

Relativist & non-relativistic fluids

• Compressible Euler Equations \approx Newton's

Laws for a Continuous Media

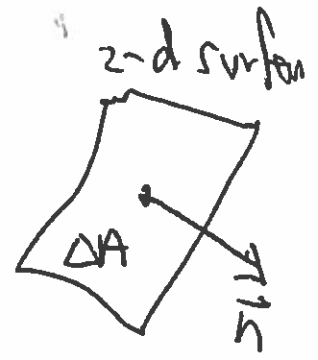
• Non-relativistic = classical version

(MA) $\rho_t + \text{div} \rho \vec{v} = 0$ [cons of mass = continuity eqn]

(MO²) $(\rho v^i)_t + \text{div}[(\rho v^i) \vec{v} + p e^i] = 0$

Here: $\rho = \frac{\text{mass}}{\text{vol}}$, $\vec{v} = (v^1, v^2, v^3) = \text{velocity}$

$p = \frac{\text{force}}{\text{area}}$ exerted by fluid



force $\approx p \cdot \Delta A \vec{n}$

• Look to solve for $\rho(\vec{x}, t), \vec{v}(\vec{x}, t)$ starting from

• Unknowns: v^1, v^2, v^3, ρ, p } 2-10 eqs } 2 cond! etc.

Equation: 4

Need Eqn of state to close - barotropic $p = p(\rho)$

• The divergence thm tells us what they mean: (2)

• General case: $q = \frac{\text{stuff}}{\text{vol}}$ is transported at velocity $\vec{v} = (v^1, v^2, v^3)$

Defn: $q \vec{v} \equiv$ "stuff flux vector"

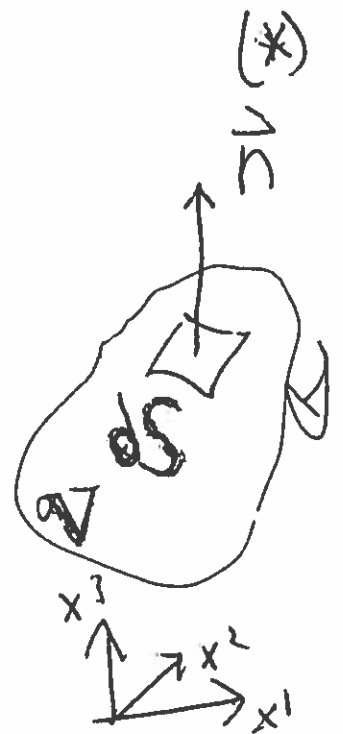
Claim: $q_t + \text{div}(q \vec{v}) = 0$

expresses "conservation of q "

E.g. Integrate (*) over 3-vol \mathcal{V} at fixed t :

$$\iiint_{\mathcal{V}} q_t + \text{div}(q \vec{v}) d\mathcal{V} = 0$$

$\underbrace{dx^1 dx^2 dx^3}$



$$\frac{d}{dt} \iiint_{\mathcal{V}} q d\mathcal{V} + \iiint_{\mathcal{V}} \text{div}(q \vec{v}) d\mathcal{V} = 0$$

$$\Leftrightarrow \frac{d}{dt} \iiint_V \rho \, dV + \iint_{\partial V} \rho \vec{v} \cdot \vec{n} \, dS = 0$$

$\underbrace{\quad\quad\quad}_V$ $\underbrace{\quad\quad\quad}_{\frac{\text{distance}}{\text{time}}}$ normal to ∂

mass in V $\underbrace{\quad\quad\quad}$ rate at which stuff passes outward thru boundary of $V \equiv \partial$

Conclude: $\rho_t + \text{div} \rho \vec{v} = 0$ expresses that the time rate of change of stuff in any volume V = rate at which stuff passes outward thru ∂V . \Leftrightarrow

Conservation of Stuff

• Conclude:

$$(MA) \quad \rho_t + \text{div } \rho \vec{v} = 0 \quad \equiv \quad \frac{d}{dt} \iiint_V \rho \, dV = - \iint_{\partial V} \rho \vec{v} \cdot \vec{n} \, dA$$

$\rho = \text{mass}$

\equiv conservation of mass

\equiv continuity eqn.

$$(mo^i) \quad \left(\rho v^i \right)_t + \text{div} \left(\rho v^i \vec{v} + p \underline{e}^i \right) = 0$$

$$\rho v^i \equiv \frac{\text{mass} \times \text{vel}}{\text{vol}}$$

$(\rho v^i) \vec{v} \equiv i\text{-mom flux vector}$

$\equiv i\text{-mom density}$

Use Div Thm to Interpret:

outward normal

$$\frac{d}{dt} \iiint_V \rho v^i \, dV = - \iint_{\partial V} \rho v^i \vec{v} \cdot \vec{n} \, dA - \iint_{\partial V} (p \underline{e}^i \cdot \vec{n}) \, dA$$

$i\text{-mom in vol } V$

rate at which $i\text{-mom}$ passes outward thru $\partial V = \text{boundary of } V$

$i\text{-comp of the force on } \partial V$

• Conclude: (CE) \Leftrightarrow Cons of Mass (MA)

$\delta(M_0) \equiv$ changes in momentum are due only to the pressure forces

The equations:

$$\begin{pmatrix} \rho \\ \rho v^1 \\ \rho v^2 \\ \rho v^3 \end{pmatrix}_t + \text{div} \begin{pmatrix} \rho v^1 & \rho v^2 & \rho v^3 \\ \rho v^1 v^1 + p & \rho v^1 v^2 & \rho v^1 v^3 \\ \rho v^2 v^1 & \rho v^2 v^2 + p & \rho v^2 v^3 \\ \rho v^3 v^1 & \rho v^3 v^2 + \rho v^3 v^3 + p \end{pmatrix}$$

or

$$\text{Div}_{t, \vec{x}} \begin{pmatrix} \rho & \rho v^1 & \rho v^2 & \rho v^3 \\ \rho v^1 & \rho v^1 v^1 + p & \rho v^1 v^2 & \rho v^1 v^3 \\ \rho v^2 & \rho v^2 v^1 & \rho v^2 v^2 + p & \rho v^2 v^3 \\ \rho v^3 & \rho v^3 v^1 & \rho v^3 v^2 & \rho v^3 v^3 + p \end{pmatrix}^{\alpha B}$$

4x4 symmetric tensor $T^{\alpha B} = T_{CE}^{\alpha B}$

Note = In frame where $v=0$, $T = \begin{bmatrix} p & p & 0 \\ 0 & p & 0 \end{bmatrix} \dots$

• For GR, Einstein wants eqn of form ⁽⁶⁾

$$G = \kappa T$$

Looks for $\text{Div } G = 0$ so

$$\text{Div } T = 0$$

is the relativistic version of compressible Euler

Claim: The relativistic version of T_{CE} is

$$T^{\alpha\beta} = (\rho + p) u^\alpha u^\beta + p g^{\alpha\beta} \quad (*)$$

↑
metric defines the
gravitational field.

No Gravity = Flat space $g^{\alpha\beta} = \eta^{\alpha\beta} = \begin{bmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix}$

(*) = the unique tensor = $\begin{bmatrix} \rho & & & \\ & p & & \\ & & p & \\ & & & p \end{bmatrix}$ in frame where $v = 0$.