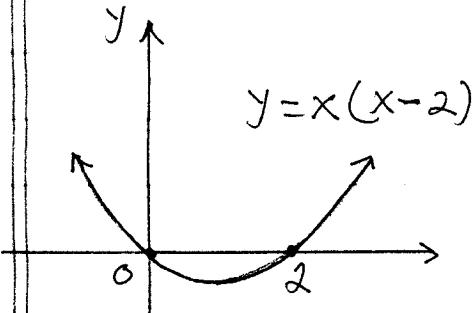


Section 13.1

1.) $\vec{r}(t) = (t+1)\vec{i} + (t^2 - 1)\vec{j} \rightarrow$

$$\begin{cases} x = t+1 \rightarrow t = x-1 \\ y = t^2 - 1 \end{cases} \xleftarrow{\text{(SUB)}} y = (x-1)^2 - 1 \rightarrow$$

$$y = x^2 - 2x + x - 1 \rightarrow y = x(x-2) \quad (\text{parabola});$$



$$\vec{v}(t) = \vec{r}'(t) = 1 \cdot \vec{i} + 2t \cdot \vec{j} \xrightarrow{\text{D}}$$

$$\vec{a}(t) = \vec{v}'(t) = 0 \cdot \vec{i} + 2 \cdot \vec{j}; \text{ then}$$

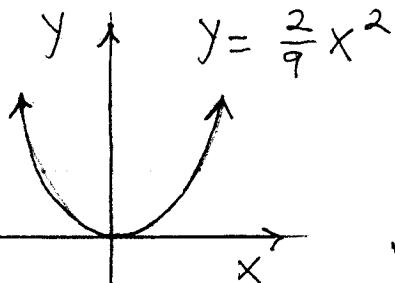
$$\vec{v}(1) = \vec{i} + 2\vec{j} \quad \text{and}$$

$$\vec{a}(1) = 2\vec{j}$$

3.) $\vec{r}(t) = e^t \vec{i} + \frac{2}{9} e^{2t} \vec{j} \rightarrow$

$$\begin{cases} x = e^t \end{cases} \xrightarrow{\text{(SUB)}}$$

$$\begin{cases} y = \frac{2}{9} e^{2t} = \frac{2}{9} (e^t)^2 \end{cases} \rightarrow y = \frac{2}{9} x^2 \quad (\text{parabola});$$



$$\vec{v}(t) = \vec{r}'(t) = e^t \cdot \vec{i} + \frac{4}{9} e^{2t} \vec{j} \xrightarrow{\text{D}}$$

$$\vec{a}(t) = \vec{v}'(t) = e^t \cdot \vec{i} + \frac{8}{9} e^{2t} \cdot \vec{j}; \text{ then}$$

$$\vec{v}(\ln 3) = e^{\ln 3} \cdot \vec{i} + \frac{4}{9} \cdot e^{2\ln 3} \cdot \vec{j}$$

$$= 3\vec{i} + \frac{4}{9} e^{\ln 3^2} \cdot \vec{j} = 3\vec{i} + \frac{4}{9} \cdot 9\vec{j} \rightarrow \vec{v} = 3\vec{i} + 4\vec{j},$$

$$\vec{a}(\ln 3) = e^{\ln 3} \vec{i} + \frac{8}{9} e^{2\ln 3} \cdot \vec{j} = 3\vec{i} + 8\vec{j}$$

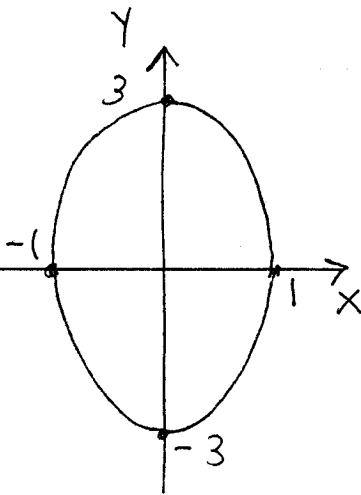
4.) $\vec{r}(t) = (\cos 2t)\vec{i} + (3 \sin 2t)\vec{j} \rightarrow$

$$\begin{cases} x = \cos 2t \end{cases}$$

$$\begin{cases} y = 3 \sin 2t \end{cases} \rightarrow \frac{y}{3} = \sin 2t, \text{ then}$$

$$x^2 + \left(\frac{y}{3}\right)^2 = \cos^2 2t + \sin^2 2t = 1 \rightarrow x^2 + \left(\frac{y}{3}\right)^2 = 1;$$

$$(\text{ellipse}) \quad \vec{v}(t) = (-2 \sin 2t)\vec{i} + (6 \cos 2t)\vec{j}$$



$$\stackrel{D}{\rightarrow} \vec{a}(t) = (-4 \cos 2t) \vec{i} + (-12 \sin 2t) \vec{j},$$

then

$$\vec{v}(0) = (-2 \sin 0) \vec{i} + (6 \cos 0) \vec{j}$$

$$= 6 \vec{j}$$

$$\vec{a}(0) = (-4 \cos 0) \vec{i} + (-12 \sin 0) \vec{j}$$

$$= -4 \vec{i}$$

$$6.) \vec{r}(t) = (4 \cos \frac{t}{2}) \vec{i} + (4 \sin \frac{t}{2}) \vec{j} \stackrel{D}{\rightarrow}$$

$$\vec{v}(t) = (-2 \sin \frac{t}{2}) \vec{i} + (2 \cos \frac{t}{2}) \vec{j} \stackrel{D}{\rightarrow}$$

$$\vec{a}(t) = (-\cos \frac{t}{2}) \vec{i} + (-\sin \frac{t}{2}) \vec{j} ; \text{ if } t = \pi$$

then $\vec{r}(\pi) = 0 \cdot \vec{i} + 4 \vec{j} = 4 \vec{j}$,

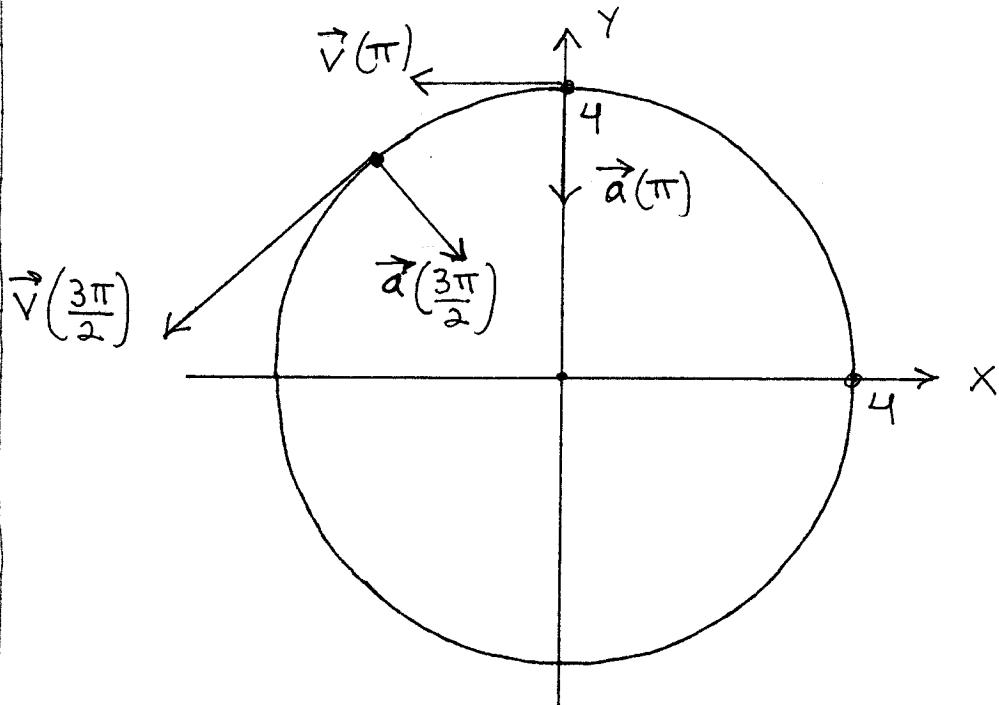
$$\vec{v}(\pi) = -2 \vec{i} + 0 \cdot \vec{j} = -2 \vec{i}$$

$$\vec{a}(\pi) = 0 \cdot \vec{i} + (-1) \vec{j} = -\vec{j} ; \text{ if } t = \frac{3\pi}{2}$$

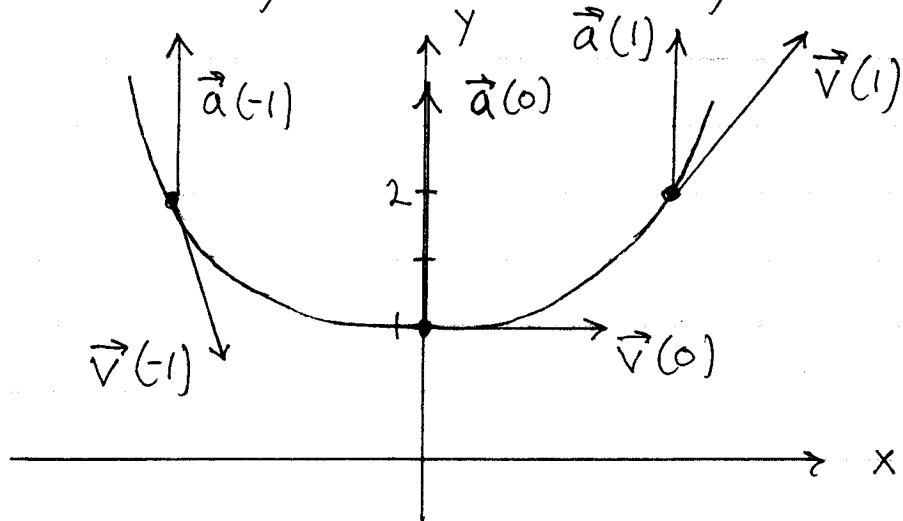
then $\vec{r}\left(\frac{3\pi}{2}\right) = (4 \cdot -\frac{\sqrt{2}}{2}) \vec{i} + (4 \cdot \frac{\sqrt{2}}{2}) \vec{j} = -2\sqrt{2} \vec{i} + 2\sqrt{2} \vec{j}$,

$$\vec{v}\left(\frac{3\pi}{2}\right) = (-2 \cdot \frac{\sqrt{2}}{2}) \vec{i} + (2 \cdot \frac{\sqrt{2}}{2}) \vec{j} = -\sqrt{2} \cdot \vec{i} - \sqrt{2} \cdot \vec{j}$$

$$\vec{a}\left(\frac{3\pi}{2}\right) = \frac{\sqrt{2}}{2} \vec{i} + -\frac{\sqrt{2}}{2} \vec{j} ;$$



8.) $\vec{r}(t) = t \cdot \vec{i} + (t^2 + 1) \cdot \vec{j} \quad \xrightarrow{D}$
 $\vec{v}(t) = 1 \cdot \vec{i} + 2t \cdot \vec{j} \quad \xrightarrow{D}$
 $\vec{a}(t) = 0 \cdot \vec{i} + 2 \cdot \vec{j}; \text{ if } t = -1 \rightarrow$
 $\vec{r}(-1) = -\vec{i} + 2\vec{j}$
 $\vec{v}(-1) = \vec{i} - 2\vec{j}, \vec{a}(-1) = 2\vec{j}; \text{ if } t = 0 \rightarrow$
 $\vec{r}(0) = \vec{j}, \vec{v}(0) = \vec{i}, \vec{a}(0) = 2\vec{j}; \text{ if } t = 1 \rightarrow$
 $\vec{r}(1) = \vec{i} + 2\vec{j}, \vec{v}(1) = \vec{i} + 2\vec{j}, \vec{a}(1) = 2\vec{j}$



10.) $\vec{r}(t) = (1+t)\vec{i} + \frac{1}{12}t^2 \cdot \vec{j} + \frac{1}{3}t^3 \cdot \vec{k} \quad \xrightarrow{D}$
 $\vec{v}(t) = 1 \cdot \vec{i} + \sqrt{2}t \cdot \vec{j} + t^2 \vec{k} \quad \xrightarrow{D}$
 $\vec{a}(t) = 0 \cdot \vec{i} + \sqrt{2} \cdot \vec{j} + 2t \cdot \vec{k}; \text{ if } t = 1 \text{ then}$
 $\vec{v}(1) = \vec{i} + \sqrt{2}\vec{j} + \vec{k} \text{ so speed is}$
 $|\vec{v}(1)| = \sqrt{1^2 + (\sqrt{2})^2 + 1^2} = \sqrt{4} = 2, \text{ then}$
 $\text{direction of motion is}$
 $\frac{\vec{v}(1)}{|\vec{v}(1)|} = \frac{1}{2}\vec{i} + \frac{1}{\sqrt{2}}\vec{j} + \frac{1}{2}\vec{k} \quad \text{and}$
 $\vec{v}(1) = 2 \left(\frac{1}{2}\vec{i} + \frac{1}{\sqrt{2}}\vec{j} + \frac{1}{2}\vec{k} \right)$

$$12.) \quad \vec{r}(t) = (\sec t) \vec{i} + (\tan t) \vec{j} + \frac{4}{3} t \vec{k} \xrightarrow{D}$$

$$\vec{v}(t) = (\sec t \tan t) \vec{i} + (\sec^2 t) \vec{j} + \frac{4}{3} \vec{k} \xrightarrow{D}$$

$$\begin{aligned} \vec{a}(t) &= (\sec t \cdot \sec^2 t + \sec t \tan t \cdot \tan t) \cdot \vec{i} \\ &\quad + (2 \sec t \cdot \sec t \tan t) \vec{j} + 0 \cdot \vec{k} \\ &= (\sec^3 t + \sec t \cdot \tan^2 t) \vec{i} \\ &\quad + (2 \sec^2 t \tan t) \vec{j}; \text{ if } t = \frac{\pi}{6} \end{aligned}$$

$$\begin{aligned} \vec{v}\left(\frac{\pi}{6}\right) &= \left(\sec \frac{\pi}{6} \tan \frac{\pi}{6}\right) \vec{i} + \left(\sec^2 \frac{\pi}{6}\right) \vec{j} + \frac{4}{3} \vec{k} \\ &= \frac{2}{\sqrt{3}} \cdot \frac{1}{\sqrt{3}} \vec{i} + \left(\frac{2}{\sqrt{3}}\right)^2 \vec{j} + \frac{4}{3} \vec{k} \\ &= \frac{2}{3} \vec{i} + \frac{4}{3} \vec{j} + \frac{4}{3} \vec{k}, \text{ so speed is} \end{aligned}$$

$$\begin{aligned} |\vec{v}\left(\frac{\pi}{6}\right)| &= \sqrt{\left(\frac{2}{3}\right)^2 + \left(\frac{4}{3}\right)^2 + \left(\frac{4}{3}\right)^2} = \sqrt{\frac{4}{9} + \frac{16}{9} + \frac{16}{9}} \\ &= \sqrt{\frac{36}{9}} = \sqrt{4} = 2; \text{ and direction} \end{aligned}$$

of motion is $\frac{\vec{v}\left(\frac{\pi}{6}\right)}{|\vec{v}\left(\frac{\pi}{6}\right)|} = \frac{1}{3} \vec{i} + \frac{2}{3} \vec{j} + \frac{2}{3} \vec{k};$

$$\vec{v}\left(\frac{\pi}{6}\right) = 2 \left(\frac{1}{3} \vec{i} + \frac{2}{3} \vec{j} + \frac{2}{3} \vec{k} \right).$$

$$13.) \quad \vec{r}(t) = (2 \ln(t+1)) \vec{i} + t^2 \vec{j} + \frac{t^2}{2} \vec{k} \xrightarrow{D}$$

$$\vec{v}(t) = \frac{2}{t+1} \vec{i} + 2t \vec{j} + t \vec{k} \xrightarrow{D}$$

$$\vec{a}(t) = \frac{-2}{(t+1)^2} \vec{i} + 2 \vec{j} + 1 \vec{k}; \text{ if } t=1$$

$$\begin{aligned} \vec{v}(1) &= 1 \vec{i} + 2 \vec{j} + 1 \vec{k} \text{ so speed is} \\ |\vec{v}(1)| &= \sqrt{1^2 + 2^2 + 1^2} = \sqrt{6} \text{ and direction} \\ \text{of motion is} \end{aligned}$$

$$\frac{\vec{v}(1)}{|\vec{v}(1)|} = \frac{1}{\sqrt{6}} \vec{i} + \frac{2}{\sqrt{6}} \vec{j} + \frac{1}{\sqrt{6}} \vec{k} ;$$

$$\vec{v}(1) = \sqrt{6} \left(\frac{1}{\sqrt{6}} \vec{i} + \frac{2}{\sqrt{6}} \vec{j} + \frac{1}{\sqrt{6}} \vec{k} \right) .$$

15.) $\vec{r}(t) = (3t+1) \vec{i} + \sqrt{3} \cdot t \vec{j} + t^2 \vec{k} \xrightarrow{D}$

$$\vec{v}(t) = 3 \cdot \vec{i} + \sqrt{3} \vec{j} + 2t \vec{k} \xrightarrow{D}$$

$$\vec{a}(t) = 0 \cdot \vec{i} + 0 \cdot \vec{j} + 2 \vec{k} ; \text{ if } t=0 \text{ then}$$

$$\vec{v}(0) = 3 \vec{i} + \sqrt{3} \vec{j} + 0 \vec{k} \text{ and}$$

$$\vec{a}(0) = 0 \cdot \vec{i} + 0 \cdot \vec{j} + 2 \vec{k} \rightarrow$$

$$|\vec{v}(0)| = \sqrt{3^2 + (\sqrt{3})^2} = \sqrt{12} \text{ and}$$

$$|\vec{a}(0)| = \sqrt{2^2} = 2 ; \text{ then}$$

$$\cos \theta = \frac{\vec{v}(0) \cdot \vec{a}(0)}{|\vec{v}(0)| |\vec{a}(0)|} = \frac{0+0+0}{\sqrt{12} \cdot 2} = 0 \text{ so}$$

$$\theta = \frac{\pi}{2}$$

17.) $\vec{r}(t) = (\ln(t^2+1)) \vec{i} + (\arctan t) \vec{j} + \sqrt{t^2+1} \cdot \vec{k} \xrightarrow{D}$

$$\vec{v}(t) = \frac{2t}{t^2+1} \vec{i} + \frac{1}{1+t^2} \vec{j} + \frac{t}{\sqrt{t^2+1}} \vec{k} \xrightarrow{D}$$

$$\vec{a}(t) = \frac{(t^2+1)(2)-2t(2t)}{(t^2+1)^2} \vec{i} + \frac{-2t}{(1+t^2)^2} \vec{j}$$

$$+ \frac{\sqrt{t^2+1} (1) - t \cdot \frac{1}{2} (t^2+1)^{-\frac{1}{2}} (2t)}{t^2+1} \vec{k}$$

$$= \frac{2-2t^2}{(t^2+1)^2} \vec{i} + \frac{-2t}{(1+t^2)^2} \vec{j} + \frac{1}{(t^2+1)^{\frac{3}{2}}} \vec{k} ; \text{ if } t=0$$

$$\vec{v}(0) = 0\vec{i} + 1\vec{j} + 0\vec{k} \text{ and}$$

$$\vec{a}(0) = 2\vec{i} + 0\vec{j} + 1\vec{k} \text{ so that}$$

$$|\vec{v}(0)| = \sqrt{1^2} = 1 \text{ and } |\vec{a}(0)| = \sqrt{2^2 + 1^2} = \sqrt{5},$$

then

$$\cos \theta = \frac{\vec{v}(0) \cdot \vec{a}(0)}{|\vec{v}(0)| |\vec{a}(0)|} = \frac{0+0+0}{(1)(\sqrt{5})} = 0$$

$$\text{so } \theta = \frac{\pi}{2}.$$

19.) $\vec{r}(t) = (t - \sin t)\vec{i} + (1 - \cos t)\vec{j} \xrightarrow{D}$

$$\vec{v}(t) = (1 - \cos t)\vec{i} + (\sin t)\vec{j} \xrightarrow{D}$$

$$\vec{a}(t) = (\sin t)\vec{i} + (\cos t)\vec{j}, \text{ then}$$

$$\vec{v}(t) \perp \vec{a}(t) \text{ iff } \vec{v}(t) \cdot \vec{a}(t) = 0 \rightarrow$$

$$\sin t(1 - \cos t) + \sin t \cdot (\cos t) = 0 \rightarrow$$

$$\sin t \cdot [1 - \cos t + \cos t] = 0 \rightarrow$$

$$\sin t = 0 \text{ for } 0 \leq t \leq 2\pi \rightarrow$$

$$t = 0, \pi, 2\pi$$

20.) $\vec{r}(t) = (\sin t)\vec{i} + t\vec{j} + (\cos t)\vec{k} \xrightarrow{D}$

$$\vec{v}(t) = (\cos t)\vec{i} + 1\vec{j} + (-\sin t)\vec{k} \xrightarrow{D}$$

$$\vec{a}(t) = (-\sin t)\vec{i} + 0\vec{j} + (-\cos t)\vec{k}, \text{ then}$$

$$\vec{v}(t) \perp \vec{a}(t) \text{ iff } \vec{v}(t) \cdot \vec{a}(t) = 0 \rightarrow$$

$$-\sin t \cdot \cos t + 0 + \sin t \cdot \cos t = 0 \rightarrow 0 = 0$$

$$\text{so } \vec{v}(t) \perp \vec{a}(t) \text{ for all values of } t$$

21.) $\int_0^1 [t^3\vec{i} + 7\vec{j} + (t+1)\vec{k}] dt$

$$= \left(\frac{1}{4}t^4\Big|_0^1\right)\vec{i} + (7t\Big|_0^1)\vec{j} + \left(\frac{1}{2}t^2+t\Big|_0^1\right)\vec{k}$$

$$= \frac{1}{4} \vec{i} + 7 \vec{j} + \frac{3}{2} \vec{k}$$

$$\begin{aligned}
 24.) \quad & \int_0^{\frac{\pi}{3}} [(\sec t \tan t) \vec{i} + (\tan t) \vec{j} + (2 \cos t \sin t) \vec{k}] dt \\
 & = (\sec t \Big|_0^{\frac{\pi}{3}}) \vec{i} + (\ln |\sec t| \Big|_0^{\frac{\pi}{3}}) \vec{j} + (\sin^2 t \Big|_0^{\frac{\pi}{3}}) \vec{k} \\
 & = (\sec \frac{\pi}{3} - \sec 0) \vec{i} + (\ln |\sec \frac{\pi}{3}| - \ln |\sec 0|) \vec{j} \\
 & \quad + (\sin^2 \frac{\pi}{3} - \sin^2 0) \vec{k} \\
 & = (2 - 1) \vec{i} + (\ln 2 - \ln 1) \vec{j} + (\frac{3}{4} - 0) \vec{k} \\
 & = 1 \cdot \vec{i} + \ln 2 \cdot \vec{j} + \frac{3}{4} \vec{k}
 \end{aligned}$$

$$\begin{aligned}
 26.) \quad & \int_0^1 \left[\frac{2}{\sqrt{1-t^2}} \vec{i} + \frac{\sqrt{3}}{1+t^2} \vec{k} \right] dt \\
 & = (2 \arcsin t \Big|_0^1) \vec{i} + (\sqrt{3} \arctan t \Big|_0^1) \vec{k} \\
 & = (2 \arcsin 1 - 2 \arcsin 0) \vec{i} \\
 & \quad + (\sqrt{3} \arctan 1 - \sqrt{3} \arctan 0) \vec{k} \\
 & = (2 \cdot \frac{\pi}{2} - 2 \cdot 0) \vec{i} + (\sqrt{3} \cdot \frac{\pi}{4} - \sqrt{3} \cdot 0) \vec{k} \\
 & = (\pi) \vec{i} + \left(\frac{\sqrt{3}}{4} \pi \right) \vec{k}
 \end{aligned}$$

$$\begin{aligned}
 31.) \quad & \vec{r}'''(t) = -32 \vec{k} \rightarrow \\
 & \vec{r}'(t) = c_1 \vec{i} + c_2 \vec{j} + (-32t + c_3) \vec{k} \\
 & \text{and } \vec{r}'(0) = 8 \vec{i} + 8 \vec{j} + 0 \cdot \vec{k} \\
 & c_1 = 8, c_2 = 8, -32(0) + c_3 = 0 \rightarrow c_3 = 0 \rightarrow \\
 & \vec{r}'(t) = 8 \vec{i} + 8 \vec{j} + (-32t) \vec{k} \rightarrow \\
 & \vec{r}(t) = (8t + c_1) \vec{i} + (8t + c_2) \vec{j} + (-16t^2 + c_3) \vec{k}
 \end{aligned}$$

$$\text{and } \vec{r}(0) = 0\cdot\vec{i} + 0\cdot\vec{j} + 100\vec{k} \rightarrow$$

$$8(0) + C_1 = 0, \quad 8(0) + C_2 = 0, \quad -16(0)^2 + C_3 = 100 \rightarrow$$

$$C_1 = 0, \quad C_2 = 0, \quad \text{and } C_3 = 100 \rightarrow$$

$$\vec{r}(t) = (8t)\vec{i} + (8t)\vec{j} + (100 - 16t^2)\vec{k}$$

33.) $\vec{r}(t) = (\sin t)\vec{i} + (t^2 \cos t)\vec{j} + e^t \vec{k} \xrightarrow{D}$

$$\vec{r}'(t) = (\cos t)\vec{i} + (2t + \sin t)\vec{j} + e^t \vec{k}$$

and $t = 0 \rightarrow$ point of tangency
is $(\sin 0, 0^2 \cos 0, e^0) = (0, -1, 1)$ and
tangent vector is

$$\begin{aligned}\vec{r}'(0) &= (\cos 0)\vec{i} + (2(0) + \sin 0)\vec{j} + e^0 \vec{k} \\ &= 1 \cdot \vec{i} + 0 \cdot \vec{j} + 1 \cdot \vec{k} \quad \text{so}\end{aligned}$$

tangent line is given by

$$L: \begin{cases} x = 0 + (1)t \\ y = -1 + (0)t \\ z = 1 + (1)t \end{cases} \rightarrow \begin{cases} x = t \\ y = -1 \\ z = 1 + t \end{cases} \quad \text{for } -\infty < t < \infty$$

34.) $\vec{r}(t) = (2 \sin t)\vec{i} + (2 \cos t)\vec{j} + 5t \vec{k} \xrightarrow{D}$

$$\vec{r}'(t) = (2 \cos t)\vec{i} + (-2 \sin t)\vec{j} + 5 \cdot \vec{k}$$

and $t = 4\pi \rightarrow$ point of tangency

$$\text{is } (2 \sin 4\pi, 2 \cos 4\pi, 20\pi) = (0, 2, 20\pi)$$

and tangent vector is

$$\begin{aligned}\vec{r}'(4\pi) &= (2 \cos 4\pi)\vec{i} + (-2 \sin 4\pi)\vec{j} + 5 \vec{k} \\ &= 2 \vec{i} + 0 \cdot \vec{j} + 5 \vec{k} \quad \text{so}\end{aligned}$$

tangent line is given by

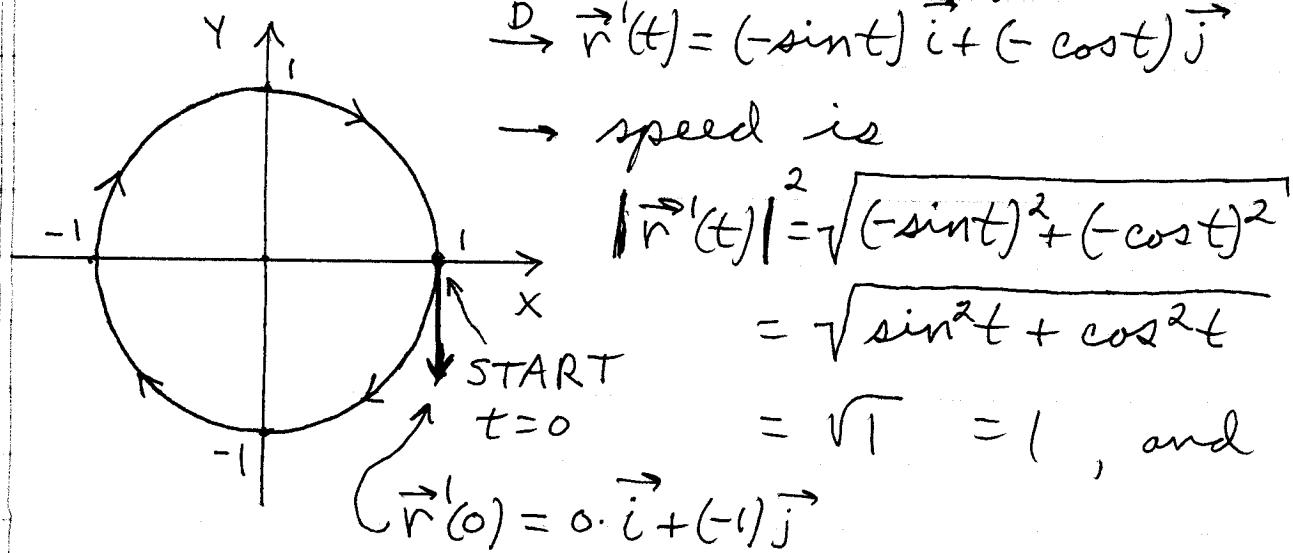
$$L: \begin{cases} x = 0 + (2)t \\ y = 2 + (0)t \\ z = 20\pi + (5)t \end{cases} \rightarrow \begin{cases} x = 2t \\ y = 2 \\ z = 20\pi + 5t \end{cases} \text{ for } -\infty < t < \infty$$

36.) $\vec{r}(t) = (\cos t)\vec{i} + (\sin t)\vec{j} + (\sin 2t)\vec{k} \xrightarrow{D}$
 $\vec{r}'(t) = (-\sin t)\vec{i} + (\cos t)\vec{j} + (2\cos 2t)\vec{k}$
and $t = \frac{\pi}{2} \rightarrow$ point of tangency is
 $(\cos \frac{\pi}{2}, \sin \frac{\pi}{2}, \sin \pi) = (0, 1, 0)$ and
tangent vector is
 $\vec{r}'(\frac{\pi}{2}) = (-\sin \frac{\pi}{2})\vec{i} + (\cos \frac{\pi}{2})\vec{j} + (2\cos \pi)\vec{k}$
 $= -1 \cdot \vec{i} + 0 \cdot \vec{j} + -2 \cdot \vec{k}$, so

tangent line is given by

$$L: \begin{cases} x = 0 + (-1)t \\ y = 1 + (0)t \\ z = 0 + (-2)t \end{cases} \rightarrow \begin{cases} x = -t \\ y = 1 \\ z = -2t \end{cases} \text{ for } -\infty < t < \infty$$

37.) d.) $\vec{r}(t) = (\cos t)\vec{i} + (-\sin t)\vec{j}$ for $t \geq 0$

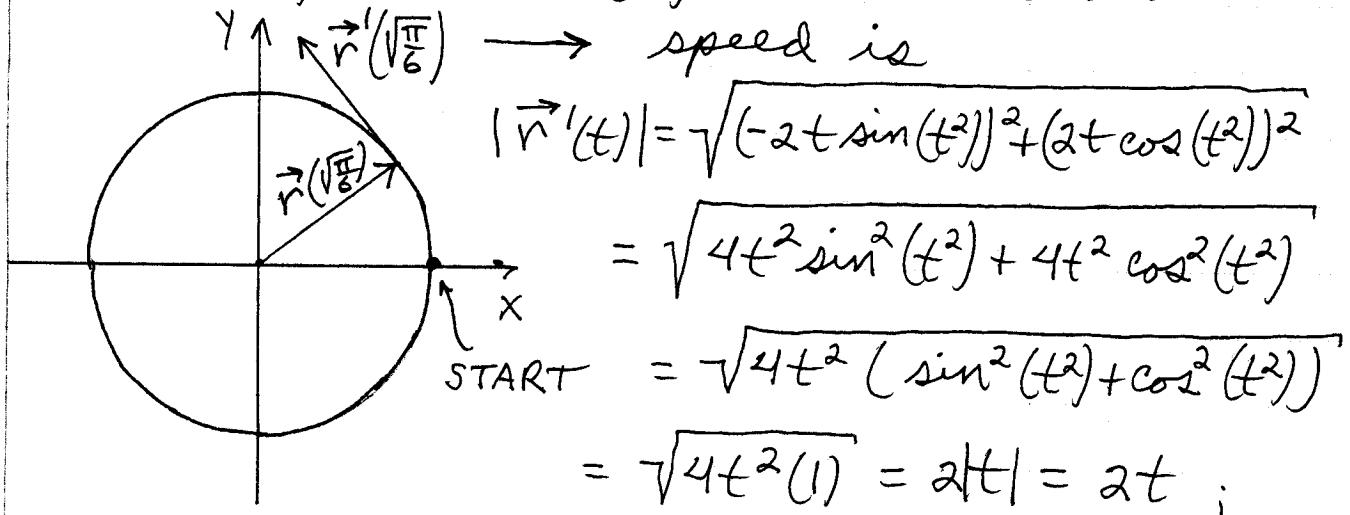


i.) YES, speed = 1

ii.) YES, since $\vec{r}'(t)$ has constant length we know $\frac{d}{dt}(\vec{r}'(t)) = \vec{r}''(t)$ is \perp to $\vec{r}'(t)$ (Example from class)

iii.) The particle moves clockwise since $\vec{r}'(0) = -\vec{j}$.

37.) e.) $\vec{r}(t) = \cos(t^2) \cdot \vec{i} + \sin(t^2) \cdot \vec{j}$ for $t \geq 0$
 $\rightarrow \vec{r}'(t) = -2t \sin(t^2) \cdot \vec{i} + 2t \cos(t^2) \cdot \vec{j}$



$$\vec{r}'(0) = 0 \cdot \vec{i} + 0 \cdot \vec{j} \quad (\text{no good information})$$

$$\vec{r}'(\sqrt{\frac{\pi}{6}}) = \left(-2\sqrt{\frac{\pi}{6}} \sin\frac{\pi}{6}\right) \vec{i} + \left(2\sqrt{\frac{\pi}{6}} \cos\frac{\pi}{6}\right) \vec{j}$$
$$= -\sqrt{\frac{\pi}{6}} \vec{i} + \sqrt{3} \sqrt{\frac{\pi}{6}} \vec{j}$$

i.) The speed of motion is $2t$, not a constant speed.

ii.) No, since velocity vector $\vec{r}'(t)$ does not have constant length

iii.) The particle moves counter-clockwise (SEE $\vec{r}'(\sqrt{\frac{\pi}{6}})$).

$$\begin{aligned}
 38.) \quad & \vec{r}(t) = (2\vec{i} + 2\vec{j} + \vec{k}) \\
 & + \cos t \left(\frac{1}{\sqrt{2}}\vec{i} - \frac{1}{\sqrt{2}}\vec{j} \right) \\
 & + \sin t \left(\frac{1}{\sqrt{3}}\vec{i} + \frac{1}{\sqrt{3}}\vec{j} + \frac{1}{\sqrt{3}}\vec{k} \right) \\
 & = \left(2 + \frac{1}{\sqrt{2}} \cos t + \frac{1}{\sqrt{3}} \sin t \right) \vec{i} \\
 & + \left(2 - \frac{1}{\sqrt{2}} \cos t + \frac{1}{\sqrt{3}} \sin t \right) \vec{j} \\
 & + \left(1 + \frac{1}{\sqrt{3}} \sin t \right) \vec{k} \rightarrow
 \end{aligned}$$

$$\begin{cases} x = 2 + \frac{1}{\sqrt{2}} \cos t + \frac{1}{\sqrt{3}} \sin t \\ y = 2 - \frac{1}{\sqrt{2}} \cos t + \frac{1}{\sqrt{3}} \sin t \\ z = 1 + \frac{1}{\sqrt{3}} \sin t \end{cases} \rightarrow z - 1 = \frac{1}{\sqrt{3}} \sin t$$

$$\rightarrow \begin{cases} x = 2 + \frac{1}{\sqrt{2}} \cos t + (z - 1) \\ y = 2 - \frac{1}{\sqrt{2}} \cos t + (z - 1) \end{cases} \text{ (ADD)} \quad (1)$$

$$\rightarrow x + y = 4 + 2z - 2$$

$$\rightarrow \boxed{x + y - 2z = 2} \quad (\text{a plane});$$

now find distance between (x, y, z) and $(2, 2, 1)$:

$$L = \sqrt{(x-2)^2 + (y-2)^2 + (z-1)^2}$$

$$= \sqrt{\left(\frac{1}{\sqrt{2}}\cos t + \frac{1}{\sqrt{3}}\sin t\right)^2 + \left(-\frac{1}{\sqrt{2}}\cos t + \frac{1}{\sqrt{3}}\sin t\right)^2 + \left(\frac{1}{\sqrt{3}}\sin t\right)^2}$$

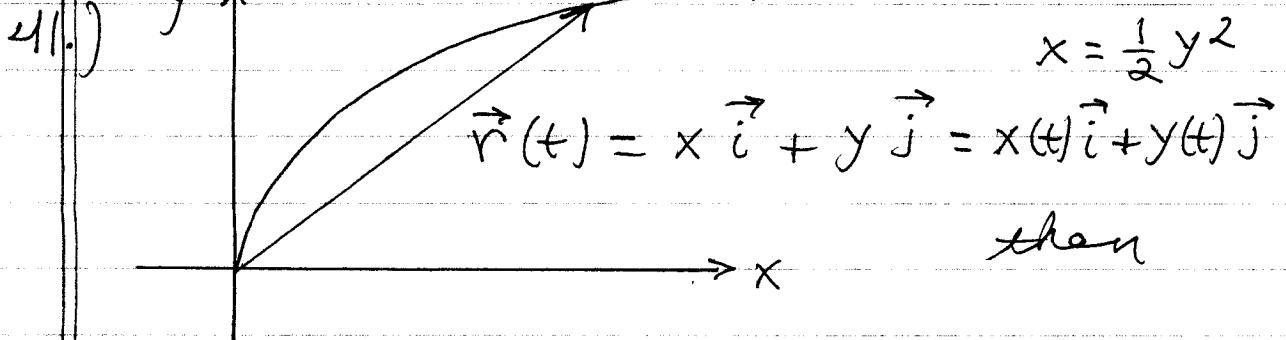
$$= \sqrt{\frac{1}{2}\cos^2 t + \frac{2}{\sqrt{6}}\cos t \sin t + \frac{1}{3}\sin^2 t + \frac{1}{2}\cos^2 t - \frac{2}{\sqrt{6}}\cos t \sin t + \frac{1}{3}\sin^2 t + \frac{1}{3}\sin^2 t}$$

$$= \sqrt{\cos^2 t + \sin^2 t} = \sqrt{1} = 1 ;$$

thus points (x, y, z) lie in the plane $x + y - 2z = 2$ and are 1 unit away from point $(2, 2, 1)$, a circle of radius 1 centered at $(2, 2, 1)$.

40.)

(NEXT after
41.)



velocity vector is

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$$\vec{r}'(t) = x'(t)\vec{i} + y'(t)\vec{j} \text{ so}$$

$$\text{speed} = |\vec{r}'(t)| = \sqrt{(x'(t))^2 + (y'(t))^2} = 5$$
$$\rightarrow [(x'(t))^2 + (y'(t))^2 = 25] ; \text{ and}$$

$$[(y(t))^2 = 2x(t)] \rightarrow 2 \cdot y(t)y'(t) = 2x'(t)$$

$$\rightarrow [(y(t))^2 (y'(t))^2 = (x'(t))^2] ; \text{ then}$$

$$(\text{SUB}) \quad 2x(t)(25 - (x'(t))^2) = (x'(t))^2$$

$$\rightarrow (\text{Solve for } x'(t).) \rightarrow$$

$$50x(t) - 2x(t) \cdot (x'(t))^2 = (x'(t))^2 \rightarrow$$

$$50x(t) = 2x(t) \cdot (x'(t))^2 + (x'(t))^2 \rightarrow$$

$$50x(t) = (2x(t) + 1)(x'(t))^2 \rightarrow$$

$$x'(t)^2 = \frac{50x(t)}{2x(t) + 1} \rightarrow x'(t) = \sqrt{\frac{50x(t)}{2x(t) + 1}} ;$$

if $x=2$, then

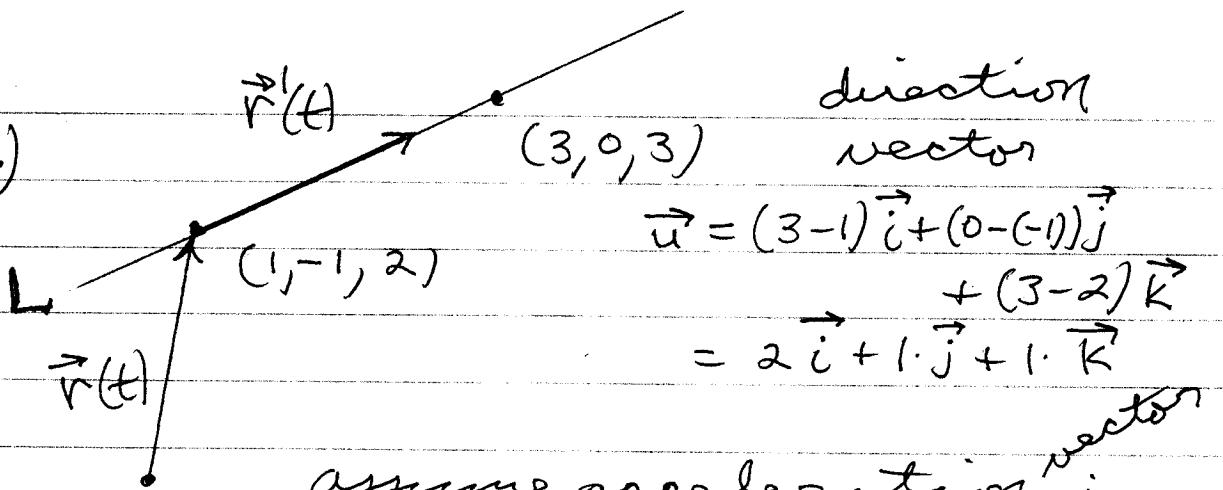
$$x'(t) = \sqrt{20} = \boxed{2\sqrt{5}} \text{ and}$$

$$y'(t) = \sqrt{25 - (x'(t))^2} = \sqrt{25 - 20} = \boxed{\sqrt{5}}.$$

thus at $(2, 2)$ velocity is

$$\begin{aligned}\vec{r}'(t) &= x'(t)\vec{i} + y'(t)\vec{j} \\ &= 2\sqrt{5}\vec{i} + \sqrt{5}\vec{j}.\end{aligned}$$

40.)



assume acceleration vector is

$$\vec{r}''(t) = 2\vec{i} + 1\cdot\vec{j} + 1\cdot\vec{k} \rightarrow$$

$$\vec{r}'(t) = (2t+c_1)\vec{i} + (t+c_2)\vec{j} + (t+c_3)\vec{k}; \text{ then}$$

$\vec{r}'(0) = c_1\vec{i} + c_2\vec{j} + c_3\vec{k}$ (the initial velocity vector) is a multiple of \vec{u} , say 5

$$5\vec{u} = 5(2\vec{i} + \vec{j} + \vec{k}) = 2S\vec{i} + S\vec{j} + S\vec{k},$$

i.e. $\vec{r}'(0) = S\vec{u}$ so that

$$c_1 = 2S, c_2 = S, \text{ and } c_3 = S \rightarrow$$

$$\vec{r}'(0) = 2S\vec{i} + S\vec{j} + S\vec{k}; \text{ and}$$

initial speed is 2 so

$$|\vec{r}'(0)| = \sqrt{(2S)^2 + S^2 + S^2} = 2 \rightarrow$$

$$6S^2 = 4 \rightarrow (S = 2/\sqrt{3}); \text{ thus}$$

$$\vec{r}'(t) = (2t + \frac{4}{\sqrt{3}})\vec{i} + (t + \frac{2}{\sqrt{3}})\vec{j} + (t + \frac{2}{\sqrt{3}})\vec{k} \text{ then}$$

$$\begin{aligned} \vec{r}(t) &= (t^2 + \frac{4}{\sqrt{3}}t + c_1)\vec{i} + (\frac{t^2}{2} + \frac{2}{\sqrt{3}}t + c_2)\vec{j} \\ &\quad + (\frac{1}{2}t^2 + \frac{2}{\sqrt{3}}t + c_3)\vec{k} \end{aligned}$$

and $\vec{r}(0) = \vec{i} + (-1)\vec{j} + 2\vec{k}$ (Given)

so $\vec{r}(0) = c_1 \vec{i} + c_2 \vec{j} + c_3 \vec{k}$, then

$c_1 = 1, c_2 = -1, c_3 = 2$ and

$$\begin{aligned}\vec{r}(t) &= \left(t^2 + \frac{4}{\sqrt{3}}t + 1\right) \vec{i} + \left(\frac{1}{2}t^2 + \frac{2}{\sqrt{3}}t - 1\right) \vec{j} \\ &\quad + \left(\frac{1}{2}t^2 + \frac{2}{\sqrt{3}}t + 2\right) \vec{k}\end{aligned}$$

$$43.) \quad \vec{r}(t) = (3\cos t) \vec{j} + (2\sin t) \vec{k} \xrightarrow{D}$$

$$\vec{r}'(t) = (-3\sin t) \vec{j} + (2\cos t) \vec{k} \rightarrow$$

$$\vec{r}''(t) = (-3\cos t) \vec{j} + (-2\sin t) \vec{k}.$$

$$\text{Let } F(t) = |\vec{v}(t)| = |\vec{r}'(t)| = \sqrt{(3\sin t)^2 + (2\cos t)^2}$$

$$\begin{aligned}F(t) &= \sqrt{9\sin^2 t + 4\cos^2 t} \\ &= \sqrt{5\sin^2 t + 4(\sin^2 t + \cos^2 t)} \\ &= \sqrt{5\sin^2 t + 4}.\end{aligned}$$

the maximum value of

$$F(t) = |\vec{v}(t)| = \sqrt{5(1)^2 + 4} = 3;$$

the minimum value of

$$F(t) = |\vec{v}(t)| = \sqrt{5(0)^2 + 4} = 2; \text{ let}$$

$$G(t) = |\vec{a}(t)| = |\vec{r}''(t)|$$

$$= \sqrt{(-3\cos t)^2 + (-2\sin t)^2}$$

$$= \sqrt{9\cos^2 t + 4\sin^2 t}$$

$$= \sqrt{5\cos^2 t + 4(\cos^2 t + \sin^2 t)}$$

$$= \sqrt{5\cos^2 t + 4}$$

the maximum value of

$$G(t) = |\vec{a}'(t)| = \sqrt{5(1)^2 + 4} = \sqrt{9} = 3;$$

the minimum value of

$$G(t) = |\vec{a}'(t)| = \sqrt{5(0)^2 + 4} = \sqrt{4} = 2.$$

45.) Theorem: If $\vec{v}(t) \cdot \vec{v}'(t) = 0$, then

$$|\vec{v}| = c, \text{ a constant}.$$

Proof: If $\vec{v}(t) \cdot \vec{v}'(t) = 0 \rightarrow$

$$\vec{v}'(t) \cdot \vec{v}(t) = 0 \text{ then}$$

$$\vec{v}(t) \cdot \vec{v}'(t) + \vec{v}'(t) \cdot \vec{v}(t) = 0 \rightarrow$$

$$D(\vec{v}(t) \cdot \vec{v}(t)) = 0 \rightarrow$$

$$\vec{v}(t) \cdot \vec{v}(t) = c_1, \text{ a constant} \rightarrow$$

$$|\vec{v}(t)|^2 = c_1 \rightarrow$$

$$|\vec{v}(t)| = \sqrt{c_1} = c, \text{ a constant. QED}$$

48.) Theorem: If $\vec{u}(t) = a\vec{i} + b\vec{j} + c\vec{k}$,

a constant vector, then

$$\vec{u}'(t) = 0 \cdot \vec{i} + 0 \cdot \vec{j} + 0 \cdot \vec{k}.$$

Proof: $\vec{u}(t) = a\vec{i} + b\vec{j} + c\vec{k} \xrightarrow{D}$

$$\begin{aligned} \frac{d}{dt} \vec{u}(t) &= \frac{d}{dt}(a)\vec{i} + \frac{d}{dt}(b)\vec{j} + \frac{d}{dt}(c)\vec{k} \\ &= 0 \cdot \vec{i} + 0 \cdot \vec{j} + 0 \cdot \vec{k}. \end{aligned}$$

QED.