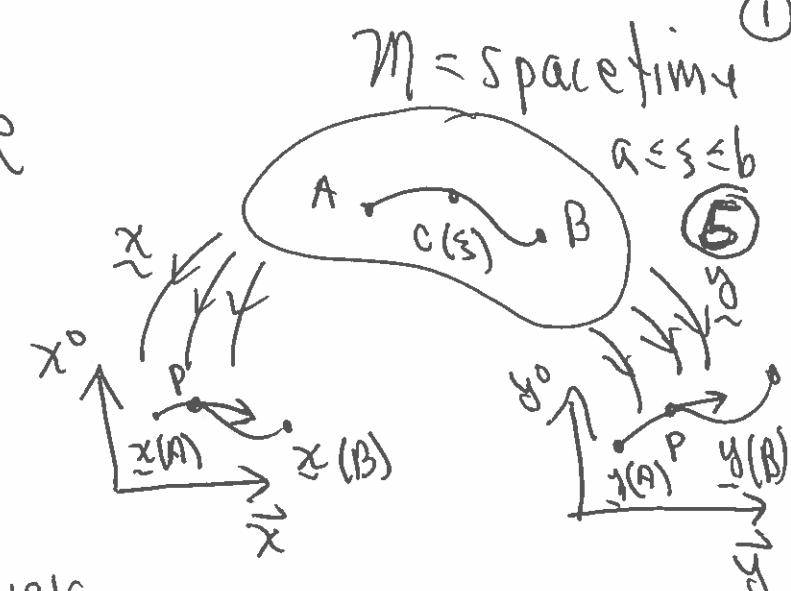


► Tensors: We have

- Summary -

• Spacetime is the manifold of events \mathcal{M}



- Coordinate systems cover spacetime, and quantitative properties of spacetime are described in word systems
- Curve $C(s)$ in spacetime can be represented in coordinate systems

$$\underline{x}^0 C(s) = \underline{x}(s) \quad x\text{-word rep of } C$$

$$\underline{y}^0 C(s) = \underline{y}(s) \quad y\text{-word rep of } C$$

Asking that tangent vectors to the same curve at P , but represented in diff word systems, be the same vector, tells us how to identify same vector in diff words

- $T_p M$ = tangent space of $M \otimes P$ is the collection of all tangent vectors $\otimes P$, with representations of a vector $X_p \in T_p M$ in different coordinates viewed as the same vector given in terms of a different basis

$$X_p = \left[\begin{array}{c} a^i \frac{\partial}{\partial x^i} \\ \vdots \\ a^d \frac{\partial}{\partial x^d} \end{array} \right]_P = \left[\begin{array}{c} \bar{a}^\alpha \frac{\partial}{\partial y^\alpha} \\ \vdots \\ \bar{a}^\alpha \frac{\partial}{\partial y^\alpha} \end{array} \right]_P$$

↑ x -basis
 of X_p ↑ x -basis
 of X_p
 basis basis

↑ y -basis
 of X_p ↑ y -basis
 of X_p
 basis basis

$$T_p M = \text{Span} \left\{ \left. \frac{\partial}{\partial x^0} \right|_P, \dots, \left. \frac{\partial}{\partial x^d} \right|_P \right\} = \left\{ \left. a^i \frac{\partial}{\partial x^i} \right|_P : a^i \in \mathbb{R} \right\}$$

$$= \text{Span} \left\{ \left. \frac{\partial}{\partial y^0} \right|_P, \dots, \left. \frac{\partial}{\partial y^d} \right|_P \right\} = \left\{ \left. \bar{a}^\alpha \frac{\partial}{\partial y^\alpha} \right|_P : \bar{a}^\alpha \in \mathbb{R} \right\}$$

$a^i = \frac{\partial x^i}{\partial y^\alpha} \bar{a}^\alpha$, $\left. \frac{\partial}{\partial x^i} \right|_P = \left. \frac{\partial y^\alpha}{\partial x^i} \frac{\partial}{\partial y^\alpha} \right|_P$

(3)

- T_p^*M = cotangent space of $M @ p$ is the collection of all 1-forms @ p , each 1-form $\overset{w_p \in T_p^*M}{\sim}$ has a different representation wrt a different basis in each coordsystem.

$$\underset{\substack{\text{x-comp} \\ \text{of } w_p}}{\overset{\rightarrow}{\underset{\substack{\text{x-coord} \\ \text{basis of} \\ 1\text{-forms}}}{\uparrow}}} \underset{\substack{\text{y-word} \\ \text{component} \\ \text{of } w_p}}{\overset{\rightarrow}{\underset{\substack{\text{y-word} \\ \text{basis} \\ \text{of 1-forms}}}{\uparrow}}} \underset{\substack{\text{y-word} \\ \text{basis} \\ \text{of 1-forms}}}{\downarrow} \underset{\substack{\text{y-word} \\ \text{basis} \\ \text{of 1-forms}}}{\downarrow}$$

$$a_i dx^i|_p = w_p = \bar{a}_\alpha dy^\alpha$$

1-forms are viewed as linear functionals on tangent vectors: $dx^i|_p : T_p M \rightarrow \mathbb{R}$

$$dx^i(\underline{x}_p) = a_i^i, \quad \underline{x}_p = a^i \frac{\partial}{\partial x^i}$$

$$w_p(\underline{x}_p) = a_i dx^i(\underline{x}_p) = a_i b^i = \bar{a}_\alpha dy^\alpha(\underline{x}_p) = \bar{a}_\alpha^i b^i$$

$$\boxed{a_i = \frac{\partial y^\alpha}{\partial x^i} \bar{a}_\alpha}$$

$$dx^i|_p = \frac{\partial x^i}{\partial y^\alpha} dy^\alpha|_p$$

$$\underline{x}_p = b^i \frac{\partial}{\partial x^i}|_p$$

$$\underline{x}_p = b^\alpha \frac{\partial}{\partial y^\alpha}|_p$$

(4)

- Conclude (Riesz Rep): T_p^*M is the dual space of T_pM (ie. the set of linear fn's on T_pM , "functional" meaning "maps to \mathbb{R} ")
 $\& \dim T_p^*M = 4.$

$$T_p^*M = \text{Span} \{ dx^0|_p, \dots, dx^3|_p \} = \{ a_i dx^i |_p \mid a^i \in \mathbb{R} \}$$

$$= \text{Span} \{ dy^0|_p, \dots, dy^3|_p \} = \{ \bar{a}_i dy^i |_p \mid a^i \in \mathbb{R} \}$$

- General tensors like Riemann Curvature tensor R^i_{jkl} have up & down indices, up transform like components of vectors a^i and down transform like components of covectors a_i . Natural generalization of vector
Key Point: Transformation depends only on 1st derivative $J = \frac{\partial y^k}{\partial x^i}$, not 2nd deriv's

Tensors: A tensor is a multi-component matrix of up & down indices such that up indices transform contravariantly & down indices transform covariantly -

Ex: $R^i_{jkl} = ({}^1_3)$ -tensor |_P

$$R^i_{jkl} = \frac{\partial x^i}{\partial y^j} R^\alpha_{\beta\gamma\delta} \frac{\partial y^\beta}{\partial x^k} \frac{\partial y^\gamma}{\partial x^l} \frac{\partial y^\delta}{\partial x^\alpha} \quad (*)$$

$$\left(\begin{array}{c} \\ \\ \end{array} \right) \rightarrow$$

same tensor
in y-coordinates

"You can think of tensors as multicomponent matrices defined at a pt P such that they transform "linearly" in each $T_p M$ by (*)

Operations on tensors -

- Raising & lowering by metric:

Ex: R^i_{jkl} is a (1) -tensor

$R_{ijlk} = g_{ij} R_{jkl}$ is a (0) -tensor

$$R^{ji}_{ijkl} = R^i_{jkl}$$

Thm: Lower & raising of indices is a tensor operation.

$$\bar{g}^{\alpha\sigma} R_{\sigma\beta\delta} = \frac{\partial y^\alpha}{\partial x^i} g_{ij} \frac{\partial y^\sigma}{\partial x^j} \frac{\partial x^k}{\partial y^\beta} \frac{\partial x^\ell}{\partial y^\delta} R_{k\beta\ell\delta}$$

- Contracting up-down indices

Ex: $R^m_{iml} = R_{ilm}$

$$= \frac{\partial y^\alpha}{\partial x^i} \frac{\partial y^\sigma}{\partial x^l} R_{\alpha\beta\sigma} \frac{\partial x^\beta}{\partial y^\alpha}$$

Thm: Contracting up down indices is a tensor operation

$$\text{I.e. } \bar{R}^\alpha_{\alpha\beta} = \frac{\partial y^\alpha}{\partial x^i} R^i_{jkl} \frac{\partial x^j}{\partial y^\alpha} \frac{\partial x^k}{\partial y^\beta} \frac{\partial x^\ell}{\partial y^\beta} = R^k_{jkl} \frac{\partial x^j}{\partial y^\alpha} \frac{\partial x^k}{\partial y^\beta}$$

$\sum_k \delta_{jk}$

- Note: A metric gives meaning to the gradient as a vector:

$$df = \frac{\partial f}{\partial x^i} dx^i \quad (\text{a 1-form} =) \\ (\text{covector})$$

$$g^{ij} \frac{\partial}{\partial x^i} = \partial^j f$$

Defn. We call $\left. \partial^j f \frac{\partial}{\partial x^i} \right|_P = \nabla f^j$ the gradient of f at P

Note: if $g^{ij} = \text{Id}^{ij} = \begin{bmatrix} 1 & . & 0 \\ . & 1 & . \\ 0 & . & 1 \end{bmatrix}$
then we can't tell diffew between
 ∇f & df &

• Example: Linear transformation:

Consider a matrix that defines a linear transformation of $T_p M$:

$$T: T_p M \rightarrow T_p M$$

$$\begin{array}{ccc} X_p & \xrightarrow{\quad} & Y_p \\ a^i \frac{\partial}{\partial x^i} \Big|_p & \xrightarrow{\quad} & b^j \frac{\partial}{\partial x^j} \Big|_p \end{array}$$

As matrix multiplication $T \underline{a} = \underline{b}$

$$\text{As tensor: } T^j_i a^i = b^j$$

\nwarrow^{row}
 \searrow^{colm}

$$\text{In } y\text{-words: } T^j_i \frac{\partial x^i}{\partial y^\alpha} \bar{a}^\alpha = \frac{\partial x^j}{\partial y^\beta} b^\beta$$

$$\frac{\partial y^\beta}{\partial x^i} T^j_i \frac{\partial x^i}{\partial y^\alpha} \bar{a}^\alpha = b^\beta$$

$$J^{-1} T_x J = T_y \Leftrightarrow \underbrace{T_\alpha^B}_{T^B_\alpha} \Rightarrow T \text{ is } (1)\text{-tensor.}$$

(9)

- Transformation matrices = (1)-tensors transform by similarity transformations
- Transformations have eigenvalues & eigenvectors defined indept of basis = coordinates:

$$\text{Eg } T_j^i a^j = \lambda a^i \quad x\text{-coords @ P}$$

$$\Leftrightarrow T_B^A \bar{a}^B = \lambda \bar{a}^A \quad y\text{-coords @ P}$$

$$T: \mathbb{X}_P \rightarrow \lambda \mathbb{X}_P \quad \text{indept of coords}$$

(Homework)

- Q_i , T_j^i are the components of
a (1,1)-tensor, so component wrt what
basis? I.e.

$$X_p = \underset{\text{comps}}{\underset{\uparrow}{a^i}} \underset{\text{basis}}{\underset{\uparrow}{\frac{\partial}{\partial x^i}}} |_p$$

$$T_p = T_j^i \cdot \underset{\text{comps}}{\underset{\uparrow}{\frac{\partial}{\partial x^i}}} \otimes \underset{\text{basis}}{\underset{\uparrow}{dx^j}}$$

$$\frac{\partial}{\partial x^i} \otimes dx^j \left[\underset{\text{comps}}{\underset{\uparrow}{w_p}}, \underset{\text{basis}}{\underset{\uparrow}{X_p}} \right] = a_i b^j$$

$$w_p = a_i dx^i \quad X_p = b^j \frac{\partial}{\partial x^j}$$

" $\left\{ \frac{\partial}{\partial x^i} \otimes dx^j \right\}$ is the x-coord basis for the
multi-linear operators $L: (T_p^*M, T_p M) \rightarrow \mathbb{R}$ "
This gives tensors a coord indept meaning.

• Thus we call $(\mathcal{Y}_1')_p^M$ = set of
all (1) -tensors at p . (11)

$$(\mathcal{Y}_1')_p^M = \text{Span} \left\{ \frac{\partial}{\partial x^i} \otimes dx^j \right\}_p = \left\{ A_j^i \frac{\partial}{\partial x^i} \otimes dx^j \right\}_p$$

$$= \text{Span} \left\{ \frac{\partial}{\partial y^a} \otimes dy^b \right\}_p = \left\{ A_j^i \frac{\partial}{\partial y^a} \otimes dy^b \right\}_p$$

For example: $A \in (\mathcal{Y}_1')_p^M \Rightarrow$

$$A = A_j^i \frac{\partial}{\partial x^i} \otimes dx^j \Big|_p : T_p^*M \times T_p M \rightarrow \mathbb{R}$$

$$A[\omega_p, \bar{x}_p] = A_j^i \frac{\partial}{\partial x^i} \otimes dx^j [\omega_p, \bar{x}_p] = A_j^i a_i b^j$$

Also:

$$\omega_p = a_i dx^i, \bar{x}_p = b^j \frac{\partial}{\partial x^j}$$

$$A = A_B^\alpha \frac{\partial}{\partial y^a} \otimes dy^B \Big|_p : T_p^*M \times T_p M \rightarrow \mathbb{R}$$

$$A[\omega_p, \bar{x}_p] = A_B^\alpha \bar{a}_a \bar{b}^B = A_j^i a_i b^j \text{ by tensor basic trans laws}$$

same operator different basis

• Conclude - Tensors are the natural linear objects that measure properties of spacetime at point P -

Eg: Curvature / Velocity / Density / Energy Momentum vector of particle
Energy-momentum density & their fluxes = stress energy tensor

Einstein - The equations that give the physical constraints on g_{ij} required for it to be a gravitational field should be expressed in terms of

Ans:

$$G_{ij} = \kappa T_{ij}$$

An equation for g_{ij} given T_{ij}

tensors -