## FINAL EXAM Math 116 Temple

- #1.(36pts) Let  $\alpha(s)$  be a regular curve in  $\mathbf{R}^3$ , parameterized by arclength.
- i) Give the definitions of T(s), N(s), B(s),  $\kappa(s)$ , and  $\tau(s)$ .
- ii) Give the 3x3 matrix A such that

$$\begin{bmatrix} \mathsf{T'} \\ \mathsf{N'} \\ \mathsf{B'} \end{bmatrix} = \mathsf{A} \begin{bmatrix} \mathsf{T} \\ \mathsf{N} \\ \mathsf{B} \end{bmatrix}$$

- iii) Define the osculating plane, normal plane and rectifying plane at a point P on the curve  $\,\alpha$  .
- #2. (12pts) Let  $\alpha(t)$  denote a regular curve in  $\mathbb{R}^3$ , and assume that  $|\alpha'(t)| = \text{const.}$  independent of t . Show that  $<\alpha',\alpha''>=0$ , where <, > denotes the dot product on  $\mathbb{R}^3$ .
- #3. (25pts) Let  $\alpha(t) = (\cos(\pi t), \sin(\pi t), t)$ . Find explicit formulas for T(t), N(t), B(t),  $\kappa(t)$ , and  $\tau(t)$ .
- #4. (16pts) Let  $\alpha(s)$  be a unit speed curve in  $R^3$ . Find a vector w(s) such that T'=wXT, N'=wXN, and B'=wXB. The vector w is called the Darboux vector.

#5. Let x and y be two different coordinate systems on a surface M,

$$x: U \rightarrow \mathbb{R}^3$$
 ,  $x(u^1,u^2) \epsilon M$  ;

y: 
$$V \rightarrow \mathbb{R}^3$$
,  $y(v^1, v^2) \in M$ .

- A) (16pts) Let  $J^i{}_{\alpha} = \frac{\partial u^i}{\partial v^{\alpha}}$  denote the Jacobian of the transformation that takes  $(v^1,v^2)$  to  $(u^1,u^2)$ , and let  $J^{\alpha}{}_{i} = \frac{\partial v^{\alpha}}{\partial u^i}$  denote its inverse. Let  $X = X^i x_i = X^1 x_1 + X^2 x_2$  be a vector field on M, and let  $g_{ij} = \langle x_i, x_j \rangle$  denote the metric and  $L^i{}_{j}$  denote the second fundamental form on M. Write the coordinate transformation laws for  $X^i$ ,  $x_i$ ,  $g_{ij}$  and  $L^i{}_{j}$  in terms of  $\frac{\partial u^i}{\partial v^{\alpha}}$  and  $\frac{\partial v^{\alpha}}{\partial u^i}$  using the summation convention.
- B) (48pts) Assume that

$$x(u^1,u^2)=(\sin(u^1u^2), \cos(u^1u^2), \ln(u^1),$$

and

$$y^{-1} \circ x = (v^1(u^1, u^2), v^2(u^1, u^2)) = (u^2 \cos(u^1), e^{u^1}u^2).$$

- i) Find  $x_1$  and  $x_2$  in terms of  $(u^1, u^2)$ .
- ii) What vector  $X^i x_i = X^1 x_1 + X^2 x_2$  in TM corresponds to the vector  $3 \frac{\partial}{\partial u^1} + 2 \frac{\partial}{\partial u^2}$  at the point  $(u^1, u^2) = (\pi, 1)$  in u-space.
- iii) What vector in the **y**-coordinates corresponds to the vector  $3\frac{\partial}{\partial u^1} + 2\frac{\partial}{\partial u^2}$  at the point  $(u^1, u^2) = (\pi, 1)$  in **u**-space.

$$g_{ij} = \langle \mathbf{x}_i, \mathbf{x}_j \rangle = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}_{ij}$$
,

at the point  $(u^1,u^2)=(\pi,1)$  in **u**-coordinates, find the metric entries at the corresponding point in **y**-coordinates.

#6. (15pts) Let X and Y be vector fields on M that are parallel along a curve  $\gamma$  in M. Show that the angle between X and Y is constant along  $\gamma$ .

**#7.** Recall that  $\gamma$  is a geodesic on M if

(\*) 
$$(\gamma'')^{k} + \Gamma^{k}_{ij}(\gamma')^{i}(\gamma')^{j} = 0,$$

all along  $\gamma$ , where

$$\Gamma^{k}_{ij} = \frac{1}{2} g^{k\sigma} \left\{ \frac{\partial}{\partial u^{j}} g_{i\sigma} + \frac{\partial}{\partial u^{i}} g_{\sigma j} - \frac{\partial}{\partial u^{\sigma}} g_{ij} \right\}.$$

(We assume the summation convention.)

- i) (12pts) Show that if  $\gamma(s)$  solves (\*), then so does  $\gamma(cs)$ , where c is any real constant.
- ii) (20pts) If  $g_{ij} = \langle x_i, x_j \rangle = \begin{bmatrix} u^1 & 0 \\ 0 & 1 \end{bmatrix}_{ij}$ , find  $\Gamma^k_{ij}$  for all i,j,k=1,2, and write the equations (\*) in this case.