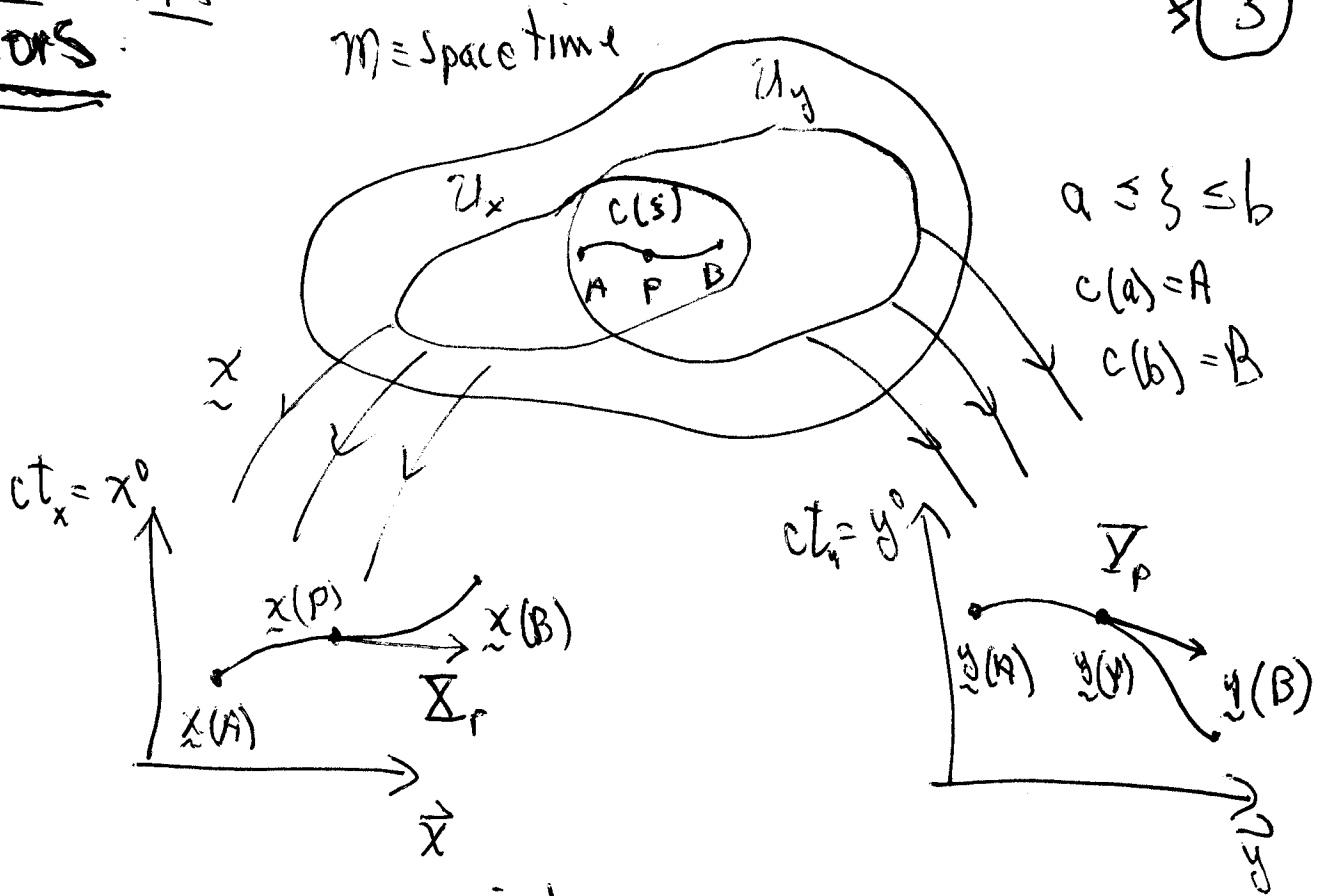


④ Vectors Tensors As

① ③



• The curve in \underline{x} -coordinates:

$$\underline{x}(c(s)) \equiv (x^0(s), x^1(s), \dots, x^3(s)) = \underline{x}^i(s) = \underline{x}^i(\xi) \quad i=0,1,2,3$$

The curve in \underline{y} -coordinates:

$$\underline{y}(c(s)) \equiv (y^0(s), \dots, y^3(s)) = \underline{y}^a(s) \quad a=0,1,2,3$$

$$= \underline{y}^a(\xi)$$

x-Tangent to curve: $\frac{d}{d\xi} \underline{x}^i(s) \Big|_P = (\dot{x}^0(s), \dots, \dot{x}^3(s)) = \dot{\underline{x}}^i(s)$

$(\underline{X}_P = \underline{x}$ -coord tangent to curve @ $P = \underline{x}(s) \Big|_P) = \dot{\underline{x}}^i(s)$

y-Tangent to curve: $\frac{d}{d\xi} \underline{y}^a(s) \Big|_P = \dot{\underline{y}}^a(s) = \dot{\underline{y}}^a(s)$

$(\underline{Y}_P = \underline{y}$ -coord tangent to curve @ $P = \underline{y}(s) \Big|_P)$

- Note: The curve $c(s)$ makes sense in spacetime. (2)

$$c: \mathbb{R} \rightarrow \mathcal{M}$$

since \mathcal{M} is a set of points ("events" of spacetime)

But: The tangent to curve at P does not make sense in \mathcal{M} . It only makes sense as a vector in each coordinate system.

- Consider $\underline{\Sigma}_P \equiv x$ -tangent to $c(s)$ @ P .

$\underline{\Sigma}_P$ has a length and a direction

$$\underline{\Sigma}_P = a^0 \vec{e}_0 + a^1 \vec{e}_1 + a^2 \vec{e}_2 + a^3 \vec{e}_3$$

Here, (a^0, a^1, a^2, a^3) are the components of $\underline{\Sigma}_P$ wrt the coordinate basis $(\vec{e}_0, \vec{e}_1, \vec{e}_2, \vec{e}_3)$.

Eg, $\vec{e}_0 = \overrightarrow{(1, 0, 0, 0)}$, $\vec{e}_1 = \overrightarrow{(0, 1, 0, 0)}$ etc

Note: The components are different from the coordinate unit vectors!

• In differential geometry we don't use the names \hat{e}_i for coordinate unit vectors. We use $\textcircled{3}$

$$\frac{\partial}{\partial x^i} = \hat{e}_i = \overbrace{(0 \dots 1 \dots 0)}^{\text{ith component}}$$

Thus: $\left\{ \frac{\partial}{\partial x^0}, \frac{\partial}{\partial x^1}, \frac{\partial}{\partial x^2}, \frac{\partial}{\partial x^3} \right\}_P$ is a basis for the tangent space of $\mathbb{R}^4 @ \underline{x}(P)$.

Note: The y-coordinate basis $\left\{ \frac{\partial}{\partial y^k} \right\}_{\alpha=0}^3 @ P$ names a different set of directions in spacetime. Sometimes we write $\frac{\partial}{\partial x^i} \Big|_P, \frac{\partial}{\partial y^k} \Big|_P$

Q: How do the components of tangent vectors ~~transform~~ transform $x \rightarrow y @ P$
 Q: how do the basic vectors transform?

Ans As tensors, by the Jacobian $\frac{\partial y^k}{\partial x^i} \Big|_P$.

Theorem. The tangent vector to $c(s) \in P^3$ in x -coords is

$$\underline{\dot{X}}_p = \dot{x}^i \frac{\partial}{\partial x^i} \Big|_p$$

and in y -coords is

$$\underline{\dot{Y}}_p = \dot{y}^\alpha \frac{\partial}{\partial y^\alpha} \Big|_p$$

(Sum repeated up-down indices from 0, 1, 2, 3)

This gives vector in terms of coord bases.

Moreover, $\dot{x}^i, \dot{y}^\alpha, \frac{\partial}{\partial x^i}, \frac{\partial}{\partial y^\alpha}$ transform by

$$\dot{y}^\alpha = \frac{\partial y^\alpha}{\partial x^i} \dot{x}^i \quad (\Leftrightarrow) \quad \underline{\dot{y}} = J \cdot \underline{\dot{x}} \quad J = \frac{\partial y}{\partial x}$$

$4 \times 1 \quad 4 \times 4 \quad 4 \times 1$

$$\frac{\partial}{\partial y^\alpha} = \frac{\partial x^i}{\partial y^\alpha} \frac{\partial}{\partial x^i} \quad (\Leftrightarrow) \quad \underline{\frac{\partial}{\partial y}} = \underline{\frac{\partial}{\partial x}} J^{-1} \quad J^{-1} = \frac{\partial x}{\partial y}$$

$1 \times 4 \quad 1 \times 4$

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Proof: To get $\vec{\Sigma}_p = \dot{x}^i \frac{\partial}{\partial x^i}$ recall:

$\tilde{x}(\xi) \equiv \tilde{x}(c(\xi))$ curve in x -coords

$$\tilde{x}(\xi) = (x^0(\xi), x^1(\xi), x^2(\xi), x^3(\xi))$$

$$\frac{d}{d\xi} \tilde{x}(\xi) \equiv \dot{\tilde{x}}(\xi) = (\dot{x}^0(\xi), \dots, \dot{x}^3(\xi))$$

∴ The vector $\overrightarrow{(\dot{x}^0(\xi), \dots, \dot{x}^3(\xi))}_p$ is tan. to $\mathcal{E}(\xi)$ at p

Conclude: in terms of the x -coord basis

$$\vec{\Sigma}_p = \underbrace{\dot{x}^i(\xi)}_{\substack{\uparrow \\ \text{components}}} \underbrace{\frac{\partial}{\partial x^i}}_{\substack{\nwarrow \\ \text{x-coord. basis}}}$$

sum $i=0,1,2,3$

Similarly: $\vec{\Gamma}_p = \dot{y}^\alpha(\xi) \frac{\partial}{\partial y^\alpha}$

• To get the transformation laws: recall

$$\begin{aligned} \tilde{x}(\xi) &= \tilde{x}(c(\xi)) & x^i(\xi) &= x^i(c(\xi)) \\ \tilde{y}(\xi) &= \tilde{y}(c(\xi)) & y^\alpha(\xi) &= y^\alpha(c(\xi)) \end{aligned}$$

so

$$\tilde{y}(c(\xi)) = \underbrace{\tilde{y} \circ \tilde{x}^{-1}}_{\substack{\tilde{y} \leftarrow \tilde{x} \\ \mathbb{R}^4 \leftarrow \mathbb{R}^4}} \circ \underbrace{\tilde{x} \circ c(\xi)}_{\tilde{x}(\xi)}$$

$$y^\alpha(\xi) = (\tilde{y}^\alpha \circ \tilde{x}^{-1}) \circ (\tilde{x} \circ c)(\xi)$$

$$\frac{d y^\alpha}{d \xi} = \dot{y}^\alpha = \frac{\partial y^\alpha}{\partial x^i} \frac{d x^i}{d \xi} = J \cdot \dot{\tilde{x}}$$

$4 \times 4 \quad 4 \times 1$

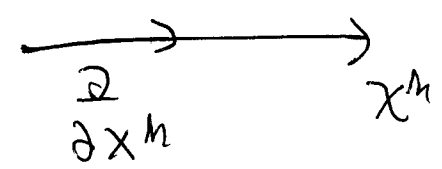
(Chain rule: $\frac{d}{d \xi} (\tilde{y}^\alpha \circ \tilde{x}^{-1}) \circ (\tilde{x} \circ c)(\xi)$)

$$= \frac{\partial y^\alpha}{\partial x^i} \frac{d x^i}{d \xi} \quad \text{sum } i = 0, 1, 2, 3$$

Eg $\left. \frac{d}{d \xi} f(x^1(\xi), x^2(\xi)) = \frac{\partial f}{\partial x^1} \frac{d x^1}{d \xi} + \frac{\partial f}{\partial x^2} \frac{d x^2}{d \xi} = \frac{\partial f}{\partial x^i} \frac{d x^i}{d \xi} \right)$

To see how the bases transform:

Consider the x -coord unit vector $\frac{\partial}{\partial x^h}$ for some fixed $h=0,1,2,3$

This is the tangent vector to the coordinate axis, i.e. the curve 

$$x^h(\xi) = \xi \quad x^j(\xi) = 0 \quad j \neq h$$

$$\dot{x}^h(\xi) = 1, \quad \dot{x}^j(\xi) = 0 \quad j \neq h$$

Thus: $\frac{\partial}{\partial x^h} = \sum_p \dots$ is tangent to curve $x(\xi)$ with $\dot{x}^h = 1, \dot{x}^j = 0 \quad j \neq h$.

But we have for this curve, \sum_p has comp's

$$y^\alpha = \frac{\partial y^\alpha}{\partial x^i} \dot{x}^i = \frac{\partial y^\alpha}{\partial x^h} \dot{x}^h = \frac{\partial y^\alpha}{\partial x^h} (\dot{x}^j = 0 \quad j \neq h! \quad \dot{x}^h = 1)$$

$$\therefore \sum_p = \frac{\partial}{\partial x^h} \text{ means } \sum_p = \dot{y}^\alpha \frac{\partial}{\partial y^\alpha} = \frac{\partial y^\alpha}{\partial x^h} \frac{\partial}{\partial y^\alpha}$$

$$\sum_p = \sum_p \text{ means } \frac{\partial}{\partial x^h} = \frac{\partial y^\alpha}{\partial x^h} \frac{\partial}{\partial y^\alpha}$$

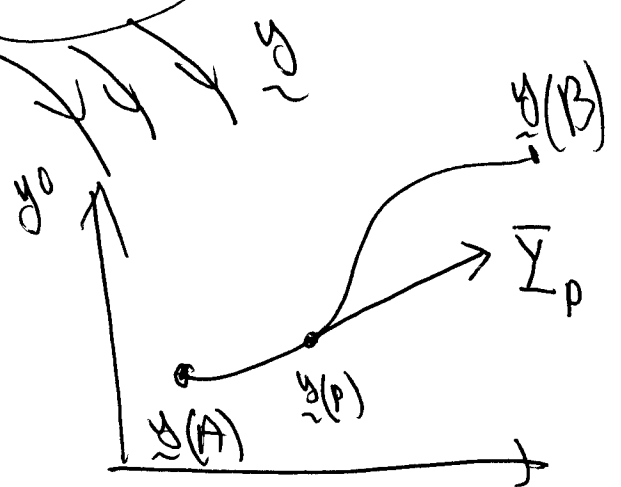
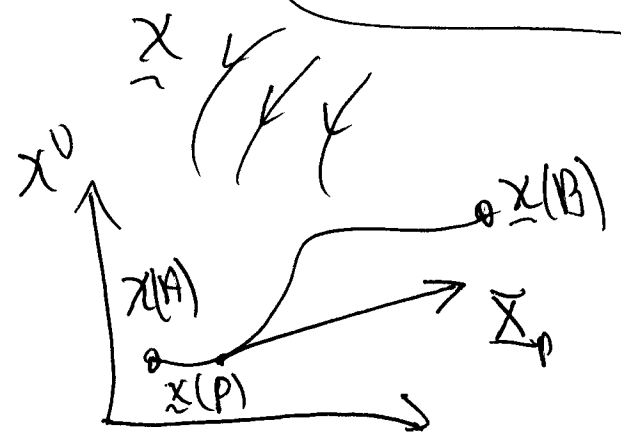
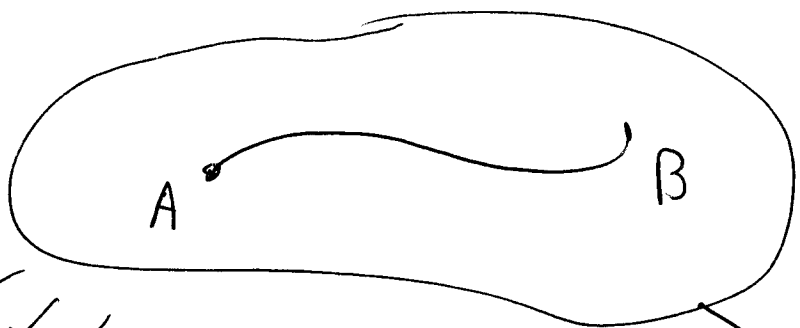
• Summary: $\underline{\Sigma}_p$ & $\underline{\Upsilon}_p$ name the same vector at p iff

$$\underline{\Sigma}_p = a^i \frac{\partial}{\partial x^i} \quad \underline{\Upsilon}_p = b^\alpha \frac{\partial}{\partial y^\alpha}$$

where $a^i = \frac{\partial x^i}{\partial y^\alpha} b^\alpha$, $\frac{\partial}{\partial x^i} = \frac{\partial y^\alpha}{\partial x^i} \frac{\partial}{\partial y^\alpha}$

$\Leftrightarrow b^\alpha = \frac{\partial y^\alpha}{\partial x^i} a^i$, $\frac{\partial}{\partial y^\alpha} = \frac{\partial x^i}{\partial y^\alpha} \frac{\partial}{\partial x^i}$ (*)

We say: $\underline{\Sigma}_p = \underline{\Upsilon}_p$ is the same vector iff (*).



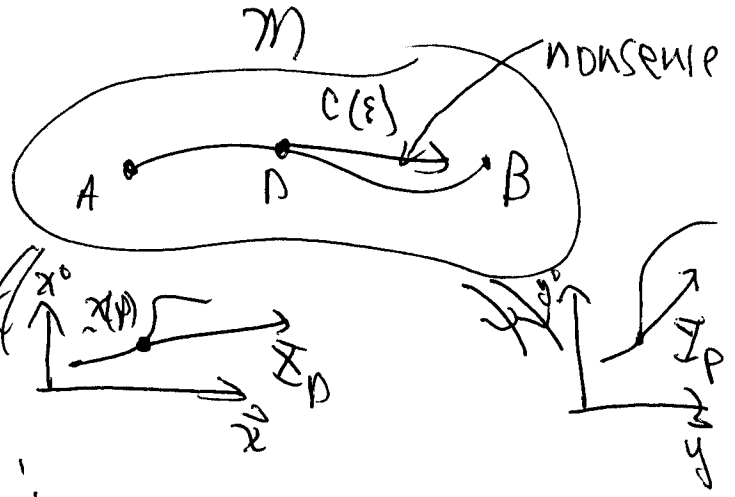
$$\underline{\Sigma}_p = \dot{x}^i \frac{\partial}{\partial x^i} = \dot{y}^\alpha \frac{\partial}{\partial y^\alpha} = \underline{\Upsilon}_p$$

Defn: We say an up-index transforms contravariantly ($a^i = \frac{\partial x^i}{\partial y^\alpha} b^\alpha$) and a

down index transforms covariantly ($\frac{\partial}{\partial x^i} = \frac{\partial y^\alpha}{\partial x^i} \frac{\partial}{\partial y^\alpha}$)

⊗ How can we define $\Sigma_p = \Sigma_p$ as something indept of coords? "c'(s)" doesn't make sense

Ans: View



$a^i \frac{\partial}{\partial x^i}$ like $b^\alpha \frac{\partial}{\partial y^\alpha}$ as

operator on functions:

$f: M \rightarrow \mathbb{R}$ (make sense)

$f \circ \tilde{x}^{-1}: \mathbb{R}^4 \rightarrow \mathbb{R}$ $f \circ \tilde{y}^{-1}: \mathbb{R}^4 \rightarrow \mathbb{R}$ (make sense)

$a^i \frac{\partial}{\partial x^i} (f \circ \tilde{x}^{-1}) = a^i \frac{\partial f}{\partial x^i} = b^\alpha \frac{\partial}{\partial y^\alpha} (f \circ \tilde{y}^{-1}) = b^\alpha \frac{\partial f}{\partial y^\alpha}$

" $a^i \frac{\partial}{\partial x^i} = b^\alpha \frac{\partial}{\partial y^\alpha}$ " in the sense that they are the same differential operator on functions.