summands and hence is independent of them, (122) implies that (123) (and the rest of (122)) vanishes almost surely.

Suppose  $\mathbf{m}_t \neq 0$  and consider any  $\mathbf{k}$  that is linearly independent of  $\mathbf{m}_t$ . The four independent random variables

$$(124) \quad \phi(\mathbf{l}-\mathbf{k}-\mathbf{m}_t), \quad \phi(\mathbf{l}+\mathbf{k}-\mathbf{m}_t), \quad \phi(\mathbf{l}-\mathbf{k}+\mathbf{m}_t), \quad \phi(\mathbf{l}+\mathbf{k}+\mathbf{m}_t)$$

appear separately in exactly one summand in (123). Consequently, (123) can not vanish, unless

$$(125) \quad f_t(\mathbf{l})\overline{f_t(\mathbf{l}-\mathbf{k})} = 0, \quad \overline{f_t(\mathbf{l})}f_t(\mathbf{l}+\mathbf{k}) = 0$$

$$(126) \quad f_t(\mathbf{l}+\mathbf{m}_t)\overline{f_t(\mathbf{l}-\mathbf{k}+\mathbf{m}_t)} = 0, \quad \overline{f_t(\mathbf{l}+\mathbf{m}_t)}f_t(\mathbf{l}+\mathbf{k}+\mathbf{m}_t) = 0$$

in (123).

On the other hand, if  $\mathbf{k}$  is parallel to  $\mathbf{m}_t \neq 0$ , then for any

$$(127) \quad \mathbf{k} \notin \{\pm\mathbf{m}_{t_0}, \pm\frac{1}{2}\mathbf{m}_{t_0}, \pm 2\mathbf{m}_{t_0}\}$$

the four terms in (124) appear separately in exactly one summand in (123). Consequently, (123) (and hence (122)) almost surely does not vanishes unless (125) and (126) hold.

Consider  $\mathbf{k} = 0$  which satisfies (127) if  $\mathbf{m}_t \neq 0$ . Clearly (125)-(126) with  $\mathbf{k} = 0$  implies that  $f_t \equiv 0$ , which violate the assumption that  $\text{supp}(f_t)$  is not a subset of a line. Thus  $\mathbf{m}_t = 0$  in the first alternative in (121).

Next we prove that the second alternative in (121) is false for all  $\mathbf{m}_t$ . Otherwise, by (41) we have

$$\begin{aligned} & \sum_{\mathbf{n} \in \mathbb{Z}_p^2} f_t(\mathbf{n}+\mathbf{k})\overline{f_t(\mathbf{n})} \\ & = \sum_{\mathbf{n} \in \mathbb{Z}_p^2} \overline{f_t(-\mathbf{n}-\mathbf{k}+\mathbf{m}_t)}f_t(-\mathbf{n}+\mathbf{m}_t)\overline{\mu(-\mathbf{n}-\mathbf{k}+\mathbf{m}_t)\mu(\mathbf{n}+\mathbf{k})\mu(\mathbf{n})\mu(-\mathbf{n}+\mathbf{m}_t)} \end{aligned}$$

which, after change of index  $\mathbf{n} \rightarrow -\mathbf{n}-\mathbf{k}+\mathbf{m}_t$  on the left hand side, becomes

$$(128) \quad \begin{aligned} 0 & = \sum_{\mathbf{n} \in \mathbb{Z}_p^2} \overline{f_t(-\mathbf{n}-\mathbf{k}+\mathbf{m}_t)}f_t(-\mathbf{n}+\mathbf{m}_t) \\ & \quad \cdot [e^{i(-\phi(-\mathbf{n}-\mathbf{k}+\mathbf{m}_t)+\phi(-\mathbf{n}+\mathbf{m}_t)-\phi(\mathbf{n}+\mathbf{k})+\phi(\mathbf{n}))} - 1] \end{aligned}$$

for all  $\mathbf{k} \in \mathbb{Z}_{2p-1}^2$ .

Consider those summands in (128), for any fixed  $\mathbf{k}$ , that share a common  $\phi(\mathbf{l})$ , for any fixed  $\mathbf{l}$ . Clearly, there are at most four such terms:

$$(129) \quad \begin{aligned} & [e^{i(-\phi(\mathbf{l})+\phi(\mathbf{l}+\mathbf{k})-\phi(-\mathbf{l}+\mathbf{m}_t)+\phi(-\mathbf{l}-\mathbf{k}+\mathbf{m}_t))} - 1] \overline{f_t(\mathbf{l})} f_t(\mathbf{l} + \mathbf{k}) \\ & + [e^{i(-\phi(\mathbf{l}-\mathbf{k})+\phi(\mathbf{l})-\phi(-\mathbf{l}+\mathbf{k}+\mathbf{m}_t)+\phi(-\mathbf{l}+\mathbf{m}_t))} - 1] \overline{f_t(\mathbf{l} - \mathbf{k})} f_t(\mathbf{l}) \\ & + [e^{i(-\phi(-\mathbf{l}+\mathbf{m}_t)+\phi(-\mathbf{l}+\mathbf{k}+\mathbf{m}_t)-\phi(\mathbf{l})+\phi(\mathbf{l}-\mathbf{k}))} - 1] \overline{f_t(-\mathbf{l} + \mathbf{m}_t)} f_t(-\mathbf{l} + \mathbf{k} + \mathbf{m}_t) \\ & + [e^{i(-\phi(-\mathbf{l}-\mathbf{k}+\mathbf{m}_t)+\phi(-\mathbf{l}+\mathbf{m}_t)-\phi(\mathbf{l}+\mathbf{k})+\phi(\mathbf{l}))} - 1] \overline{f_t(-\mathbf{l} - \mathbf{k} + \mathbf{m}_t)} f_t(-\mathbf{l} + \mathbf{m}_t) \end{aligned}$$

which must vanish under (128).

Some observations are in order. First, both  $\phi(\mathbf{l})$  and  $\phi(-\mathbf{l} + \mathbf{m}_t)$  appear exactly once in each summand in (129). Second, the following pairings of the other phases

$$(130) \quad \{\phi(\mathbf{l} + \mathbf{k}), \phi(-\mathbf{l} - \mathbf{k} + \mathbf{m}_t)\}, \quad \{\phi(\mathbf{l} - \mathbf{k}), \phi(-\mathbf{l} + \mathbf{k} + \mathbf{m}_t)\}$$

also appear exactly twice in (129). As long as

$$(131) \quad \begin{aligned} & \mathbf{k} \neq \mathbf{0} \\ & \& \mathbf{l} \neq \mathbf{m}_t/2, \end{aligned}$$

the two sets in (130) are not identical and, since each contains at least one element that is independent of the other, we have

$$(132) \quad 0 = [e^{i(-\phi(\mathbf{l})+\phi(\mathbf{l}+\mathbf{k})-\phi(-\mathbf{l}+\mathbf{m}_t)+\phi(-\mathbf{l}-\mathbf{k}+\mathbf{m}_t))} - 1] \overline{f_t(\mathbf{l})} f_t(\mathbf{l} + \mathbf{k}) \\ + [e^{i(\phi(-\mathbf{l}-\mathbf{k}+\mathbf{m}_t)-\phi(-\mathbf{l}+\mathbf{m}_t)+\phi(\mathbf{l}+\mathbf{k})-\phi(\mathbf{l}))} - 1] \overline{f_t(-\mathbf{l} - \mathbf{k} + \mathbf{m}_t)} f_t(-\mathbf{l} + \mathbf{m}_t)$$

$$(133) \quad 0 = [e^{i(-\phi(\mathbf{l}-\mathbf{k})+\phi(\mathbf{l})-\phi(-\mathbf{l}+\mathbf{k}+\mathbf{m}_t)+\phi(-\mathbf{l}+\mathbf{m}_t))} - 1] \overline{f_t(\mathbf{l} - \mathbf{k})} f_t(\mathbf{l}) \\ + [e^{i(\phi(-\mathbf{l}+\mathbf{m}_t)-\phi(-\mathbf{l}+\mathbf{k}+\mathbf{m}_t)+\phi(\mathbf{l})-\phi(\mathbf{l}-\mathbf{k}))} - 1] \overline{f_t(-\mathbf{l} + \mathbf{m}_t)} f_t(-\mathbf{l} + \mathbf{k} + \mathbf{m}_t).$$

Because the two factors

$$[e^{i(-\phi(\mathbf{l})+\phi(\mathbf{l}+\mathbf{k})-\phi(-\mathbf{l}+\mathbf{m}_t)+\phi(-\mathbf{l}-\mathbf{k}+\mathbf{m}_t))} - 1], \quad [e^{i(-\phi(\mathbf{l}-\mathbf{k})+\phi(\mathbf{l})-\phi(-\mathbf{l}+\mathbf{k}+\mathbf{m}_t)+\phi(-\mathbf{l}+\mathbf{m}_t))} - 1]$$

differ with their complex conjugates in a random manner independently from  $f_t$ , both (132) and (133) are almost surely false unless

$$(134) \quad \overline{f_t(\mathbf{l})} f_t(\mathbf{l} + \mathbf{k}) = 0, \quad f_t(\mathbf{l}) \overline{f_t(\mathbf{l} - \mathbf{k})} = 0,$$

$$(135) \quad f_t(-\mathbf{l} + \mathbf{m}_t) \overline{f_t(-\mathbf{l} - \mathbf{k} + \mathbf{m}_t)} = 0, \quad \overline{f_t(-\mathbf{l} + \mathbf{m}_t)} f_t(-\mathbf{l} + \mathbf{k} + \mathbf{m}_t) = 0.$$

On the other hand, if  $\mathbf{l} = \mathbf{m}_t/2$  but  $\mathbf{k} \neq \mathbf{0}$ , then

$$(136) \quad \mathbf{l} + \mathbf{k} = -\mathbf{l} + \mathbf{k} + \mathbf{m}_t \neq -\mathbf{l} - \mathbf{k} + \mathbf{m}_t = \mathbf{l} - \mathbf{k},$$

and hence (129) = 0 becomes

$$0 = [e^{i(-2\phi(\mathbf{l})+\phi(\mathbf{l}+\mathbf{k})+\phi(\mathbf{l}-\mathbf{k}))} - 1] \overline{f_t(\mathbf{l})} f_t(\mathbf{l} + \mathbf{k}) + [e^{i(-2\phi(\mathbf{l})+\phi(\mathbf{l}+\mathbf{k})+\phi(\mathbf{l}-\mathbf{k}))} - 1] \overline{f_t(\mathbf{l} - \mathbf{k})} f_t(\mathbf{l})$$

implying (134). In other words, (134) holds true for  $\mathbf{k} \neq \mathbf{0}$ .

Now we show that (134) for  $\mathbf{k} \neq \mathbf{0}$  implies that  $f_t$  has at most one nonzero pixel.

Suppose that  $f_t(\mathbf{l}) \neq 0$  for some  $\mathbf{l}$ . Then by (134),  $f_t(\mathbf{n}) = 0$  for all other  $\mathbf{n} \neq \mathbf{l}$ , i.e.  $f_t$  is a singleton which contradicts the assumption that  $\text{supp}(f_t)$  is not a subset of a line.

Consequently the second alternative in (121) is false almost surely. The proof is complete.

#### APPENDIX D. PROOF OF THEOREM 7.2

The argument is a more detailed, corrected exposition of that for Theorem 5.1 in [26] where the condition  $\widehat{f}(0) \neq 0$  is missing.

Recall that for  $(\mathbf{k}, \mathbf{k}') \in C_{\mathbf{t}, \mathbf{t}'} := L_{\mathbf{t}, \mathbf{t}'}(f) \cap L_{\mathbf{t}, \mathbf{t}'}(g)$

$$\begin{aligned}\widehat{g}_{\mathbf{t}'}^*(\mathbf{k}')e^{-i2\pi\mathbf{k}'\cdot\mathbf{l}_{\mathbf{t}'}/p} &= \widehat{g}_{\mathbf{t}}^*(\mathbf{k})e^{-i2\pi\mathbf{k}\cdot\mathbf{l}_{\mathbf{t}}/p} \\ \widehat{f}_{\mathbf{t}'}^*(\mathbf{k}')e^{-i2\pi\mathbf{k}'\cdot\mathbf{l}_{\mathbf{t}'}/p} &= \widehat{f}_{\mathbf{t}}^*(\mathbf{k})e^{-i2\pi\mathbf{k}\cdot\mathbf{l}_{\mathbf{t}}/p}.\end{aligned}$$

Suppose that the first alternative in (121) holds true for  $\mathbf{t}'$ , i.e.

$$(137) \quad g_{\mathbf{t}'}^*(\mathbf{n}) = e^{i\theta_{\mathbf{t}'}} f_{\mathbf{t}'}^*(\mathbf{n} + \mathbf{m}_{\mathbf{t}'}) \lambda_{\mathbf{t}'}(\mathbf{n} + \mathbf{m}_{\mathbf{t}'})$$

with

$$\lambda_{\mathbf{t}'}(\mathbf{n}) = \mu(\mathbf{n}) / \mu(\mathbf{n} - \mathbf{m}_{\mathbf{t}'}),$$

implying

$$\widehat{g}_{\mathbf{t}'}^*(\mathbf{k}') = e^{i\theta_{\mathbf{t}'}} e^{i2\pi\mathbf{m}_{\mathbf{t}'}\cdot\mathbf{k}'/p} (\widehat{f}_{\mathbf{t}'}^* \star \widehat{\lambda}_{\mathbf{t}'})(\mathbf{k}')$$

where  $\star$  denotes the discrete convolution over  $\mathbb{Z}_p^2$ .

We now prove that the second alternative in (121) can not hold for  $\mathbf{t}$ . Otherwise, for some  $\mathbf{m}_{\mathbf{t}}$

$$(138) \quad g_{\mathbf{t}}^*(\mathbf{n}) = e^{i\theta_{\mathbf{t}}} \overline{f_{\mathbf{t}}^*(-\mathbf{n} + \mathbf{m}_{\mathbf{t}}) \nu_{\mathbf{t}}(-\mathbf{n} + \mathbf{m}_{\mathbf{t}})}$$

with

$$\nu_{\mathbf{t}}(\mathbf{n}) = \mu(\mathbf{n}) / \overline{\mu(-\mathbf{n} + \mathbf{m}_{\mathbf{t}})}.$$

implying

$$\widehat{g}_{\mathbf{t}}^*(\mathbf{k}) = \overline{(\widehat{f}_{\mathbf{t}}^* \star \widehat{\nu}_{\mathbf{t}})(\mathbf{k})} e^{-i2\pi\mathbf{m}_{\mathbf{t}}\cdot\mathbf{k}/p}.$$

For  $(\mathbf{k}, \mathbf{k}') \in C_{\mathbf{t}, \mathbf{t}'}$ ,

$$e^{i\theta_{\mathbf{t}'}} e^{i2\pi(\mathbf{m}_{\mathbf{t}'} - \mathbf{l}_{\mathbf{t}'})\cdot\mathbf{k}'/p} \widehat{f}_{\mathbf{t}'}^* \star \widehat{\lambda}_{\mathbf{t}'}(\mathbf{k}') e^{-i2\pi\mathbf{k}'\cdot\mathbf{l}_{\mathbf{t}'}/p} = e^{i\theta_{\mathbf{t}}} e^{-i2\pi(\mathbf{m}_{\mathbf{t}} + \mathbf{l}_{\mathbf{t}})\cdot\mathbf{k}/p} \overline{\widehat{f}_{\mathbf{t}}^* \star \widehat{\nu}_{\mathbf{t}}(\mathbf{k})},$$

implying

$$(139) \quad \begin{aligned}0 &= e^{i\theta_{\mathbf{t}'}} e^{i2\pi(\mathbf{m}_{\mathbf{t}'} - \mathbf{l}_{\mathbf{t}'})\cdot\mathbf{k}'/p} \sum_{\mathbf{n} \in \mathbb{Z}_n^2} e^{i\phi(\mathbf{n})} e^{-i\phi(\mathbf{n} - \mathbf{m}_{\mathbf{t}'})} f_{\mathbf{t}'}^*(\mathbf{n}) e^{-i2\pi\mathbf{n}\cdot\mathbf{k}'/p} \\ &\quad - e^{i\theta_{\mathbf{t}}} e^{-i2\pi(\mathbf{m}_{\mathbf{t}} + \mathbf{l}_{\mathbf{t}})\cdot\mathbf{k}/p} \sum_{\mathbf{n} \in \mathbb{Z}_n^2} e^{-i\phi(\mathbf{n})} e^{-i\phi(-\mathbf{n} + \mathbf{m}_{\mathbf{t}})} \overline{f_{\mathbf{t}}^*(\mathbf{n})} e^{i2\pi\mathbf{n}\cdot\mathbf{k}/p}.\end{aligned}$$

We now show that eq. (139) can not hold for any  $\mathbf{m}_{\mathbf{t}'}, \mathbf{m}_{\mathbf{t}}$ .

For fixed  $\mathbf{l}$ , only one term in (139) contains  $e^{i\phi(\mathbf{l})}$ :

$$e^{i\theta_{\mathbf{t}'}} e^{i2\pi(\mathbf{m}_{\mathbf{t}'} - \mathbf{l}_{\mathbf{t}'})\cdot\mathbf{k}'/p} e^{i\phi(\mathbf{l})} e^{-i\phi(\mathbf{l} - \mathbf{m}_{\mathbf{t}'})} f_{\mathbf{t}'}^*(\mathbf{l}) e^{-i2\pi\mathbf{l}\cdot\mathbf{k}'/p}$$

which must vanish by itself following (139) unless the random factors cancel out, i.e.  $\mathbf{m}_{\mathbf{t}'} = 0$ .

If  $\mathbf{m}_{\mathbf{t}'} \neq 0$  then  $f_{\mathbf{t}'}^*(\mathbf{l}) = 0$  for all  $\mathbf{l}$ , contrary to the assumption of a non-line  $f_{\mathbf{t}'}^*$ . On the other hand, if  $\mathbf{m}_{\mathbf{t}'} = 0$ , the summands of the first sum in (139) are non-random (as  $e^{i\phi(\mathbf{n})}e^{-i\phi(\mathbf{n}-\mathbf{m}_{\mathbf{t}'})} = 1$ ) while those of the second sum are random (as  $e^{-i\phi(\mathbf{n})}e^{-i\phi(-\mathbf{n}+\mathbf{m}_{\mathbf{t}'})} = e^{-i\phi(\mathbf{n})-i\phi(-\mathbf{n})}$ ) for some  $\mathbf{n}$ . Consequently, both sums must vanish separately, in particular,

$$\sum_{\mathbf{n} \in \mathbb{Z}_n^2} f_{\mathbf{t}'}^*(\mathbf{n})e^{-i2\pi\mathbf{n}\cdot\mathbf{k}'/p} = \widehat{f}_{\mathbf{t}'}^*(\mathbf{k}') = 0, \quad (\mathbf{k}, \mathbf{k}') \in C_{\mathbf{t}, \mathbf{t}'},$$

implying  $\widehat{f}(0) = 0$  which violates our assumption.

Consequently, the only viable alternative for  $\mathbf{t}$  under (137) is

$$(140) \quad g_{\mathbf{t}}^*(\mathbf{n}) = e^{i\theta_{\mathbf{t}}} f_{\mathbf{t}}^*(\mathbf{n} + \mathbf{m}_{\mathbf{t}}) \lambda_{\mathbf{t}}(\mathbf{n} + \mathbf{m}_{\mathbf{t}}), \quad \forall \mathbf{t} \in \mathcal{T},$$

for some  $\mathbf{m}_{\mathbf{t}}$ .

For  $(\mathbf{k}, \mathbf{k}') \in C_{\mathbf{t}, \mathbf{t}'}$ ,

$$(141) \quad e^{i\theta_{\mathbf{t}}} e^{i2\pi(\mathbf{m}_{\mathbf{t}}-\mathbf{l}_{\mathbf{t}})\cdot\mathbf{k}} \widehat{f}_{\mathbf{t}}^* \star \widehat{\lambda}_{\mathbf{t}}(\mathbf{k}) = e^{i\theta_{\mathbf{t}'}} e^{i2\pi(\mathbf{m}_{\mathbf{t}'}-\mathbf{l}_{\mathbf{t}'})\cdot\mathbf{k}'} \widehat{f}_{\mathbf{t}'}^* \star \widehat{\lambda}_{\mathbf{t}'}(\mathbf{k}'),$$

implying

$$(142) \quad 0 = e^{i\theta_{\mathbf{t}}} e^{i2\pi(\mathbf{m}_{\mathbf{t}}-\mathbf{l}_{\mathbf{t}})\cdot\mathbf{k}/p} \sum_{\mathbf{n} \in \mathbb{Z}_n^2} e^{i\phi(\mathbf{n})} e^{-i\phi(\mathbf{n}-\mathbf{m}_{\mathbf{t}})} f_{\mathbf{t}}^*(\mathbf{n}) e^{-i2\pi\mathbf{n}\cdot\mathbf{k}/p} \\ - e^{i\theta_{\mathbf{t}'}} e^{i2\pi(\mathbf{m}_{\mathbf{t}'}-\mathbf{l}_{\mathbf{t}'})\cdot\mathbf{k}'/p} \sum_{\mathbf{n} \in \mathbb{Z}_n^2} e^{i\phi(\mathbf{n})} e^{-i\phi(\mathbf{n}-\mathbf{m}_{\mathbf{t}'})} f_{\mathbf{t}'}^*(\mathbf{n}) e^{-i2\pi\mathbf{n}\cdot\mathbf{k}'/p}.$$

Given  $\mathbf{l}$ , only the following two terms contain  $e^{i\phi(\mathbf{l})}$

$$e^{i\theta_{\mathbf{t}}} e^{i2\pi(\mathbf{m}_{\mathbf{t}}-\mathbf{l}_{\mathbf{t}})\cdot\mathbf{k}/p} e^{i\phi(\mathbf{l})} e^{-i\phi(\mathbf{l}-\mathbf{m}_{\mathbf{t}})} f_{\mathbf{t}}^*(\mathbf{l}) e^{-i2\pi\mathbf{l}\cdot\mathbf{k}/p} \\ - e^{i\theta_{\mathbf{t}'}} e^{i2\pi(\mathbf{m}_{\mathbf{t}'}-\mathbf{l}_{\mathbf{t}'})\cdot\mathbf{k}'/p} e^{i\phi(\mathbf{l})} e^{-i\phi(\mathbf{l}-\mathbf{m}_{\mathbf{t}'})} f_{\mathbf{t}'}^*(\mathbf{l}) e^{-i2\pi\mathbf{l}\cdot\mathbf{k}'/p}$$

which must vanish by (142) unless  $\mathbf{m}_{\mathbf{t}} = 0$  or  $\mathbf{m}_{\mathbf{t}'} = 0$ .

If  $\mathbf{m}_{\mathbf{t}} = \mathbf{m}_{\mathbf{t}'} = 0$ , then  $g_{\mathbf{t}}^*(\mathbf{n}) = e^{i\theta_{\mathbf{t}}} f_{\mathbf{t}}^*(\mathbf{n})$  and  $g_{\mathbf{t}'}^*(\mathbf{n}) = e^{i\theta_{\mathbf{t}'}} f_{\mathbf{t}'}^*(\mathbf{n})$  for all  $\mathbf{n}$ .

By Proposition 4.1  $\widehat{f}_{\mathbf{t}}(0) = \widehat{f}_{\mathbf{t}'}(0) = \widehat{f}(0) \neq 0$ , it follows from  $\widehat{g}_{\mathbf{t}}(0) = \widehat{g}_{\mathbf{t}'}(0)$  that  $\theta_{\mathbf{t}} = \theta_{\mathbf{t}'}$ .

If only one of them vanishes, say  $\mathbf{m}_{\mathbf{t}} = 0, \mathbf{m}_{\mathbf{t}'} \neq 0$ , then the first sum in (142) is non-random while the second sum is random and hence both must vanish separately. In particular

$$\sum_{\mathbf{n} \in \mathbb{Z}_n^2} f_{\mathbf{t}}^*(\mathbf{n}) e^{-i2\pi\mathbf{n}\cdot\mathbf{k}/p} = \widehat{f}_{\mathbf{t}}^*(\mathbf{k}) = 0, \quad (\mathbf{k}, \mathbf{k}') \in C_{\mathbf{t}, \mathbf{t}'}$$

implying  $\widehat{f}(0) = 0$  which violates our assumption.

The remaining case,  $\mathbf{m}_{\mathbf{t}} \neq 0$  &  $\mathbf{m}_{\mathbf{t}'} \neq 0$  is further split into two sub-cases:  $\mathbf{m}_{\mathbf{t}} \neq \mathbf{m}_{\mathbf{t}'}$  and  $\mathbf{m}_{\mathbf{t}} = \mathbf{m}_{\mathbf{t}'}$ .

Suppose  $\mathbf{m}_{\mathbf{t}} \neq \mathbf{m}_{\mathbf{t}'}$  and both are nonzero. Then the random factors in (142)

$$e^{i\phi(\mathbf{n})} e^{-i\phi(\mathbf{n}-\mathbf{m}_{\mathbf{t}})}, \quad e^{i\phi(\mathbf{m})} e^{-i\phi(\mathbf{m}-\mathbf{m}_{\mathbf{t}'})}$$

can not balance out to satisfy (142).

Consider the remaining undesirable possibility under (141):  $\mathbf{m}_t = \mathbf{m}_{t'} \neq 0$ . Let  $\mathbf{m}_0 := \mathbf{m}_t = \mathbf{m}_{t'}$ . Then (142) becomes

$$\begin{aligned} 0 &= e^{i\theta_t} e^{i2\pi(\mathbf{m}_0 - \mathbf{l}_t) \cdot \mathbf{k}/p} \sum_{\mathbf{n} \in \mathbb{Z}_n^2} e^{i\phi(\mathbf{n})} e^{-i\phi(\mathbf{n} - \mathbf{m}_0)} f_t^*(\mathbf{n}) e^{-i2\pi \mathbf{n} \cdot \mathbf{k}/p} \\ &\quad - e^{i\theta_{t'}} e^{i2\pi(\mathbf{m}_0 - \mathbf{l}_{t'}) \cdot \mathbf{k}'/p} \sum_{\mathbf{n} \in \mathbb{Z}_n^2} e^{i\phi(\mathbf{n})} e^{-i\phi(\mathbf{n} - \mathbf{m}_0)} f_{t'}^*(\mathbf{n}) e^{-i2\pi \mathbf{n} \cdot \mathbf{k}'/p} \\ &= \sum_{\mathbf{n} \in \mathbb{Z}_n^2} e^{i\phi(\mathbf{n})} e^{-i\phi(\mathbf{n} - \mathbf{m}_0)} \left[ e^{i\theta_t} e^{i2\pi(\mathbf{m}_0 - \mathbf{l}_t) \cdot \mathbf{k}/p} f_t^*(\mathbf{n}) e^{-i2\pi \mathbf{n} \cdot \mathbf{k}/p} \right. \\ &\quad \left. - e^{i\theta_{t'}} e^{i2\pi(\mathbf{m}_0 - \mathbf{l}_{t'}) \cdot \mathbf{k}'/p} f_{t'}^*(\mathbf{n}) e^{-i2\pi \mathbf{n} \cdot \mathbf{k}'/p} \right], \end{aligned}$$

implying

$$(143) \quad e^{i\theta_t} e^{i2\pi(\mathbf{m}_0 - \mathbf{l}_t) \cdot \mathbf{k}/p} f_t^*(\mathbf{n}) e^{-i2\pi \mathbf{n} \cdot \mathbf{k}/p} = e^{i\theta_{t'}} e^{i2\pi(\mathbf{m}_0 - \mathbf{l}_{t'}) \cdot \mathbf{k}'/p} f_{t'}^*(\mathbf{n}) e^{-i2\pi \mathbf{n} \cdot \mathbf{k}'/p}, \quad \forall \mathbf{n},$$

for  $(\mathbf{k}, \mathbf{k}') \in C_{t, t'}$ .

Rewriting (143) for  $f_t^*(\mathbf{n}) \neq 0$  (then  $f_{t'}^*(\mathbf{n}) \neq 0$ ), we have

$$e^{i2\pi(\mathbf{l}_{t'} \cdot \mathbf{k}' - \mathbf{l}_t \cdot \mathbf{k})/p} e^{i2\pi(\mathbf{m}_0 - \mathbf{n}) \cdot (\mathbf{k} - \mathbf{k}')/p} = e^{i(\theta_{t'} - \theta_t)} f_{t'}^*(\mathbf{n}) / f_t^*(\mathbf{n})$$

whose left hand side is a linear phase factor and whose right hand side is independent of  $(\mathbf{k}, \mathbf{k}') \in C_{t, t'}$ . Hence

$$\mathbf{l}_{t'} \cdot \mathbf{k}' - \mathbf{l}_t \cdot \mathbf{k} + (\mathbf{m}_0 - \mathbf{n}) \cdot (\mathbf{k} - \mathbf{k}') = a \quad \text{mod } p$$

for some constant  $a \in \mathbb{R}$  for all  $\mathbf{n}$  such that  $f_t^*(\mathbf{n}) f_{t'}^*(\mathbf{n}) \neq 0$ , and consequently, by (143)

$$(144) \quad e^{i\theta_t} f_t^*(\mathbf{n}) = e^{ia} e^{i\theta_{t'}} f_{t'}^*(\mathbf{n}), \quad \forall \mathbf{n}.$$

By the common line property,  $\theta_t = \theta_{t'} + a$  and  $f_t^* = f_{t'}^*$ .

Let us turn to the last undesirable alternative:

$$(145) \quad g_t^*(\mathbf{n}) \mu(\mathbf{n}) = e^{i\theta_t} \overline{f_t^*(-\mathbf{n} + \mathbf{m}_t) \mu(-\mathbf{n} + \mathbf{m}_t)},$$

$$(146) \quad g_{t'}^*(\mathbf{n}) \mu(\mathbf{n}) = e^{i\theta_{t'}} \overline{f_{t'}^*(-\mathbf{n} + \mathbf{m}_{t'}) \mu(-\mathbf{n} + \mathbf{m}_{t'})}.$$

For  $(\mathbf{k}, \mathbf{k}') \in C_{t, t'}$ ,

$$e^{i\theta_{t'}} e^{-i2\pi(\mathbf{m}_{t'} + \mathbf{l}_{t'}) \cdot \mathbf{k}'/p} \widehat{f_{t'}^*} \star \widehat{\nu}_{t'}(\mathbf{k}') = e^{i\theta_t} e^{-i2\pi(\mathbf{m}_t + \mathbf{l}_t) \cdot \mathbf{k}/p} \widehat{f_t^*} \star \widehat{\nu}_t(\mathbf{k}),$$

implying

$$(147) \quad \begin{aligned} 0 &= e^{i\theta_{t'}} e^{-i2\pi(\mathbf{m}_{t'} + \mathbf{l}_{t'}) \cdot \mathbf{k}'/p} \sum_{\mathbf{n} \in \mathbb{Z}_n^2} e^{-i\phi(\mathbf{n})} e^{-i\phi(-\mathbf{n} + \mathbf{m}_{t'})} \overline{f_{t'}^*(\mathbf{n})} e^{i2\pi \mathbf{n} \cdot \mathbf{k}'/p} \\ &\quad - e^{i\theta_t} e^{-i2\pi(\mathbf{m}_t + \mathbf{l}_t) \cdot \mathbf{k}/p} \sum_{\mathbf{n} \in \mathbb{Z}_n^2} e^{-i\phi(\mathbf{n})} e^{-i\phi(-\mathbf{n} + \mathbf{m}_t)} \overline{f_t^*(\mathbf{n})} e^{i2\pi \mathbf{n} \cdot \mathbf{k}/p}. \end{aligned}$$

For fixed  $\mathbf{l}$ , only the following four terms contain  $e^{-i\phi(\mathbf{l})}$

$$(148) \quad \begin{aligned} &e^{i\theta_{t'}} e^{-i2\pi(\mathbf{m}_{t'} + \mathbf{l}_{t'}) \cdot \mathbf{k}'/p} e^{-i\phi(\mathbf{l})} \left[ e^{-i\phi(\mathbf{l} - \mathbf{m}_{t'})} \overline{f_{t'}^*(\mathbf{l})} e^{i2\pi \mathbf{l} \cdot \mathbf{k}'/p} + e^{-i\phi(\mathbf{m}_{t'} - \mathbf{l})} \overline{f_{t'}^*(\mathbf{m}_{t'} - \mathbf{l})} e^{i(\mathbf{m}_{t'} - \mathbf{l}) \cdot \mathbf{k}'/p} \right] \\ &- e^{i\theta_t} e^{-i2\pi(\mathbf{m}_t + \mathbf{l}_t) \cdot \mathbf{k}/p} e^{-i\phi(\mathbf{l})} \left[ e^{-i\phi(\mathbf{l} - \mathbf{m}_t)} \overline{f_t^*(\mathbf{l})} e^{i2\pi \mathbf{l} \cdot \mathbf{k}/p} + e^{-i\phi(\mathbf{m}_t - \mathbf{l})} \overline{f_t^*(\mathbf{m}_t - \mathbf{l})} e^{i(\mathbf{m}_t - \mathbf{l}) \cdot \mathbf{k}/p} \right] \end{aligned}$$



which must sum to zero by (147).

But the expression in (148) can not be zero unless  $\mathbf{m}_t = \mathbf{m}_{t'}(:= \mathbf{m}_0)$  and the following equations hold for  $(\mathbf{k}, \mathbf{k}') \in C_{t,t'}$ ,

$$(149) \quad e^{i\theta_{t'}} e^{-i2\pi(\mathbf{m}_0 + \mathbf{l}_{t'}) \cdot \mathbf{k}' / p} \overline{f_{t'}^*(\mathbf{1})} e^{i2\pi \mathbf{1} \cdot \mathbf{k}' / p} = e^{i\theta_t} e^{-i2\pi(\mathbf{m}_0 + \mathbf{l}_t) \cdot \mathbf{k} / p} \overline{f_t^*(\mathbf{1})} e^{i2\pi \mathbf{1} \cdot \mathbf{k} / p}$$

$$(150) \quad e^{i\theta_{t'}} e^{-i2\pi(\mathbf{m}_0 + \mathbf{l}_{t'}) \cdot \mathbf{k}' / p} \overline{f_{t'}^*(\mathbf{m}_0 - \mathbf{1})} e^{i2\pi(\mathbf{m}_0 - \mathbf{1}) \cdot \mathbf{k}' / p} = e^{i\theta_t} e^{-i2\pi(\mathbf{m}_0 + \mathbf{l}_t) \cdot \mathbf{k} / p} \overline{f_t^*(\mathbf{m}_0 - \mathbf{1})} e^{i2\pi(\mathbf{m}_0 - \mathbf{1}) \cdot \mathbf{k} / p}.$$

For  $f_{t'}^*(\mathbf{1})f_t^*(\mathbf{1}) \neq 0$ , (149) implies that for  $(\mathbf{k}, \mathbf{k}') \in C_{t,t'}$  and some constant  $a \in \mathbb{R}$ ,

$$(151) \quad a + (\mathbf{m}_0 + \mathbf{l}_{t'} - \mathbf{1}) \cdot \mathbf{k}' = (\mathbf{m}_0 + \mathbf{l}_t - \mathbf{1}) \cdot \mathbf{k} \pmod{p},$$

and consequently,

$$(152) \quad e^{-i\theta_{t'}} e^{-i\theta_0} f_{t'}^*(\mathbf{1}) = e^{-i\theta_t} f_t^*(\mathbf{1}).$$

The same analysis for (150) leads to the equivalent equation (152). By the common line property,  $\theta_t = \theta_{t'} + a$  and  $f_t^* = f_{t'}^*$ .

The two undesirable ambiguities (144) and (152) is summarized by the second alternative in (51). The proof is complete.

DEPARTMENT OF MATHEMATICS, UNIVERSITY OF CALIFORNIA, DAVIS, CALIFORNIA  
95616, USA. EMAIL: FANNJIANG@MATH.UCDAVIS.EDU