

Feb 29/22
Wed

119A Conservative Systems

①

Conservative Systems -

Theorem: Every system of form $\ddot{\underline{x}} = -\nabla U(\underline{x})$ has an energy $E = \frac{1}{2} |\dot{\underline{x}}|^2 + U(\underline{x})$ meaning:

$E(\underline{x}(t))$ is constant along solutions.

"Solutions can only move along level curves of E "

Holds for $\underline{x}(t) = (x_1(t), \dots, x_n(t)) \in \mathbb{R}^n$

Proof: Let $\underline{x}(t)$ solve $\ddot{\underline{x}} = -\nabla U(\underline{x})$. Then

$$\frac{d}{dt} E(t) = \frac{d}{dt} \left(\frac{1}{2} (\dot{x}_1^2 + \dots + \dot{x}_n^2) \right) - \frac{d}{dt} U(\underline{x}(t))$$

$$= \dot{x}_1 \ddot{x}_1 + \dots + \dot{x}_n \ddot{x}_n - \nabla U \cdot \dot{\underline{x}}$$

$$= \dot{\underline{x}} \cdot \ddot{\underline{x}} - \nabla U \cdot \dot{\underline{x}}$$

$$= \dot{\underline{x}} \cdot (\ddot{\underline{x}} - \nabla U) = 0 \quad \checkmark$$

• To find the energy - "mult by the velocity" ⁽²⁾
 & create a total derivative"

$$\ddot{\underline{x}} + \nabla U = 0$$

$$\dot{\underline{x}} (\ddot{\underline{x}} + \nabla U) = 0$$

$$\underbrace{\dot{\underline{x}} \ddot{\underline{x}}}_{\frac{d}{dt} \left(\frac{1}{2} \dot{\underline{x}}^2 \right)} + \underbrace{\nabla U \cdot \dot{\underline{x}}}_{\frac{d}{dt} U(\underline{x}(t))} = 0$$

$$\frac{d}{dt} \left(\frac{1}{2} \dot{\underline{x}}^2 \right) + \frac{d}{dt} U(\underline{x}(t)) = 0$$

$$\frac{d}{dt} \left\{ \frac{1}{2} \dot{\underline{x}}^2 + U(\underline{x}(t)) \right\} = 0$$

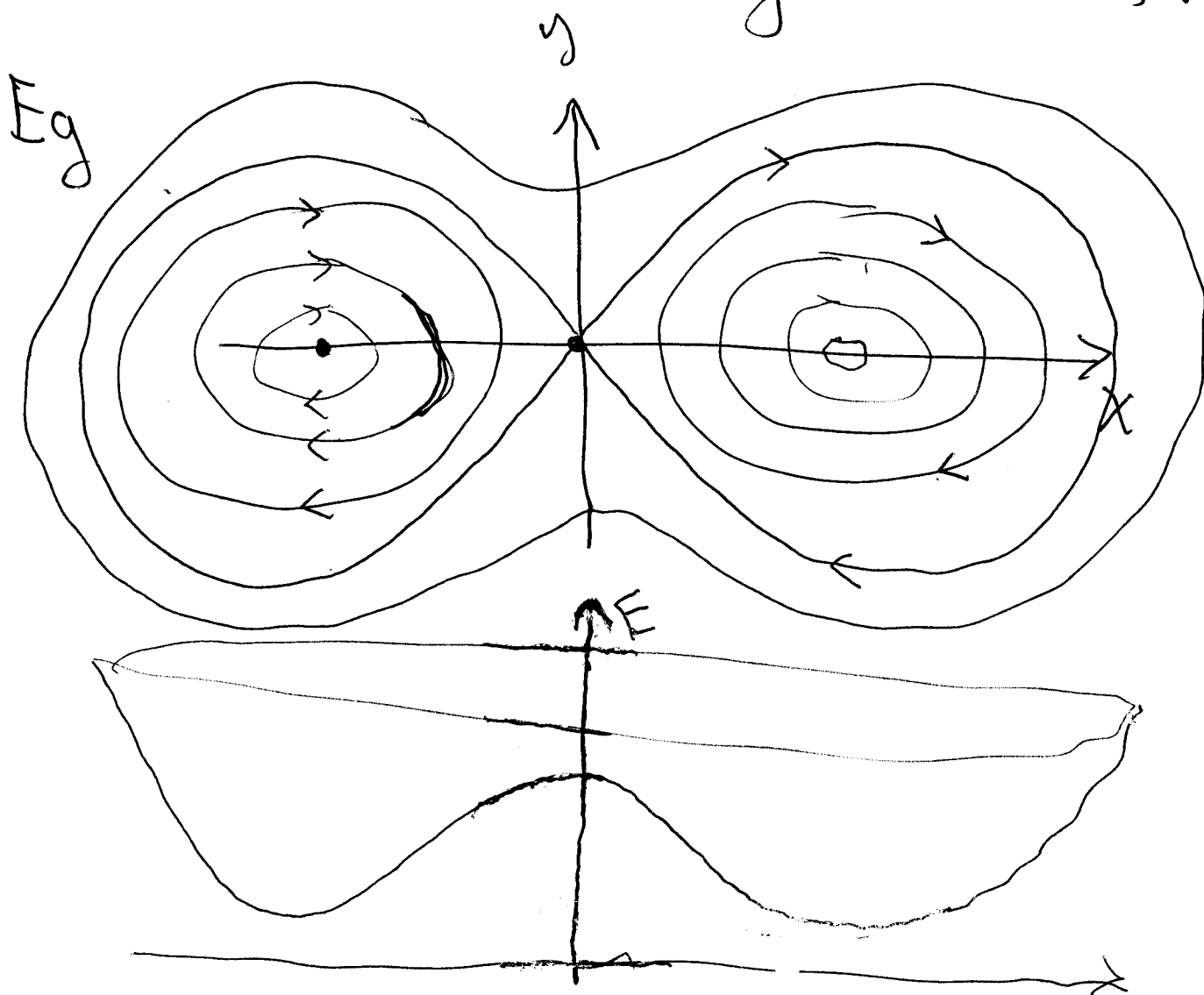
$$\underbrace{\hspace{10em}}_{E(t)}$$

③ If x is a scalar — $\ddot{x} = -\nabla U = -U'(x)$

\Rightarrow 1st order system: $x = x$ $y = \dot{x}$ $\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} y \\ -U'(x) \end{pmatrix}$

Energy: $E = \frac{1}{2} \dot{x}^2 + U(x) = \frac{1}{2} y^2 + U(x)$

• Solutions must move along level curves of E



Double potential Eg: $E = \frac{1}{2} y^2 - \frac{1}{2} x^2 + \frac{1}{4} x^4$
 $\ddot{x} = x - x^3$

More general:

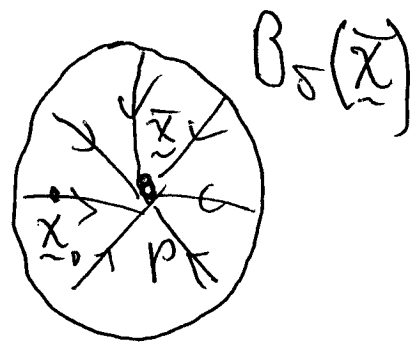
might not come from
 $\ddot{x} = -\nabla U$

(4)

Defn: Given $\dot{\underline{x}} = f(\underline{x})$, a conserved quantity or energy is a function $E(\underline{x})$ that is constant on solutions, and non-constant in any open ball. A system with conserved quantity is called a conservative system.

Theorem: A conservative system cannot have an attracting fixed pt or a repelling fixed pt.

Pf. All trajectories starting



from $\underline{x}_0 \in B_\delta(\bar{\underline{x}}) = \{ \underline{x} : |\underline{x} - \bar{\underline{x}}| < \delta \}$

tend toward $\bar{\underline{x}}$. Thus $E(\underline{x}_0) = E(\underline{x}(t)) = E(\bar{\underline{x}})$

$\Rightarrow E$ is constant on $B_\delta(\bar{\underline{x}}) \nexists$.

• Recall: Solutions of nonlinear systems can blow up in finite time -

Eg $\dot{x} = x^2$ $x(t) = \frac{1}{\frac{1}{x_0} - t}$ $t \rightarrow \frac{1}{x_0} \rightarrow \infty$

Could happen in 2x2 nonlinear system -

Eg: $\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} x^2 \\ y^2 \end{pmatrix} \Rightarrow \begin{pmatrix} x \\ y \end{pmatrix} (t) = \begin{pmatrix} \frac{1}{\frac{1}{x_0} - t} \\ \frac{1}{\frac{1}{y_0} - t} \end{pmatrix}$

Ex: Show that if $\dot{\underline{x}} = f(\underline{x})$ is conservative, then the solution of ivp

$$\dot{\underline{x}} = f(\underline{x})$$

$$\underline{x}(0) = \underline{x}_0$$

does not blow up so long as

$\mathcal{J} = \{ \underline{x} : E(\underline{x}) = E(\underline{x}_0) \}$ is bounded.

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Solution: $E(\underline{x}(t)) = E(\underline{x}_0)$ all along the solution, so $\underline{x}(t)$ stays in the set \mathcal{S} and so cannot go off to infinity at any value of t .

Note: if \mathcal{S} is closed & bounded \Leftrightarrow compact & $f(\underline{x})$ is continuous then:

Thm - a continuous function is bounded on a compact set.

$\Rightarrow |\dot{\underline{x}}| = |f(\underline{x})| \leq M$ on $\mathcal{S} \Rightarrow$ the derivative is bounded $\forall t \Rightarrow$ solution $\underline{x}(t)$ exists for all time \rightarrow

True in any number of dimensions

Ex: Consider 2x2 conservative system (7)

$$\ddot{x} = -U'(x) \quad \dot{x} = y$$

$$\dot{\underline{x}} = \begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} y \\ -U'(x) \end{pmatrix} = f(\underline{x})$$

Let \bar{x} be an isolated, ^{regular} local min of U :

$\bar{x} = (\bar{x}, 0)$ is a rest point.

$$U'(\bar{x}) = 0$$

$$U''(\bar{x}) > 0$$

(1) Evs of linearized equations

$$\dot{\underline{x} - \bar{x}} + Df(\bar{x})(\underline{x} - \bar{x})$$

are purely imaginary \Rightarrow center

(2) Nonlinear trajectories are closed orbits in a nbhd of \bar{x} .

\Rightarrow "Energy makes the closed orbits of the linearized eqn's perturb to nonlinear eqn's"

Soln (1) $f(\underline{x}) = f(\bar{\underline{x}}) + \underbrace{\begin{pmatrix} \nabla f_1(\bar{\underline{x}}) \\ \nabla f_2(\bar{\underline{x}}) \end{pmatrix}}_{\text{wavy line}} (\underline{x} - \bar{\underline{x}}) + \text{h.o.t}$

evalk: $\lambda^2 - \tau + \Delta = 0$

$\tau = 0 \quad \Delta = U''(\bar{\underline{x}})$

$$\begin{pmatrix} 0 & 1 \\ -U''(\bar{\underline{x}}) & 0 \end{pmatrix}$$

$\lambda = \pm i \sqrt{U''(\bar{\underline{x}})}$



~~Soln (2) " For solution trajectories of suff. close to $\bar{\underline{x}} = (\bar{x}, 0)$, $E(\underline{x}(t)) = E(\bar{\underline{x}})$~~

~~$E(\underline{x}(t)) = \frac{1}{2}y^2 + U(x) =$~~

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Soln(2): Nonlinear solutions move along level curves of $E = \frac{1}{2}y^2 + U(x)$

But: $\nabla E(x, y) = \begin{pmatrix} U'(x) \\ y \end{pmatrix} \Rightarrow \nabla E(\bar{x}, 0) = 0$

$$H(\bar{x}, 0) = \begin{bmatrix} -\nabla E_x \\ -\nabla E_y \end{bmatrix}_{\bar{x}} = \begin{bmatrix} U''(\bar{x}) & 0 \\ 0 & 1 \end{bmatrix}$$

\Rightarrow evals $\lambda = U''(\bar{x}), 1 > 0 \Rightarrow \bar{x} = (\bar{x}, 0)$

is isolated rel min \Rightarrow

"Level curves of E are closed curves with no rest pts near \bar{x} " (Not a complete proof)

