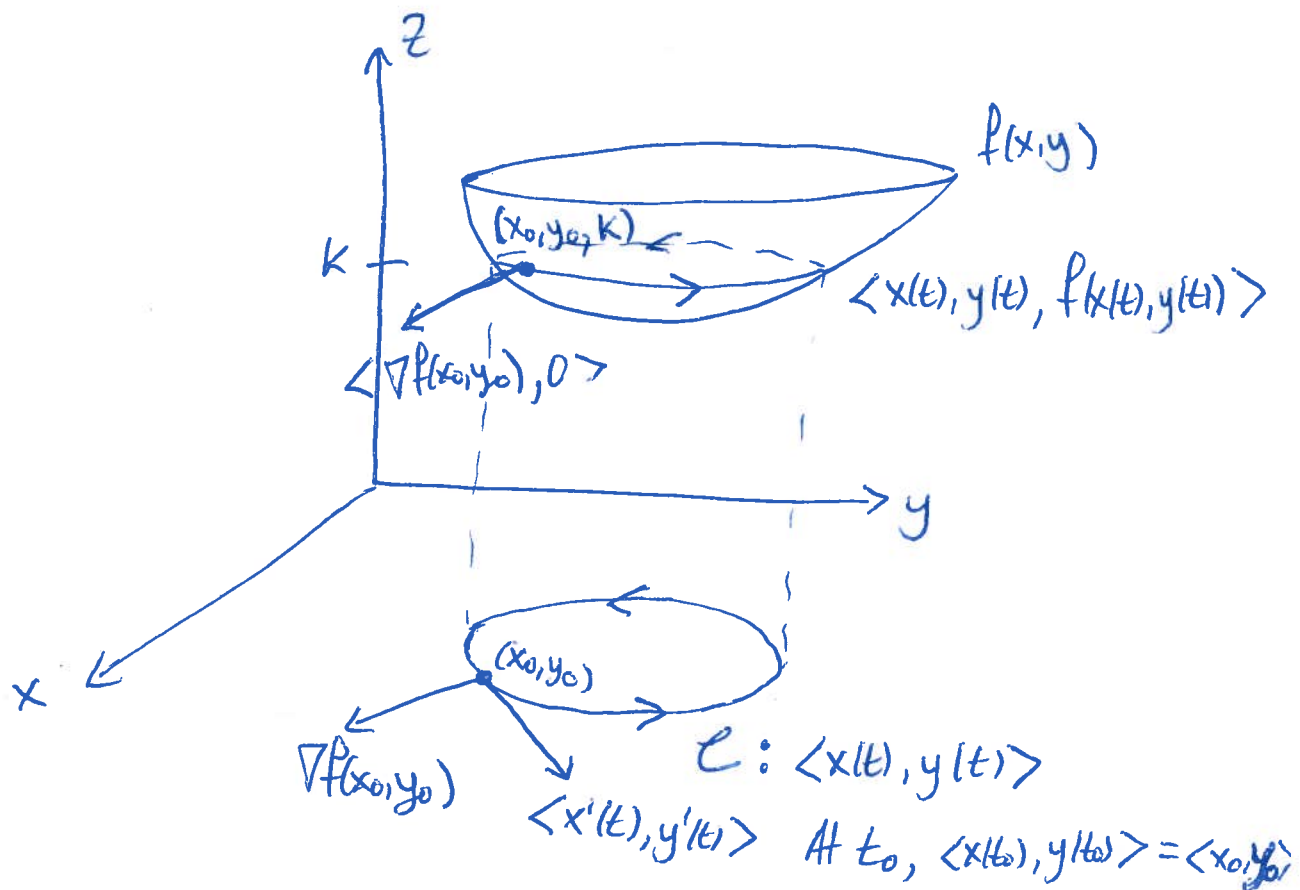


Directional Derivatives and the Gradient Vector

Gradient vector : $\nabla f(x,y) = \langle f_x(x,y), f_y(x,y) \rangle$

Directional derivative : $D_{\vec{u}} f(x,y) = \nabla f(x,y) \cdot \vec{u}$ (spits out a number)

What are these?



How does your altitude change as you travel around C?

$$\begin{aligned} \frac{dz}{dt} &= \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} \\ &= \nabla f(x,y) \cdot \langle x'(t), y'(t) \rangle \end{aligned}$$

How is your altitude change as you travel around the surface $z=f(x,y)$?

Stays the same! $\Rightarrow \frac{dz}{dt} = 0$!

$$\Rightarrow 0 = \nabla f(x,y) \cdot \langle x'(t), y'(t) \rangle$$

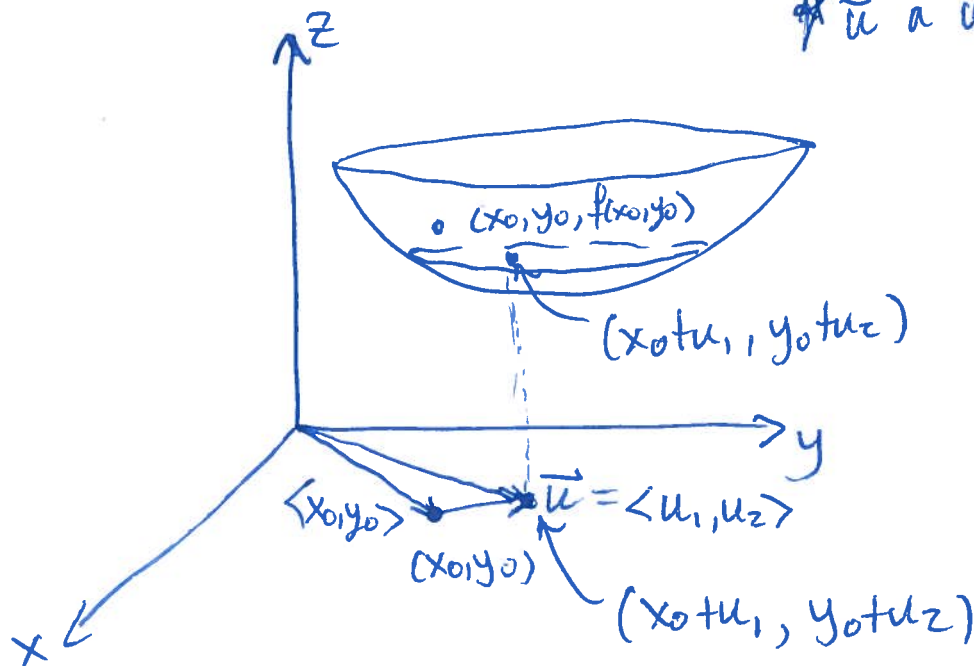
So $\nabla f(x,y)$ is normal to $\mathcal{C}$.
(perpendicular to your velocity)

* Gradient points in direction of steepest ascent

Directional derivative: $D_{\vec{u}} f(x,y) = \nabla f(x,y) \cdot \vec{u}$

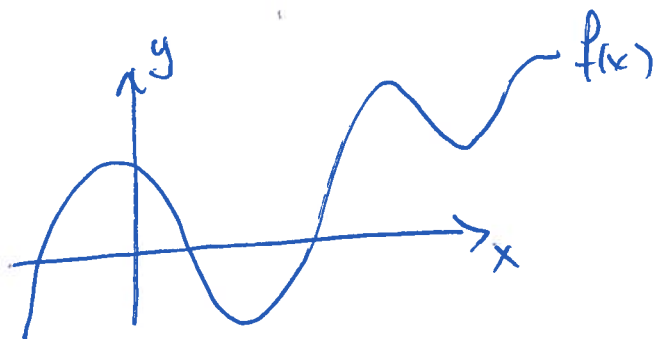
"How does f change if you travel in the $\vec{u}$ direction"

* $\vec{u}$ a unit vector



Optimization

17A



Find local max/min: 1. Find critical points
2. Determine which are max/min

Find absolute max/min: 3. Pick the largest/smallest value of f .

If on an interval, need to also check endpoints.

Now back to 17C,

Same idea, but slightly more complicated:

1. 2nd derivative test ($f_x = 0$ and $f_y = 0$)

$$D = \begin{vmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{vmatrix} = f_{xx}f_{yy} - (f_{xy})^2$$

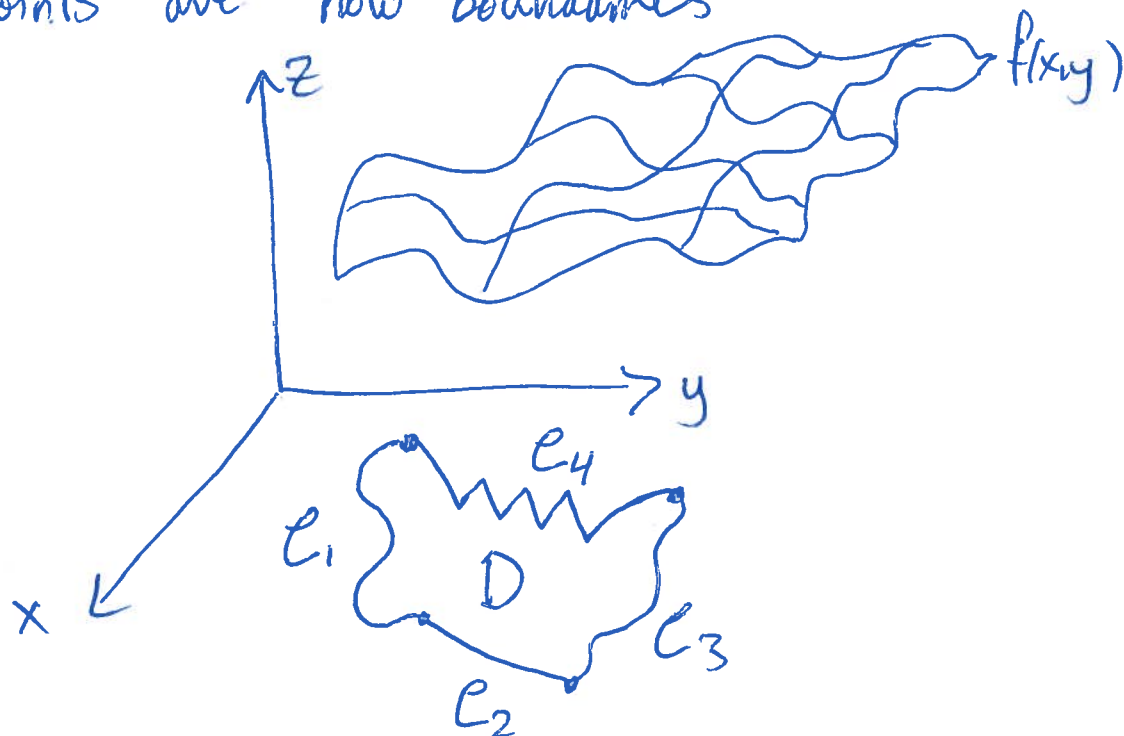
(a) $D > 0$ and $f_{xx} > 0 \rightarrow$ local min

(b) $D > 0$ and $f_{yy} < 0 \rightarrow$ local max

(c) $D < 0 \rightarrow$ saddle

(d) $D = 0 \rightarrow$ inconclusive

2. Endpoints are now boundaries



After find the critical points of f in D , we need to investigate f on the boundary.

Say on C_1 , ~~we~~ we know the points are given by (x, y) where $y = g(x)$. Then, along C_1 , f is $f(x, y) = f(x, g(x))$.

$\rightarrow$ Then use 1D techniques.

Method of Lagrange Multipliers

maximize $f(x)$

Subject to $g_1(x)=0, g_2(x)=0, \dots, g_m(x)=0$

$$\nabla f(x) = \sum_{k=1}^m \lambda_k \nabla g_k(x) \Leftrightarrow \nabla f(x) - \sum_{k=1}^m \lambda_k \nabla g_k(x) = 0$$

$$\mathcal{L} = f - \sum_{k=1}^m \lambda_k g_k$$

$$\nabla \mathcal{L} = 0 \quad \Leftrightarrow \quad \begin{cases} \nabla f - \sum \lambda_k \nabla g_k = 0 \\ g_1(x) = g_2(x) = \dots = g_m(x) = 0 \end{cases}$$