Autonomous Differential Equations

A first-order differential equation with independent variable t and dependent variable y is **autonomous** if

$$\frac{dy}{dt} = f(y).$$

The rate of change of y(t) depends only on the value of y.

Examples of autonomous equations: exponential growth model, radioactive decay, logistic population model

Example.
$$\frac{dv}{dt} = -kv + a\sin bt$$

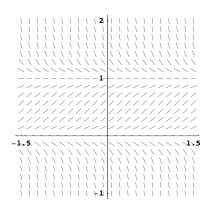
This is a nonautonomous linear differential equation that is related to simple models of voltage in an electric circuit (k, a, a) and b are parameters).

Comments:

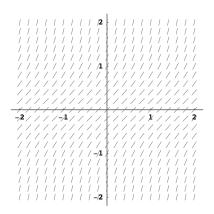
- 1. Many interesting models in science and engineering are autonomous (but not every model).
- 2. Every autonomous equation is separable, but the integrals may be impossible to calculate in terms of standard functions.

Basic Fact: Given the graph of one solution to an autonomous equation, we can get the graphs of many other solutions by translating that graph left or right.

Example 1.
$$\frac{dy}{dt} = 4y(1-y)$$

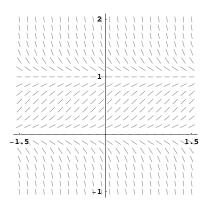


Example 2. $\frac{dy}{dt} = 1 + y^2$



The slope field has so much redundant information that we can replace it with the **phase** line. Here's the phase line for our standard example:

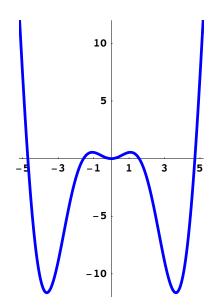
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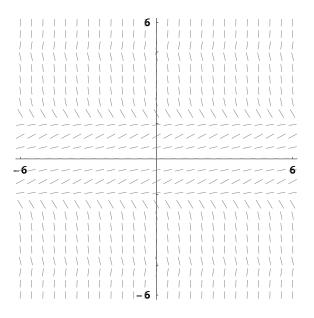


Building phase lines

How do we go about building a phase line from a differential equation?

Example
$$\frac{dy}{dt} = y^2 \cos y$$

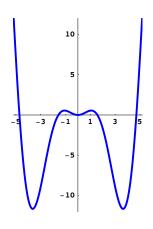


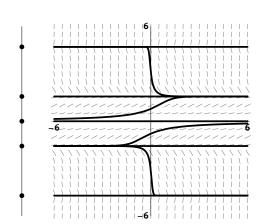


A little more about phase lines

At the end of last class we discussed the following example.

Example 1. $\frac{dy}{dt} = y^2 \cos y$





Example 2. $\frac{dy}{dt} = f(y)$ where f(y) is given by the graph

