

Phase Retrieval with Random Mask

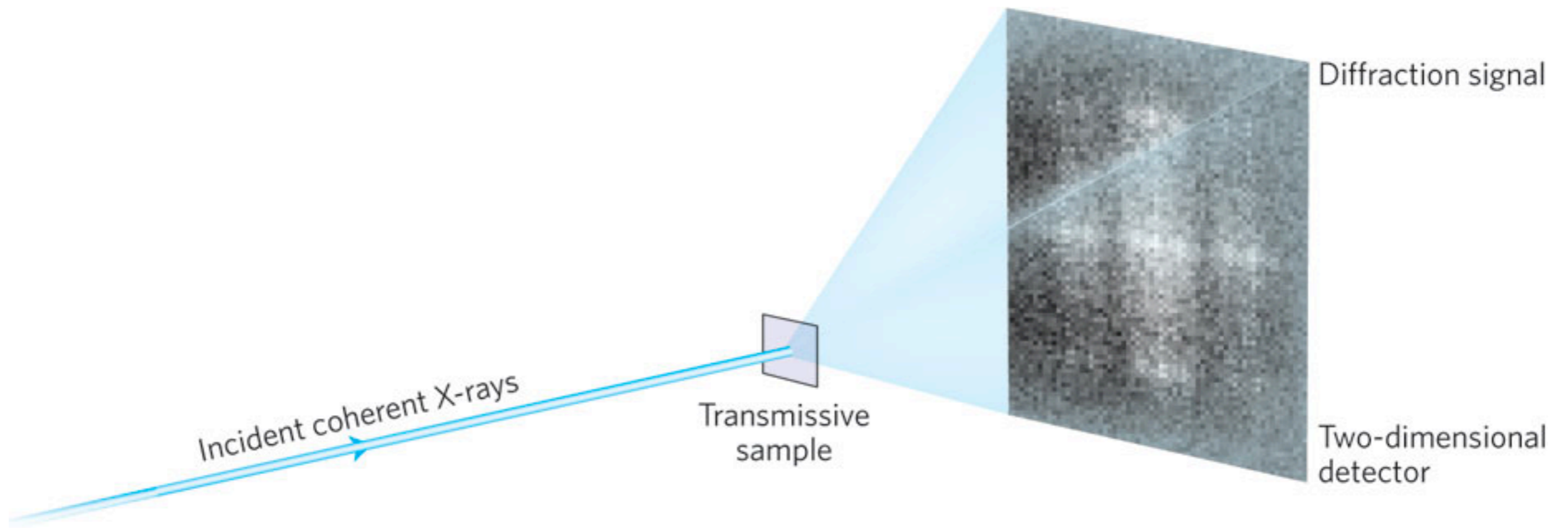
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Lensless coherent imaging



Phase retrieval with oversampling

Discrete finite objects

Let $\mathbf{n} = (n_1, n_2) \in \mathbb{Z}^2$ and $\mathbf{z} = (z_1, z_2) \in \mathbb{C}^2$.

multi-index : $\mathbf{z}^{\mathbf{n}} = z_1^{n_1} z_2^{n_2}$

Let the object be represented by $f(\mathbf{n}), \mathbf{n} \leq \mathbf{N} = (N, N)$

Fourier transform describes **wave propagation**

$$F(e^{i2\pi w_1}, e^{i2\pi w_2}) = \sum_{\mathbf{n}} f(\mathbf{n}) e^{-i2\pi \mathbf{n} \cdot \mathbf{w}}$$

Analytic continuation \implies z -transform

$$F(\mathbf{z}) = \sum_{\mathbf{n}} f(\mathbf{n}) \mathbf{z}^{-\mathbf{n}}.$$

Discrete phase retrieval problem:

Determine $f(\mathbf{n})$ from Fourier magnitude data

$$|F(\mathbf{w})|, \quad \forall \mathbf{w} = (e^{i2\pi w_1}, e^{i2\pi w_2}) \in [0, 1]^2$$

Phase = Face ?



$$f_L = \text{Lena}$$
$$F_L(\mathbf{w}) = |F_L(\mathbf{w})|e^{i\theta_L(\mathbf{w})}$$

$$F_1(\mathbf{w}) = |F_B(\mathbf{w})|e^{i\theta_L(\mathbf{w})}$$
$$f_1 = |\Phi^* F_1|$$

$$f_B = \text{Barbara}$$
$$F_B(\mathbf{w}) = |F_B(\mathbf{w})|e^{i\theta_B(\mathbf{w})}$$

$$F_2(\mathbf{w}) = |F_L(\mathbf{w})|e^{i\theta_B(\mathbf{w})}$$
$$f_2 = |\Phi^* F_2|$$

Phase = Face !



$$F_1(\mathbf{w}) = |F_B(\mathbf{w})|e^{i\theta_L(\mathbf{w})}$$
$$f_1 = |\Phi^* F_1|$$

$$F_2(\mathbf{w}) = |F_L(\mathbf{w})|e^{i\theta_B(\mathbf{w})}$$
$$f_2 = |\Phi^* F_2|$$

Fourier magnitude data:

$$\begin{aligned} |F(\mathbf{w})|^2 &= \sum_{\mathbf{n}=-N}^N \sum_{\mathbf{m}} f(\mathbf{m} + \mathbf{n}) f^*(\mathbf{m}) e^{-i2\pi\mathbf{n}\cdot\mathbf{w}} \\ &= \sum_{\mathbf{n}=-N}^N C_f(\mathbf{n}) e^{-i2\pi\mathbf{n}\cdot\mathbf{w}} \end{aligned}$$

where

$$C_f(\mathbf{n}) = \sum_{\mathbf{m}} f(\mathbf{m} + \mathbf{n}) f^*(\mathbf{m})$$

is the **autocorrelation** function of f .

Fourier magnitude data contain complete information about autocorrelation function.

Sampling Theorem:

$\text{supp}(C_f) \subset [-N, N]^2 \implies [0, 1]^2$ is reduced to the Nyquist grid

$$\mathcal{M} = \left\{ (k_1, k_2) : k_j = 0, \frac{1}{2N+1}, \frac{2}{2N+1}, \dots, \frac{2N}{2N+1} \right\}$$

Harmonic (50%) & non-harmonic (50%) Fourier coefficients

Oversampling ratio

$$\sigma = \frac{\text{Fourier magnitude data number}}{\text{unknown image pixel number}}$$

Standard ratio: $\sigma = 2^d$

Compressed measurement: $\sigma < 2^d$

Trivial ambiguities

Autocorrelation:

$$C_f(\mathbf{n}) = \sum_{\mathbf{m}+\mathbf{n} \in \mathcal{N}} f(\mathbf{m} + \mathbf{n}) f^*(\mathbf{m})$$

Invariant under:

(i) global phase,

$$f(\mathbf{n}) \longrightarrow e^{i\theta} f(\mathbf{n}), \quad \text{for some } \theta \in [0, 2\pi],$$

(ii) spatial translation

$$f(\mathbf{n}) \longrightarrow f(\mathbf{n} + \mathbf{m}), \quad \text{some } \mathbf{m} \in \mathbb{Z}^2$$

(iii) conjugate inversion (twin image)

$$f(\mathbf{n}) \longrightarrow f^*(\mathbf{N} - \mathbf{n}).$$

Nontrivial ambiguity

THEOREM (Hayes 82, Pitts-Greenleaf 03)

Let the z -transform $F(z)$ of a finite complex-valued sequence $\{f(n)\}$ be given by

$$F(z) = \alpha z^{-m} \prod_{k=1}^p F_k(z), \quad m \in \mathbb{N}^2, \alpha \in \mathbb{C}$$

where $F_k, k = 1, \dots, p$ are nontrivial irreducible polynomials. Let $G(z)$ be the z -transform of another finite sequence $g(n)$. Suppose $|F(w)| = |G(w)|, \forall w \in [0, 1]^2$. Then $G(z)$ must have the form

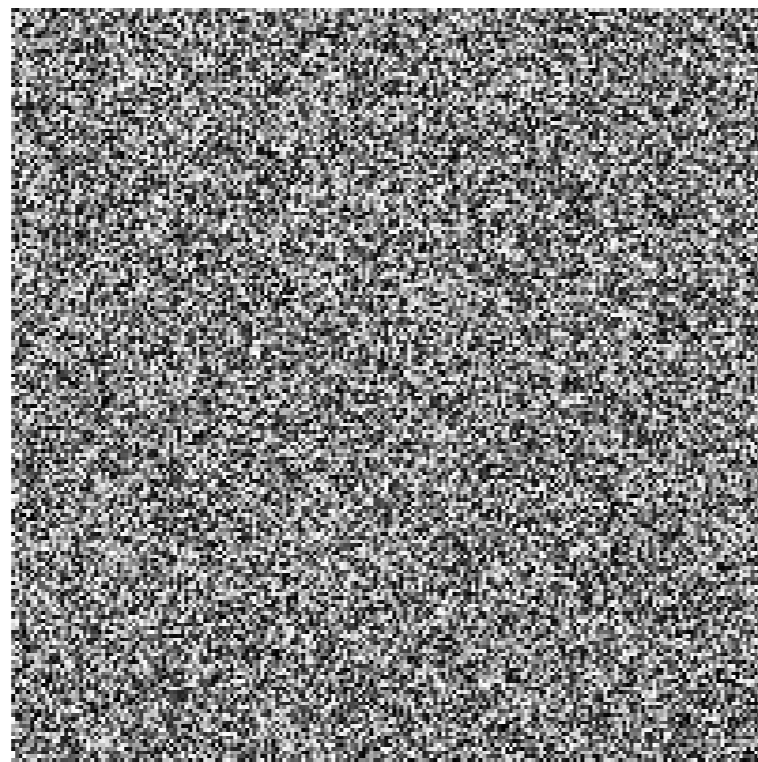
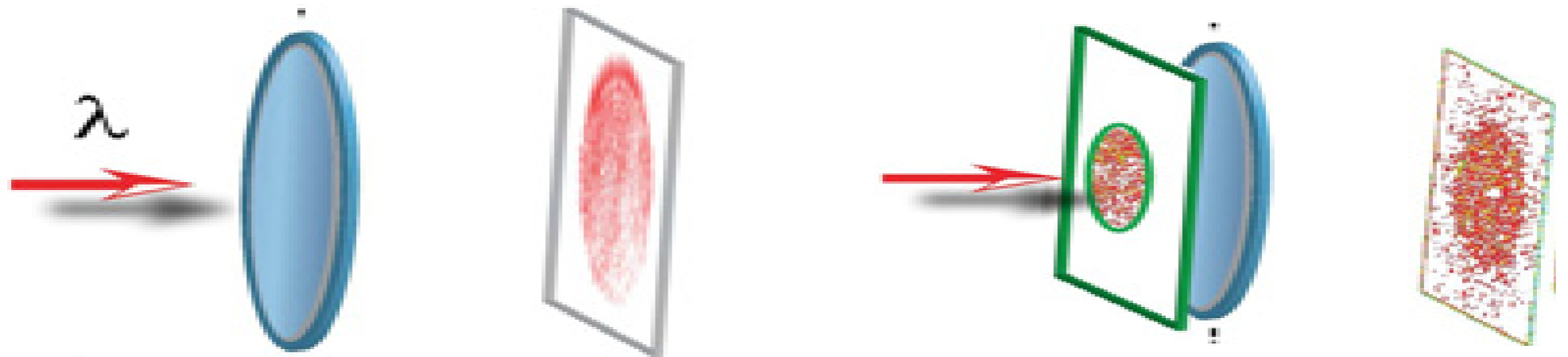
$$G(z) = |\alpha| e^{i\theta} z^{-p} \left(\prod_{k \in I} F_k(z) \right) \left(\prod_{k \in I^c} F_k^*(1/z^*) \right), \quad p \in \mathbb{N}^2, \theta \in \mathbb{R}$$

where I is a subset of $\{1, 2, \dots, p\}$.

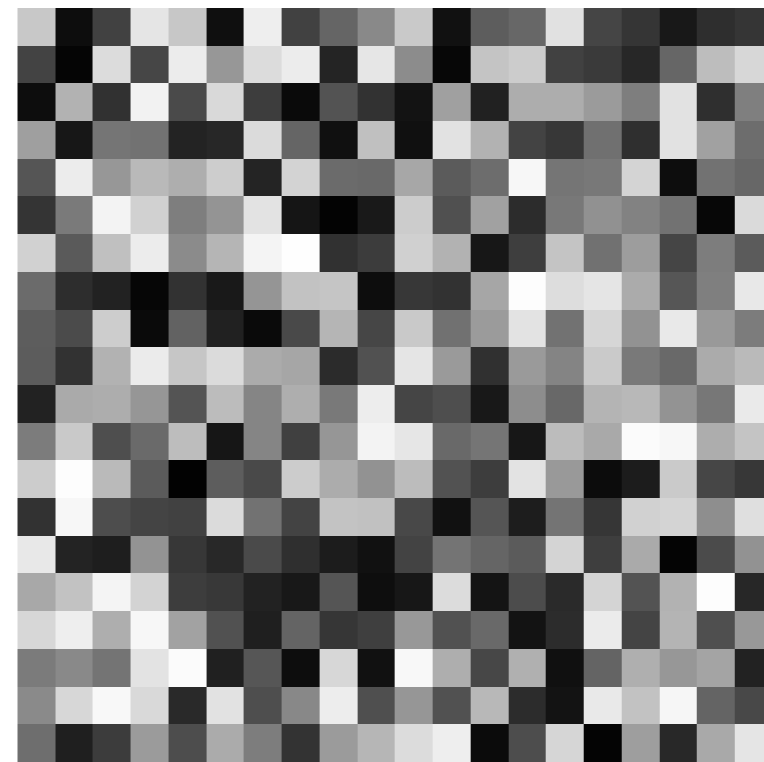
Nontrivial ambiguity: Partial conjugate inversion on factors.

Random mask

Coded aperture imaging



(a) 200×200 HRM



(b) 20×20 LRM

Random illumination

$$\tilde{f}(n) = f(n)\lambda(n) \quad (\text{illuminated object})$$

$\lambda(n)$, representing the illumination field, is a **known** sequence of samples of random variables.

Let $\lambda(n)$ be continuous random variables with respect to the Lebesgue measure on \mathbb{S}^1 (the unit circle), \mathbb{R} or \mathbb{C} .

Case of \mathbb{S}^1 can be facilitated by a **random phase modulator** with

$$\lambda(n) = e^{i\phi(n)}$$

where $\phi(n)$ are continuous random variables on $[0, 2\pi]$.

Case of \mathbb{R} : **random amplitude modulator.**

Case of \mathbb{C} : both phase and amplitude modulations.

Irreducibility

THEOREM. Suppose the object $\{f(n)\}$ is **rank ≥ 2** . Then the z -transform of the illuminated object $f(n)\lambda(n)$ is irreducible with probability one.

False for **rank 1** objects: Fundamental Thm of Algebra

$$\sigma = \frac{\text{Fourier magnitude data number}}{\text{unknown image pixel number}} = 2^d$$

Absolute uniqueness

THEOREM If $f(n)$ is **real and nonnegative** for every n then, with probability one, f is determined **absolutely** uniquely by the Fourier magnitude measurement on the lattice \mathcal{L} .

THEOREM Suppose the phases of the object belong to $[a, b] \subset [0, 2\pi]$. Then the solution to the Fourier phasing problem has a unique solution with probability

$$1 - |\mathcal{N}| \left| \frac{b - a}{2\pi} \right|^{[S/2]} .$$

Objects w/o constraint

THEOREM Suppose that $\{\lambda_1(n)\}$ are i.i.d. In addition, if either of the following holds true

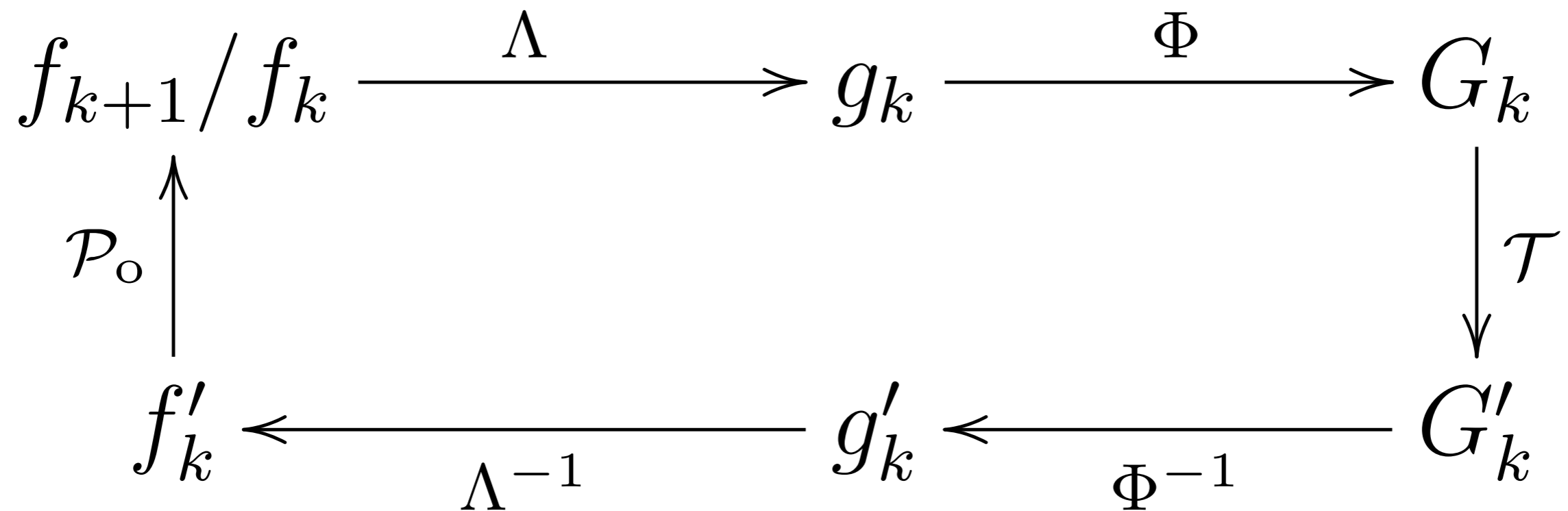
(i) $\{\lambda_2(n)\}$ are i.i.d. continuous random variables with respect to the Lebesgue measure on S^1 , \mathbb{R} or \mathbb{C} and $\{\lambda_2(n)\}$ are **independent** of $\{\lambda_1(n)\}$;

(ii) $\{\lambda_2(n)\}$ are **deterministic**;

then with probability one $f(n)$ is uniquely determined, **up to a constant phase factor**, by the Fourier magnitude measurements with two masks λ_1 and λ_2 .

Alternating projections

Gerchberg-Saxton; Error Reduction (Fienup)



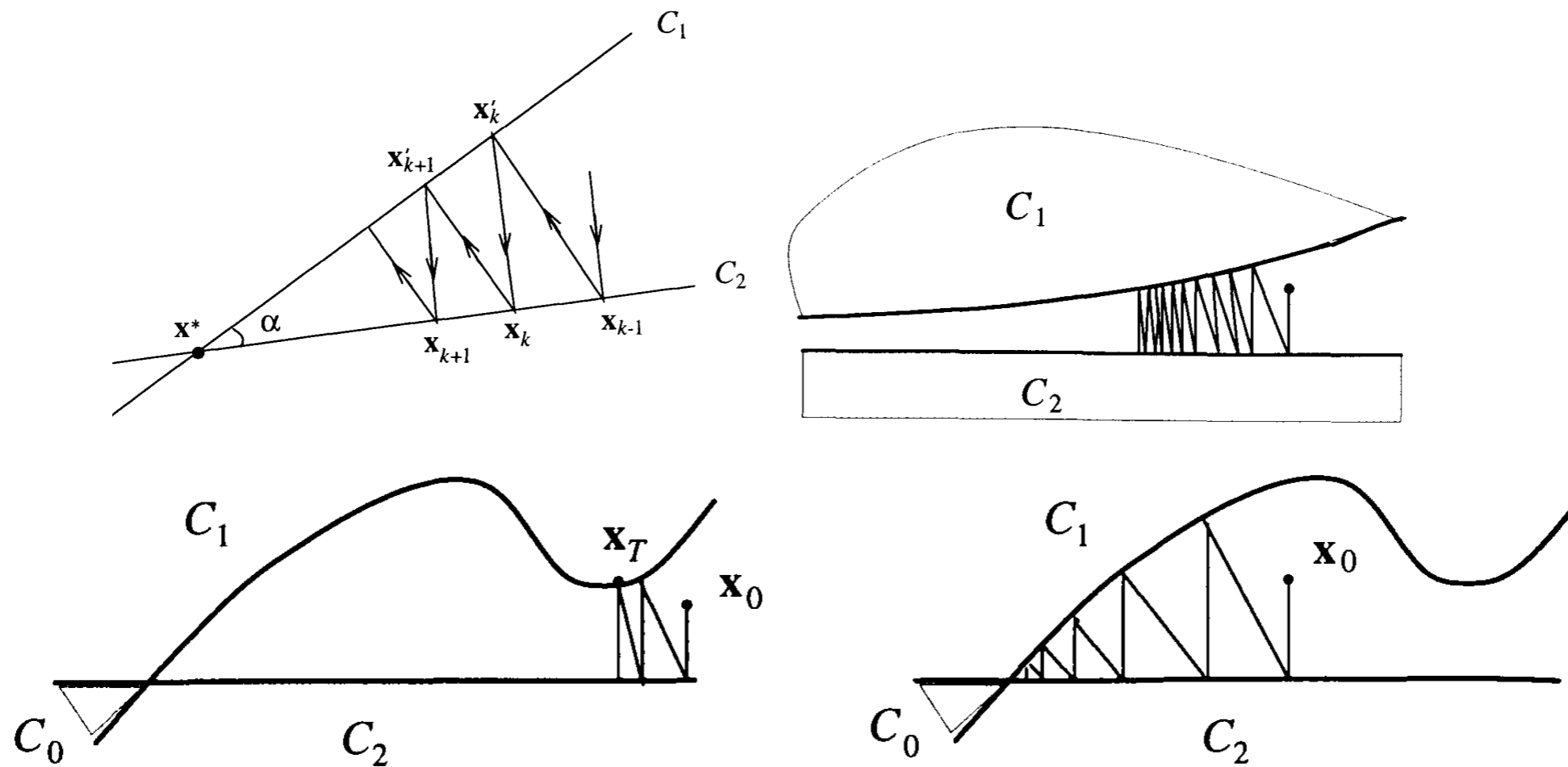
Multiple masks

$$\mathcal{P}_1 = \Lambda_1^{-1} \Phi^{-1} \mathcal{T}_1 \Phi \Lambda_1$$

$$\mathcal{P}_2 = \Lambda_2^{-1} \Phi^{-1} \mathcal{T}_2 \Phi \Lambda_2.$$

$$f_{k+1} = \mathcal{P}_0 \mathcal{P}_2 \mathcal{P}_1 f_k.$$

Error Reduction (Gerchberg-Saxton)



Bregman 65: **convex** constraints \implies convergence to **a feasible solution**.

Fourier magnitude data are a non-convex constraint!

Nonconvexity or nonuniqueness ?

Convergence

THEOREM

Let the object f be rank ≥ 2 . Let h be a fixed point of $\mathcal{P}_0\mathcal{P}_f$ such that $\mathcal{P}_f h$ satisfies the **zero-padding** condition.

(a) If f is real-valued, $h = \pm f$ with probability one,

(b) If f satisfies the sector condition, then $h = e^{i\nu} f$, with probability at least

$$1 - |\mathcal{N}| \left| \frac{b-a}{2\pi} \right|^{[S/2]}.$$

LEMMA Suppose the object constraint is **convex**. Then

$$\|\mathcal{P}_f\{f_{k+1}\} - f_{k+1}\| \leq \|\mathcal{P}_f\{f_k\} - f_k\|.$$

The equality holds if and only if $f_{k+1} = f_k$.

Error metrics

Relative error

$$e(\hat{f}) = \begin{cases} \|f - \hat{f}\| / \|f\| \\ \min_{\nu \in [0, 2\pi)} \|f - e^{i\nu} \hat{f}\| / \|f\| \end{cases}$$

Relative residual

$$r(\hat{f}) = \frac{\|Y - |\Phi \Lambda \mathcal{P}_o\{\hat{f}\}| \|}{\|Y\|}$$

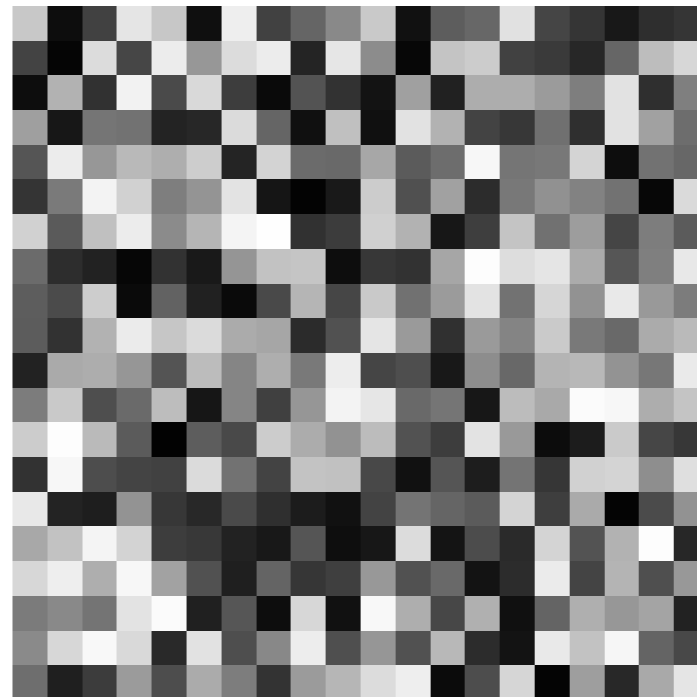
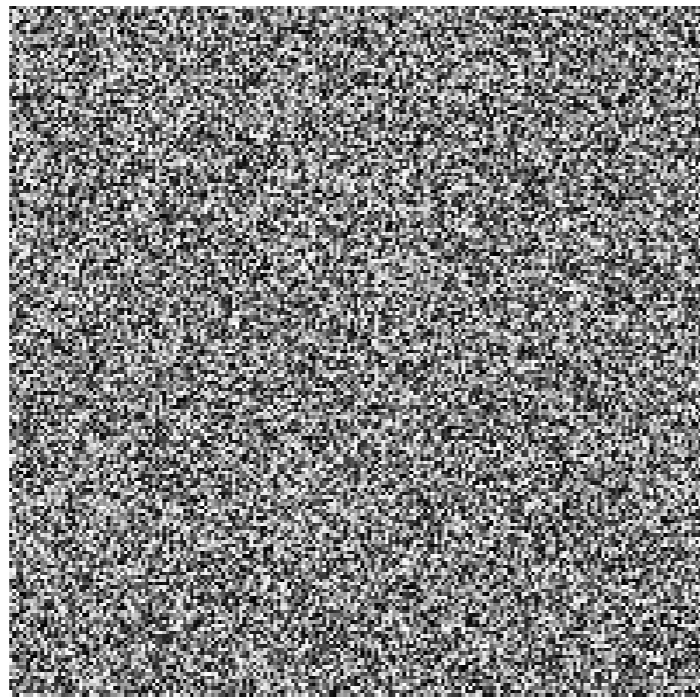
Objects with Loose Support

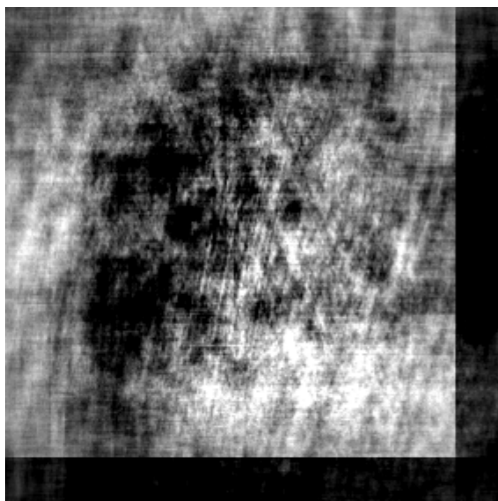


(a)

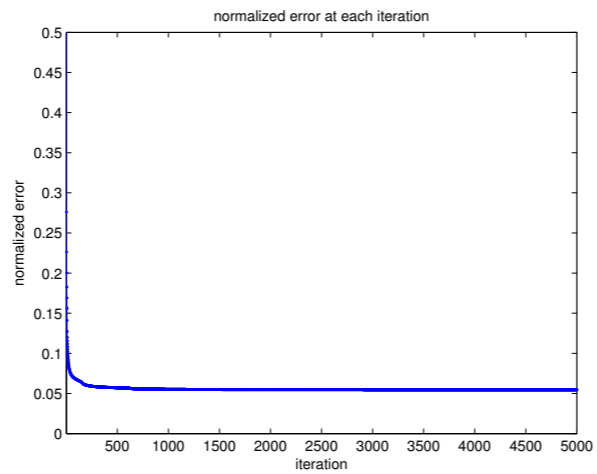


(b)





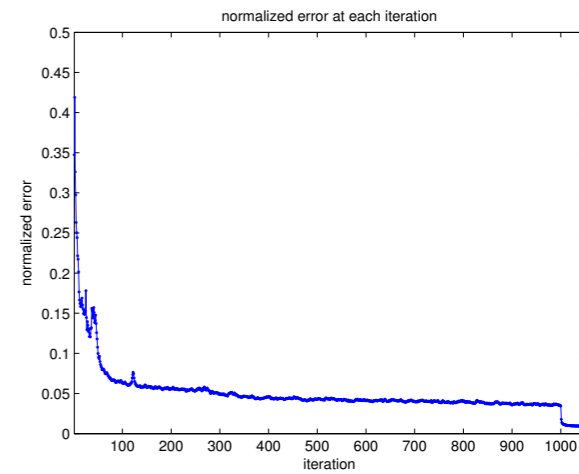
(a)



(b)



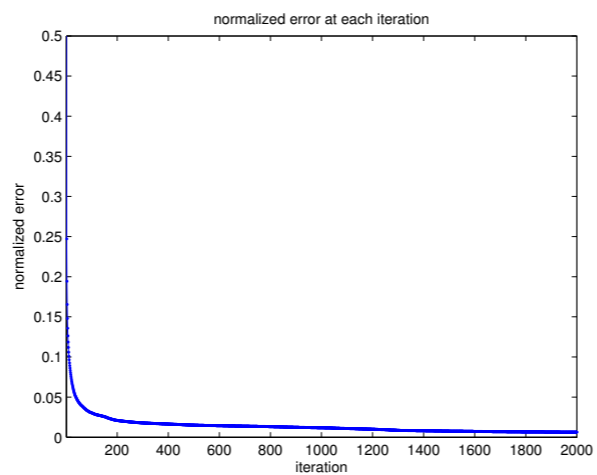
(c)



(d)



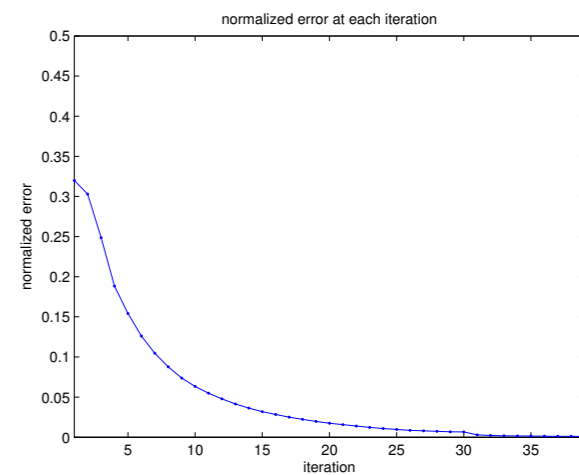
(e)



(f)



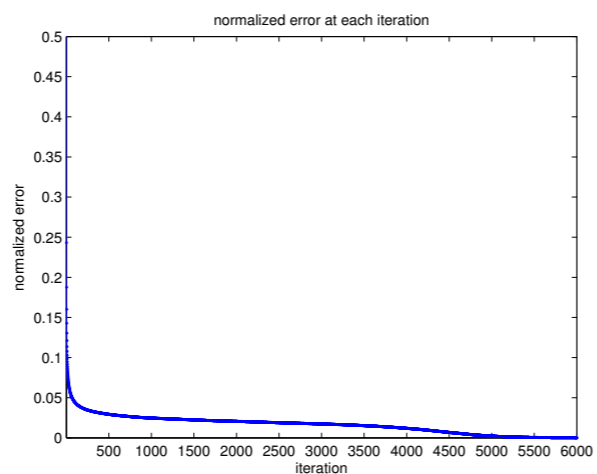
(g)



(h)



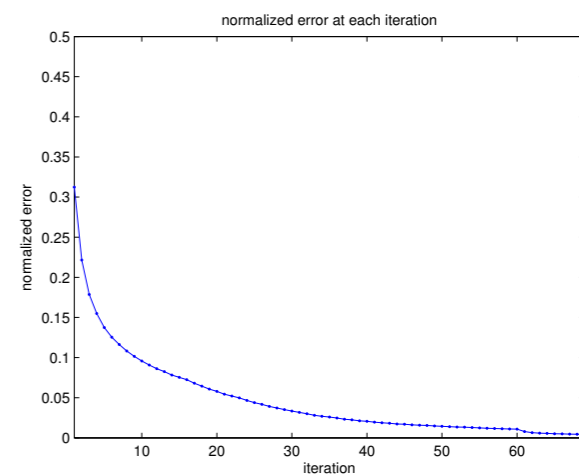
(i)



(j)

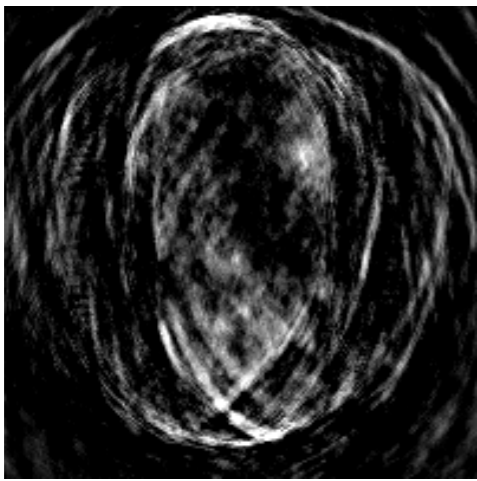


(k)

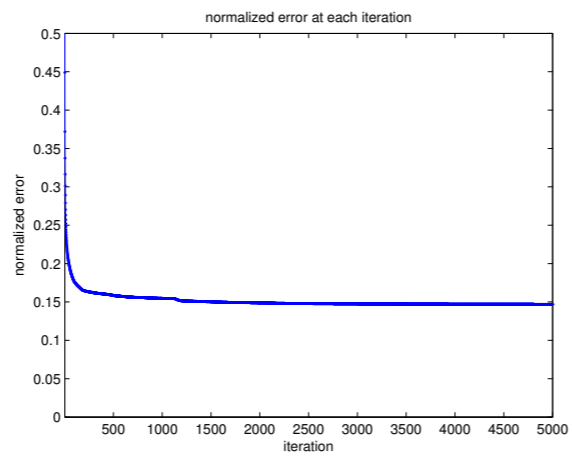


(l)

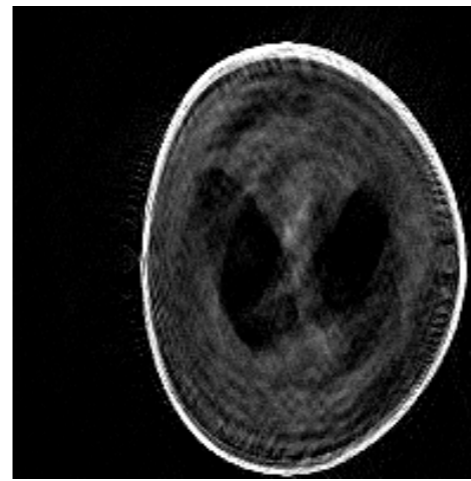
(e)-(h) Low resolution 40 x 40-block mask with OR=2
(i)-(l) High resolution mask with OR=1



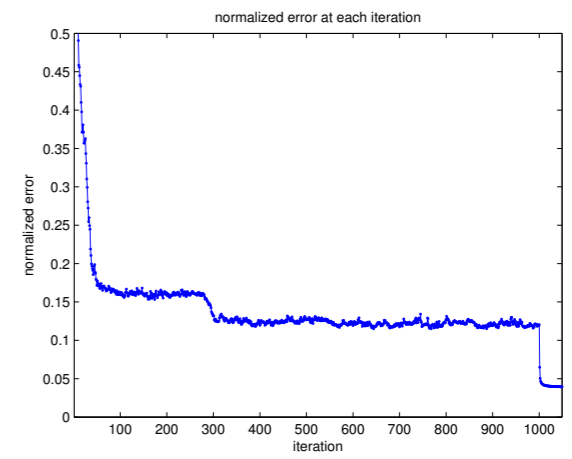
(a)



(b)



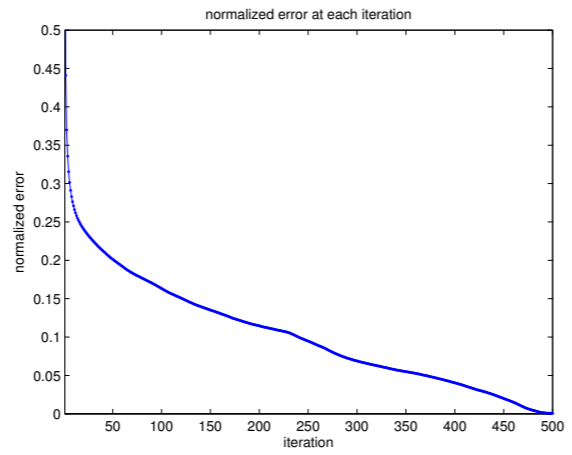
(c)



(d)



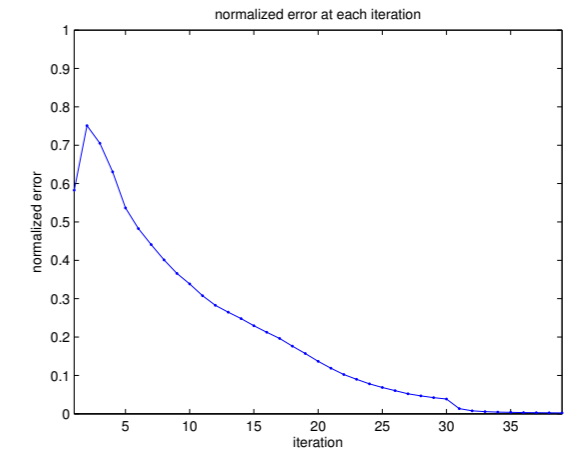
(e)



(f)



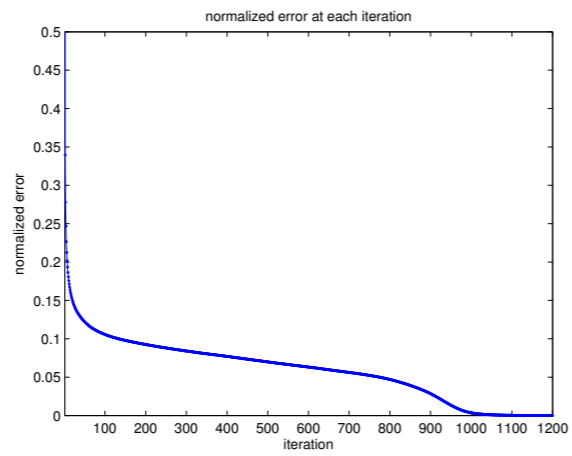
(g)



(h)



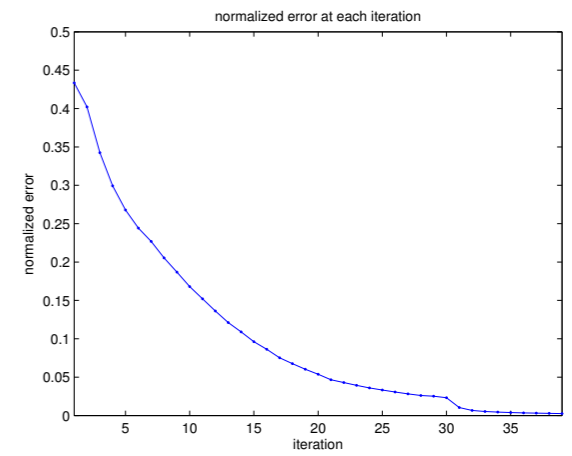
(i)



(j)



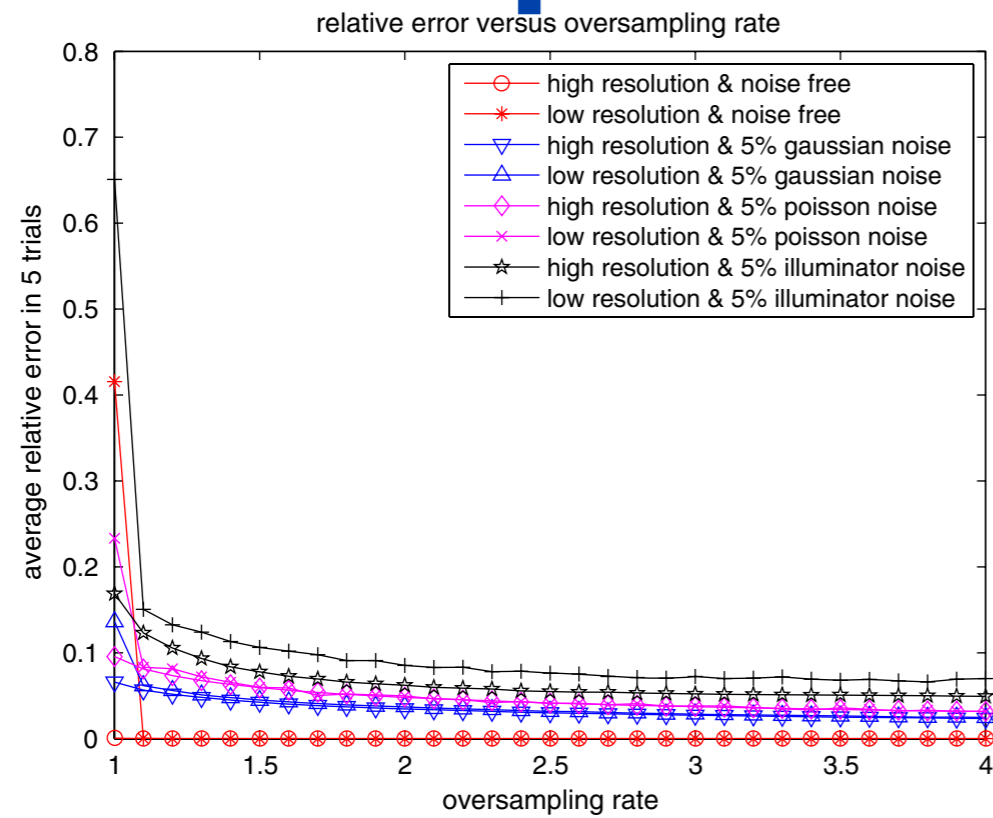
(k)



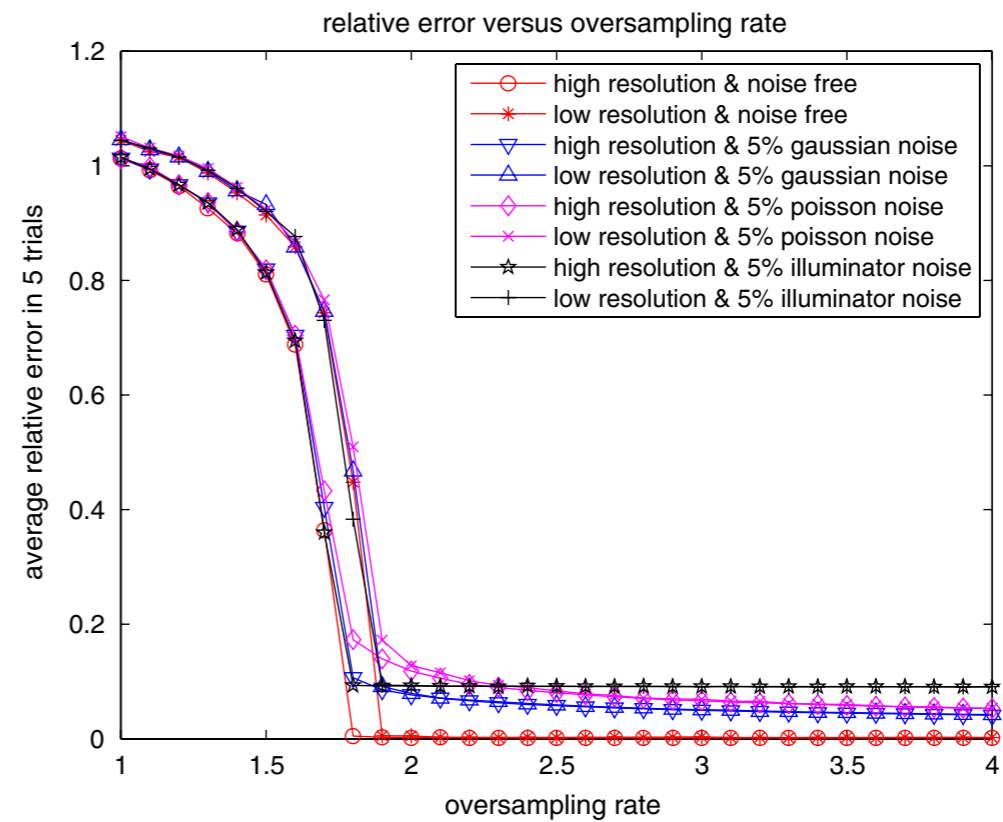
(l)

(e) - (h) Low resolution 40 x 40-block mask with OR=2
(i) - (l) High resolution mask with OR=1

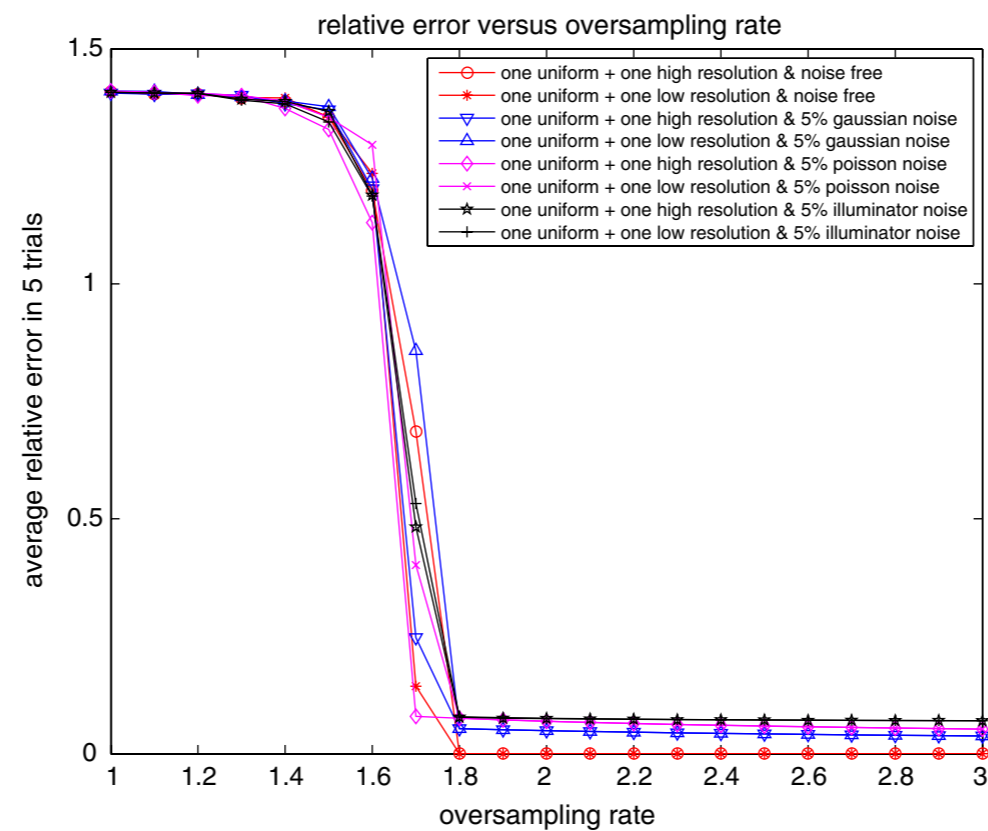
Compressed measurement



(a)



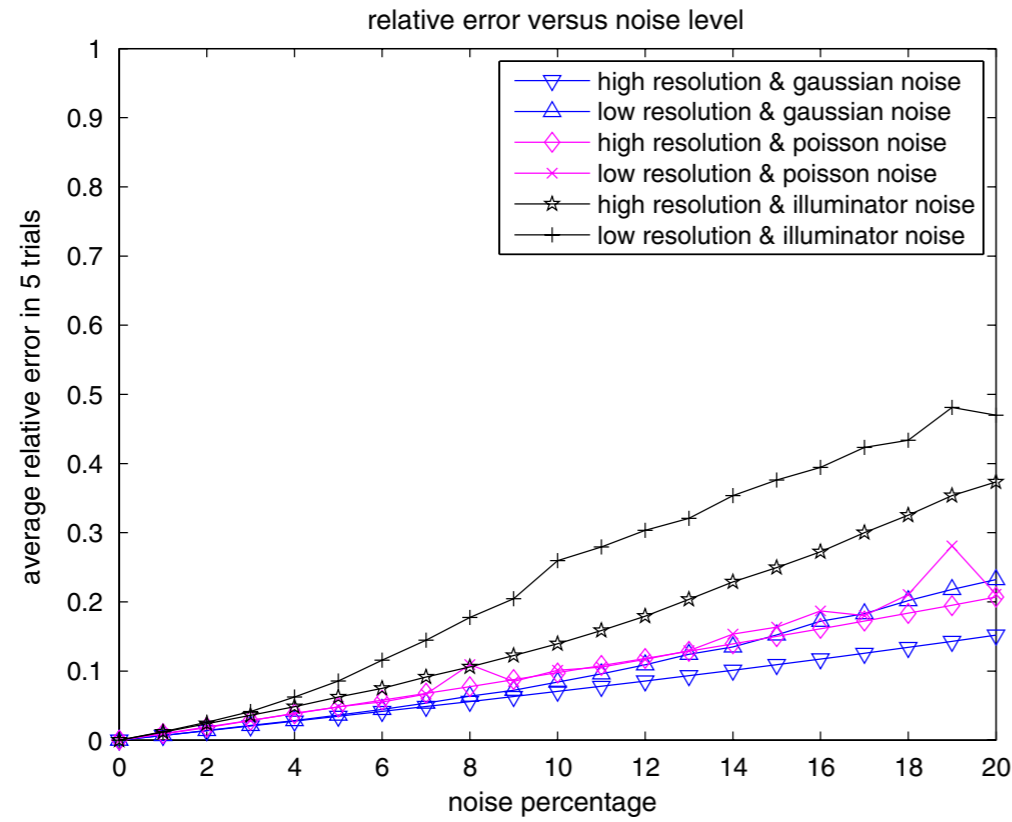
(b)



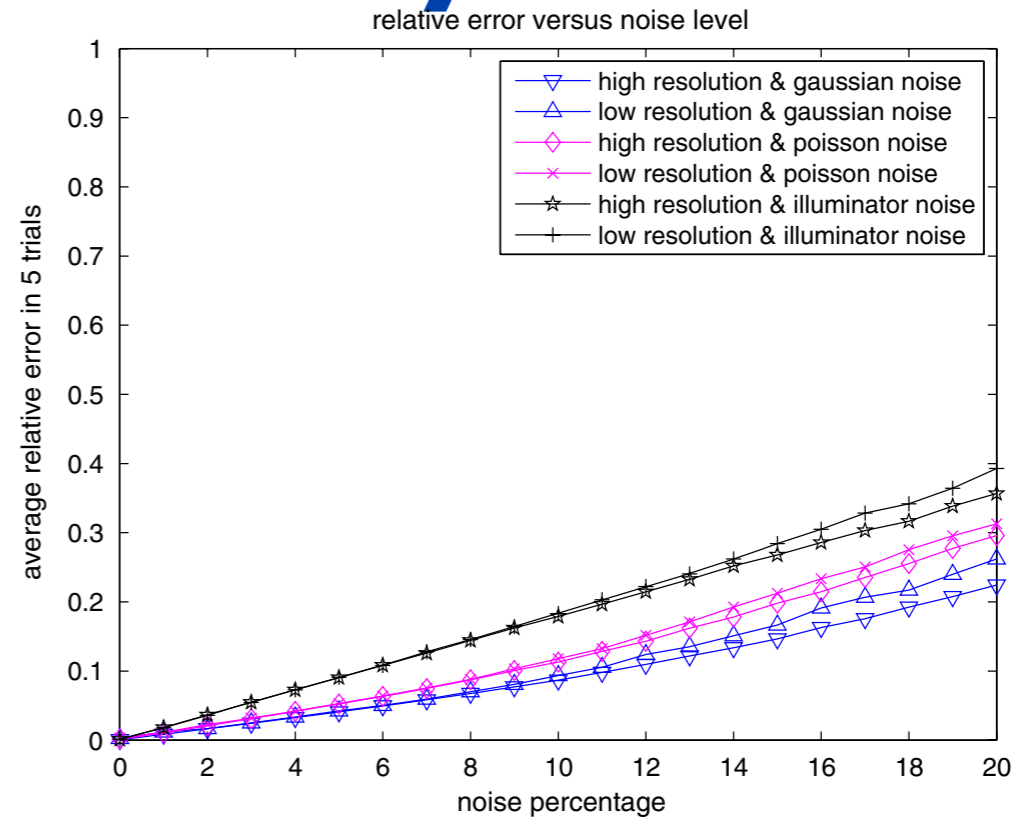
(c)

(a) real-valued (b) positive real & imaginary parts (c) no constraint

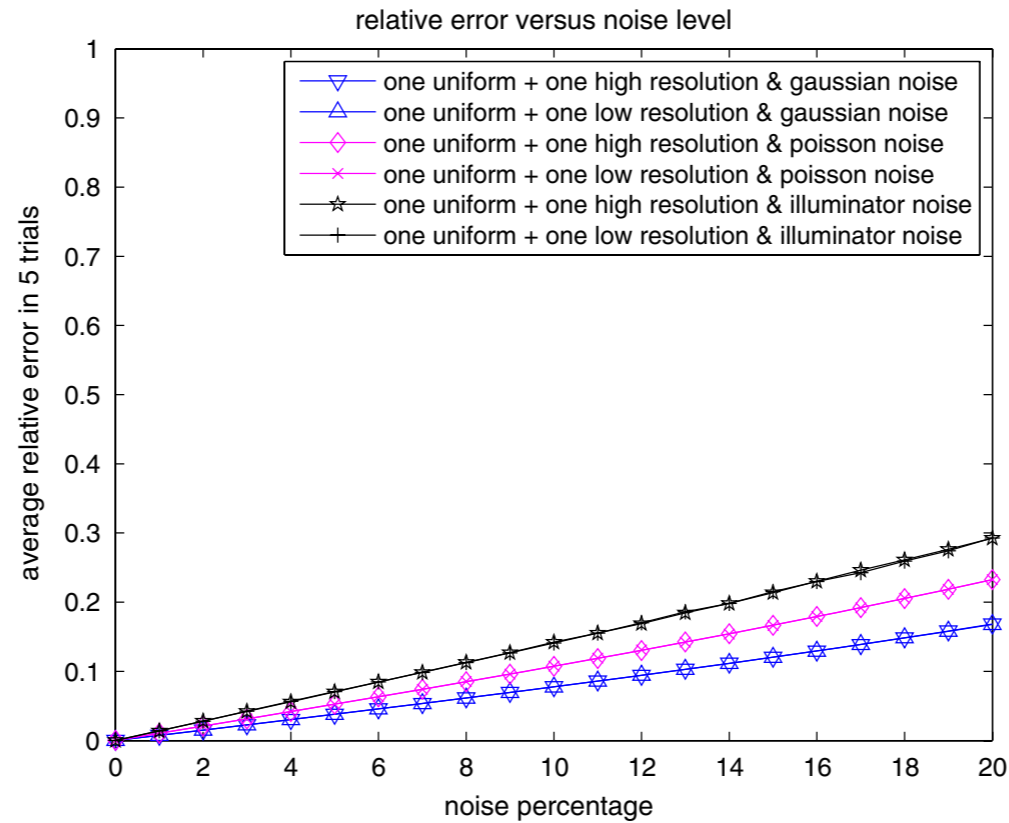
Noise stability



(a)



(b)



(c)

(a) real-valued objects (b) positive real & imaginary parts (c) no constraint

Roughly known mask

THEOREM Let the object f be positive and rank ≥ 2 . Suppose the uncertainty of the mask estimate $\lambda_0 = \{\exp(i\phi_0(\mathbf{n}))\}$ is

$$\phi(\mathbf{n}) \in \llbracket \phi_0(\mathbf{n}) - \delta\pi, \phi_0(\mathbf{n}) + \delta\pi \rrbracket$$

with $\delta < 1$.

Suppose that another non-negative image \tilde{f} and mask estimate $\tilde{\lambda} = \{\exp(i\tilde{\phi}(\mathbf{n}))\}$ satisfying

$$\tilde{\phi}(\mathbf{n}) \in \llbracket \phi_0(\mathbf{n}) - \delta\pi, \phi_0(\mathbf{n}) + \delta\pi \rrbracket$$

together produce the same Fourier intensity data on \mathcal{L} as do f and λ . Then, with probability no less than

$$1 - |\mathcal{N}|\delta^{\lfloor S/2 \rfloor}$$

$\tilde{f}(\mathbf{n}) = f(\mathbf{n}) \forall \mathbf{n}$ and furthermore $\tilde{\phi}(\mathbf{n}) = \theta + \phi(\mathbf{n})$ for a constant $\theta \in \mathbb{R}$ wherever $f(\mathbf{n}) \neq 0$.

Sketch of proof

There exist some m and $\theta \in [0, 2\pi]$ such that either

$$\tilde{\lambda}(n)\tilde{f}(n) = \exp(i\theta)\lambda(m+n)f(m+n)$$

or

$$\tilde{\lambda}(n)\tilde{f}(n) = \exp(i\theta)\overline{\lambda(m-n)f(m-n)}.$$

In the former case,

$$\tilde{f}(n) = \exp(i\theta) \frac{|\lambda(m+n)| \exp(i\phi(n+m))}{|\tilde{\lambda}(n)| \exp(i\angle \tilde{\lambda}(n))} f(n+m)$$

Roughly known mask

THEOREM Let f be a complex-valued object of rank ≥ 2 .

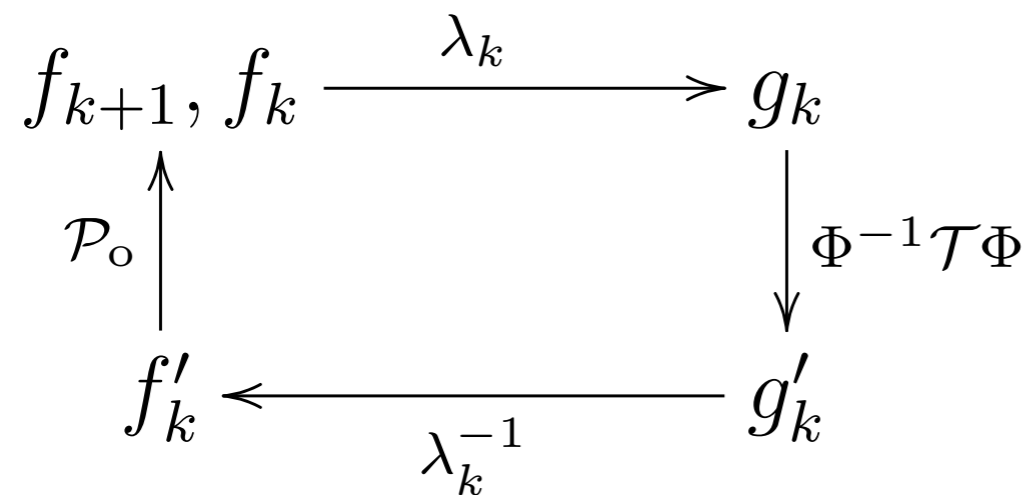
Let the first mask $\lambda^{(1)}$ is only roughly known with uncertainty δ . Suppose the second mask $\lambda^{(2)}$ is exactly known and assume the **non-degeneracy** condition on $\lambda^{(2)}f$.

Suppose that for a phase mask $\tilde{\lambda}$ of the same uncertainty δ and an object \tilde{f} produce the same Fourier magnitudes on \mathcal{L} . Then with probability no less than

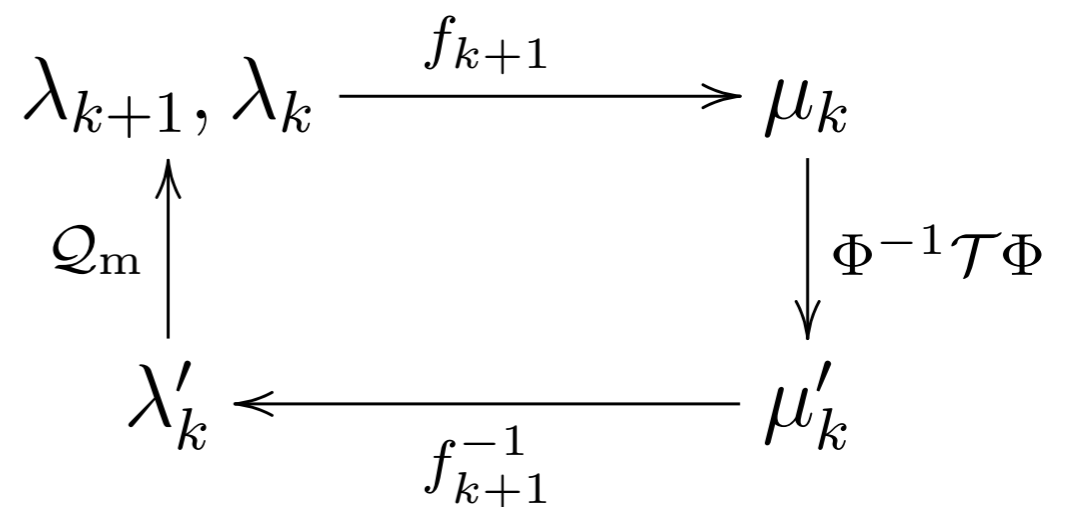
$$1 - |\mathcal{N}|_{\delta}^{\lfloor S/2 \rfloor}$$

$\tilde{f}(\mathbf{n}) = \exp(i\nu_1)f(\mathbf{n}), \forall \mathbf{n}$, and $\tilde{\lambda}(\mathbf{n}) = \exp(i\nu_2)\lambda(\mathbf{n})$ if $f(\mathbf{n}) \neq 0$.

Object & Mask updates



(a) object update



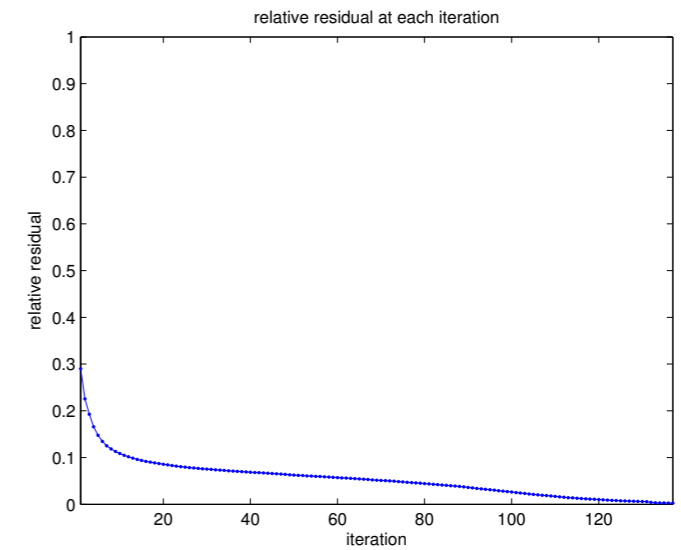
(b) mask update



(a)



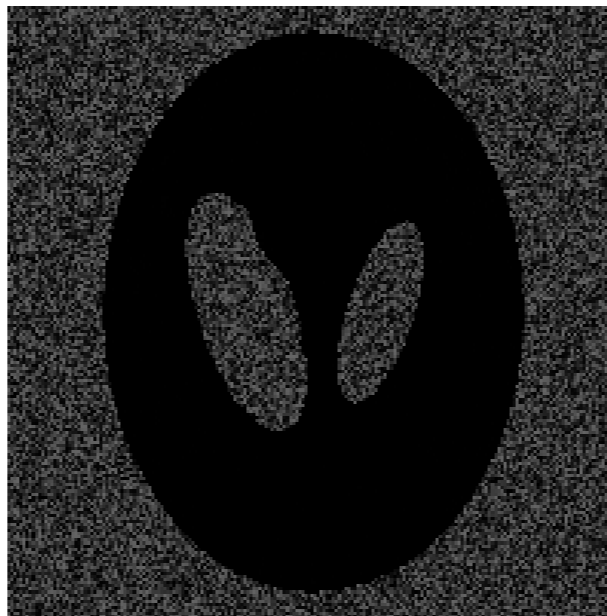
(b)



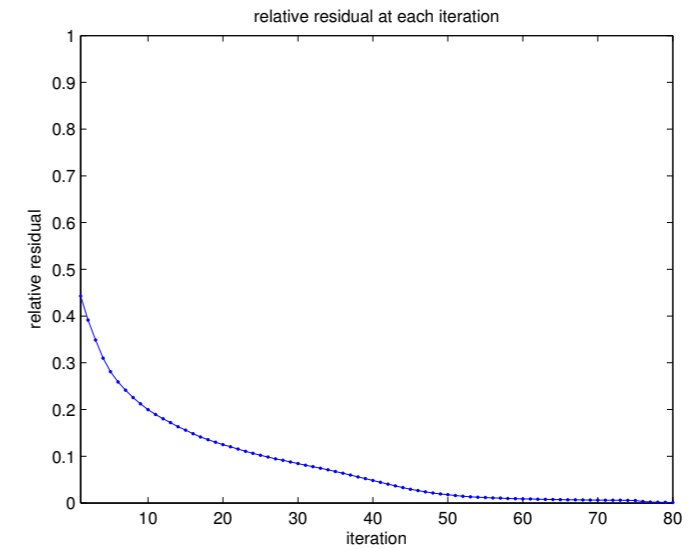
(c)



(d)



(e)



(f)

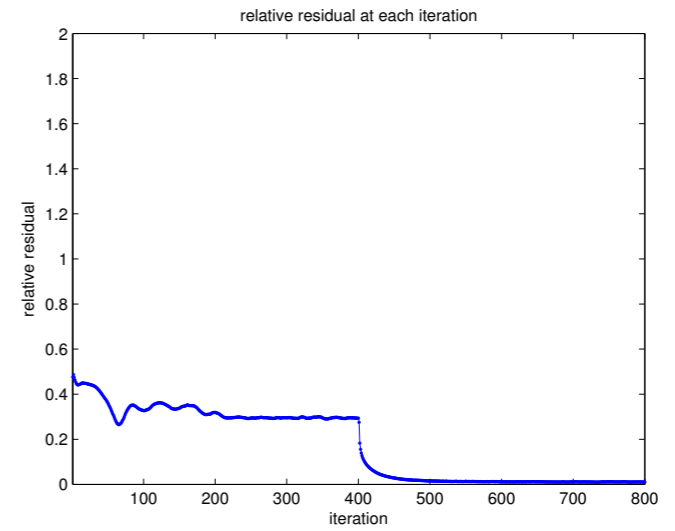
Fig. 5. Recovery of non-negative images with one LRM of $\delta = 0.2$. (a) the recovered cameraman \hat{f} by 131 DRER + 6 AER steps. $e(\hat{f}) \approx 1.43\%$ and $\rho(\hat{f}, \hat{\lambda}) \approx 0.25\%$. (d) the recovered phantom \hat{f} by 75 DRER + 5 AER steps. $e(\hat{f}) \approx 0.33\%$ and $\rho(\hat{f}, \hat{\lambda}) \approx 0.12\%$. The middle column shows the absolute phase differences between λ and $\hat{\lambda}$. The right column shows the relative residual at each iteration.



(a)



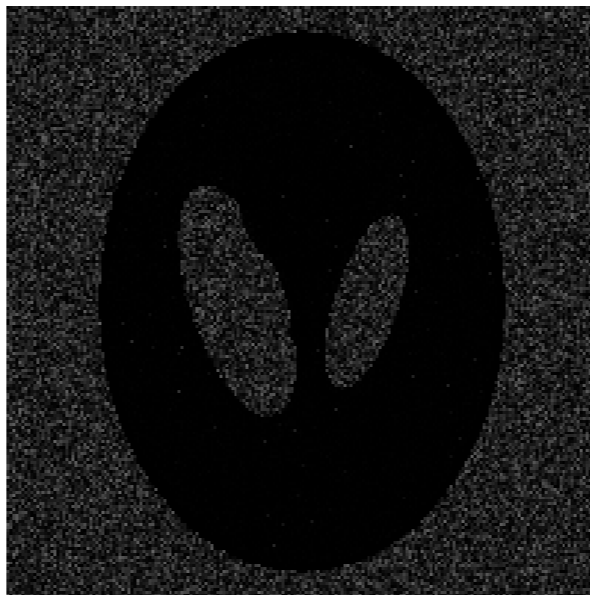
(b)



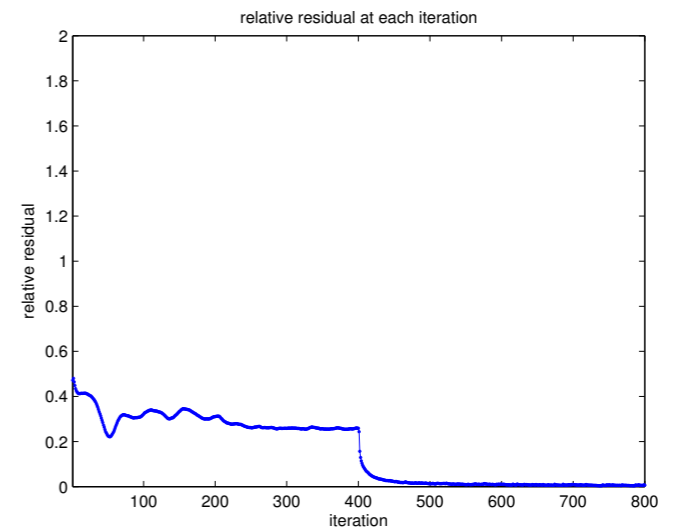
(c)



(d)

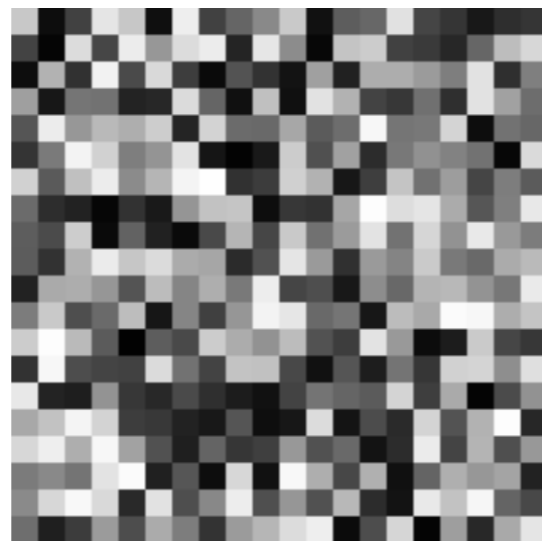
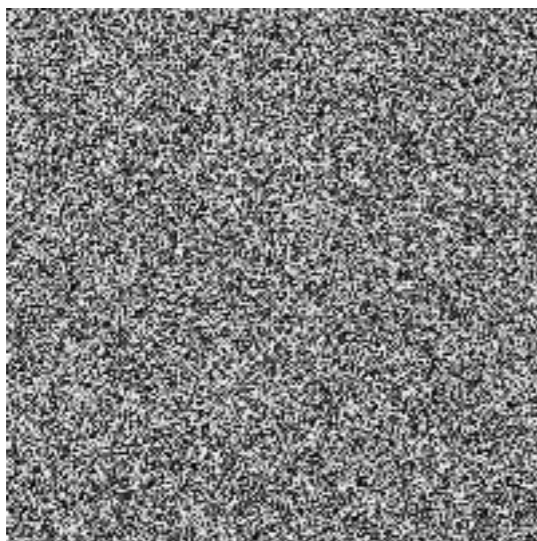
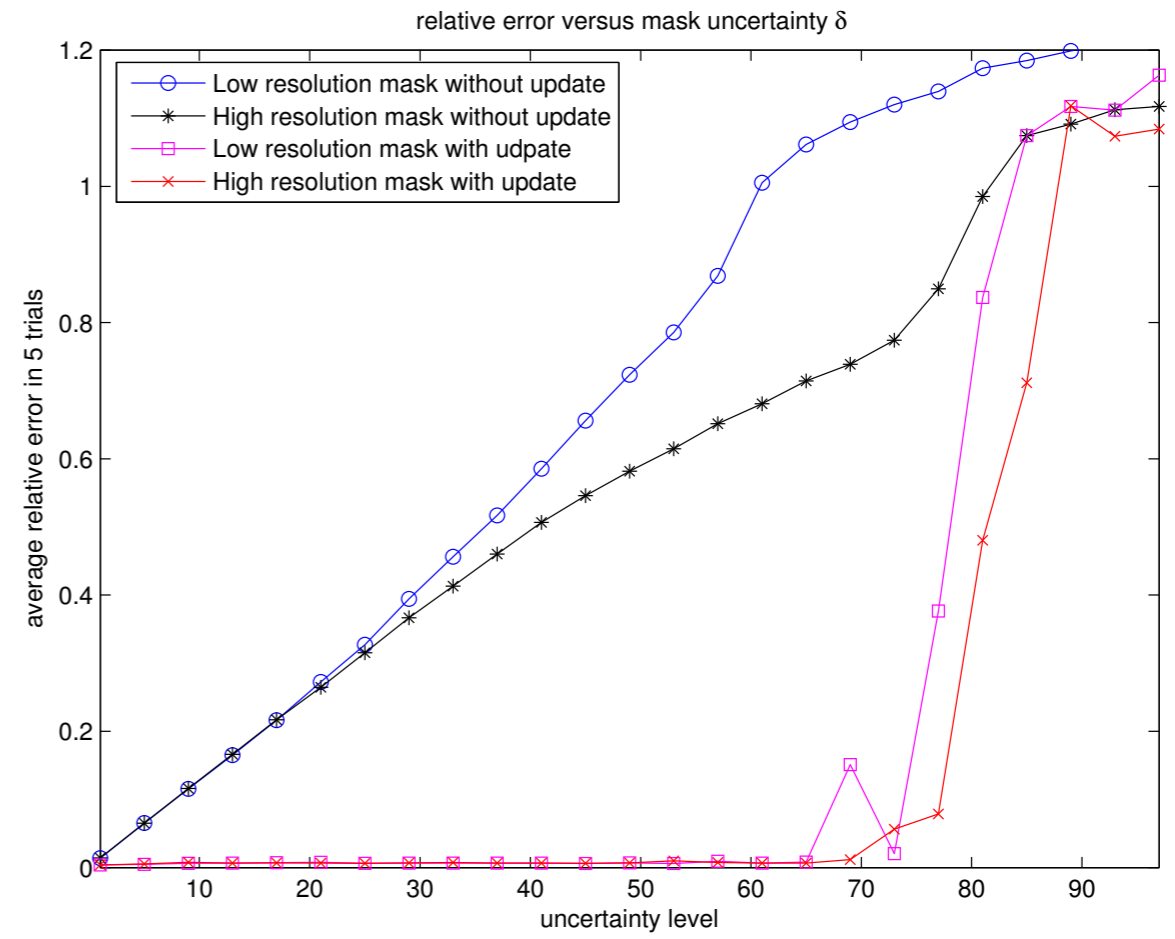
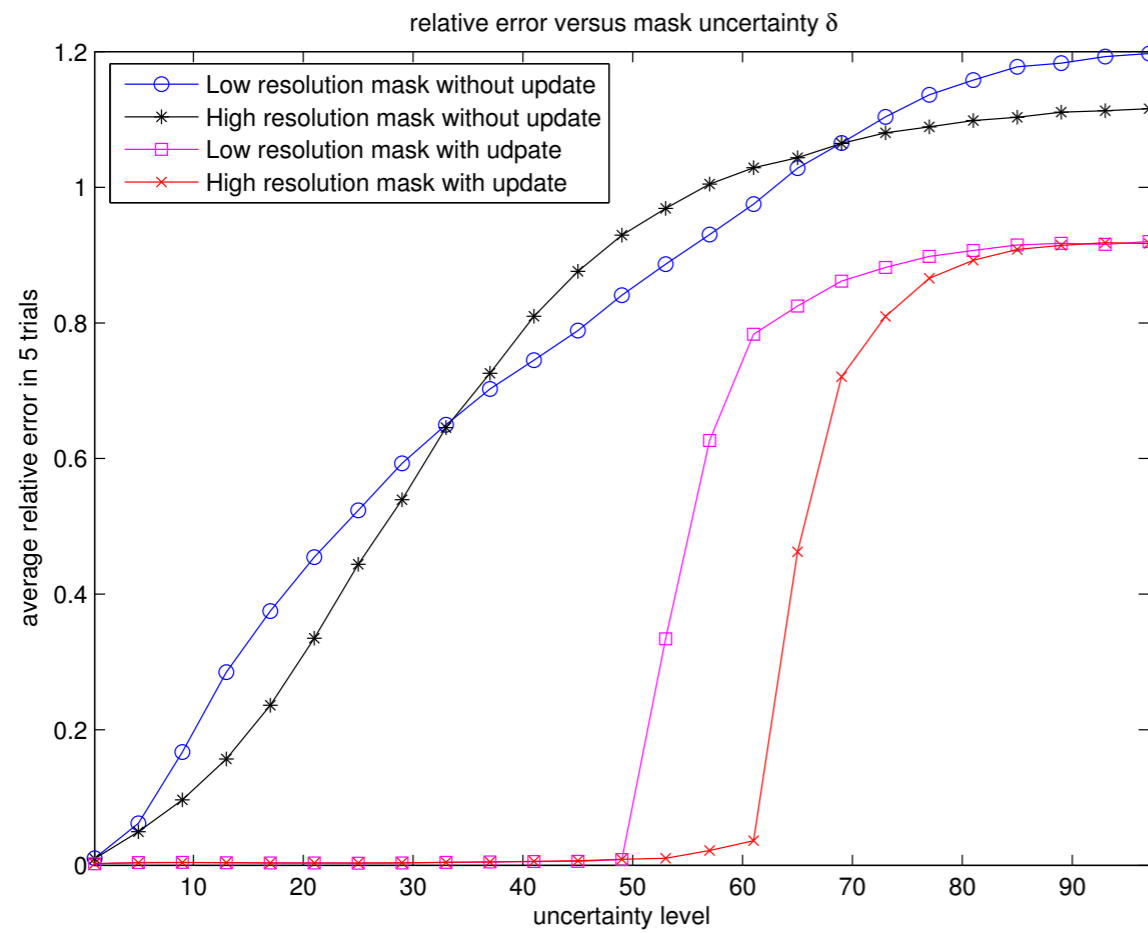


(e)



(f)

Fig. 6. Recovery of generic complex-valued images with one UM and one LRM of $\delta = 0.2$. (a) absolute values of the recovered cameraman \hat{f} by 400 DRER + 400 AER steps. $e(\hat{f}) \approx 2.39\%$ and $\rho(\hat{f}, \hat{\lambda}) \approx 1.03\%$. (d) absolute values of the recovered phantom \hat{f} by 400 DRER + 400 AER steps. $e(\hat{f}) \approx 1.37\%$ and $\rho(\hat{f}, \hat{\lambda}) \approx 0.65\%$. The middle column shows the absolute phase differences between λ and $\hat{\lambda}$. The right column shows the relative residual at each iteration.



Maximum of 200+1000 delta steps for DRER and AER separately

Conclusions

 Random mask as enabling tool for phase retrieval.

 Uniqueness

 Mask uncertainty

 Fast convergence

 $OR = 1$ (real) or 2 (complex)

 References:

- F.: Inverse Problems 28 (2012) 075008
- F & Liao: Journal of Optical Society of America A 29 (2012), 1847-1859.
- F & Liao: Phase retrieval with roughly known mask, arXiv:1212.3858